

AC Servo System

MITSUBISHI ELECTRIC SERVO SYSTEM  
**MELSERV/O**

Linear Servo Motor  
User's Manual  
(LM-H4M/LM-H3/LM-U2/LM-F/LM-K2)

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-LM-H4M  
-LM-H3  
-LM-U2  
-LM-F  
-LM-K2



# SAFETY INSTRUCTIONS

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Please read the instructions carefully before using the equipment.

To use the equipment correctly, do not attempt to install, operate, maintain, or inspect the equipment until you have read through this manual, installation guide, and appended documents carefully. Do not use the equipment until you have a full knowledge of the equipment, safety information and instructions.

In this manual, the safety instruction levels are classified into "WARNING" and "CAUTION".



## WARNING

Indicates that incorrect handling may cause hazardous conditions, resulting in death or severe injury.

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## CAUTION

Indicates that incorrect handling may cause hazardous conditions, resulting in medium or slight injury.


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Note that the CAUTION level may lead to a serious consequence depending on conditions.


Please follow the instructions of both levels because they are important to personnel safety.

Forbidden actions and required actions are indicated by the following diagrammatic symbols.



Indicates a forbidden action. For example, "No Fire" is indicated by .



Indicates a required action. For example, grounding is indicated by .

In this manual, precautions for hazards that can lead to property damage, instructions for other functions, and other information are shown separately in the "POINT" area.

After reading this manual, keep it accessible to the operator.

## [Transportation]

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## CAUTION

- To prevent injury, transport the products correctly according to their mass.
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## [Installation/wiring]

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## WARNING

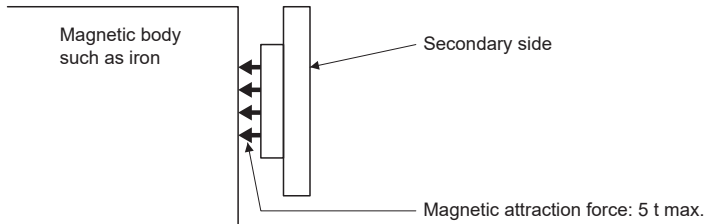
- To prevent an electric shock, turn off the power and wait for 15 minutes or more before starting wiring and/or inspection.
  - To prevent an electric shock, ground the linear servo motor securely.
  - To prevent an electric shock, any person who is involved in wiring should be fully competent to do the work.
  - To prevent an electric shock, do not attempt to wire the linear servo motor until it has been mounted.
  - To prevent an electric shock, do not touch the conductive parts.
-

## [Installation/wiring]

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### CAUTION

- To prevent injury, only professional engineers with knowledge of the product should install the product.
- To prevent injury when handling the linear servo motor, do not touch sharp edges such as the sharp edges of the linear servo motor with bare hands.
- On linear servo motors, the permanent magnet on the secondary side generates attraction force in the area between the magnetic material. This attraction force may cause injuries to hands and other body parts that enter the area between the secondary side and the magnetic material, so take special care when handling the motor.



## [Maintenance]

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### WARNING

- To prevent an electric shock, any person who is involved in inspection should be fully competent to do the work.

### CAUTION

- To prevent injury, only professional engineers with knowledge of the product should replace the product.

## [Disposal]

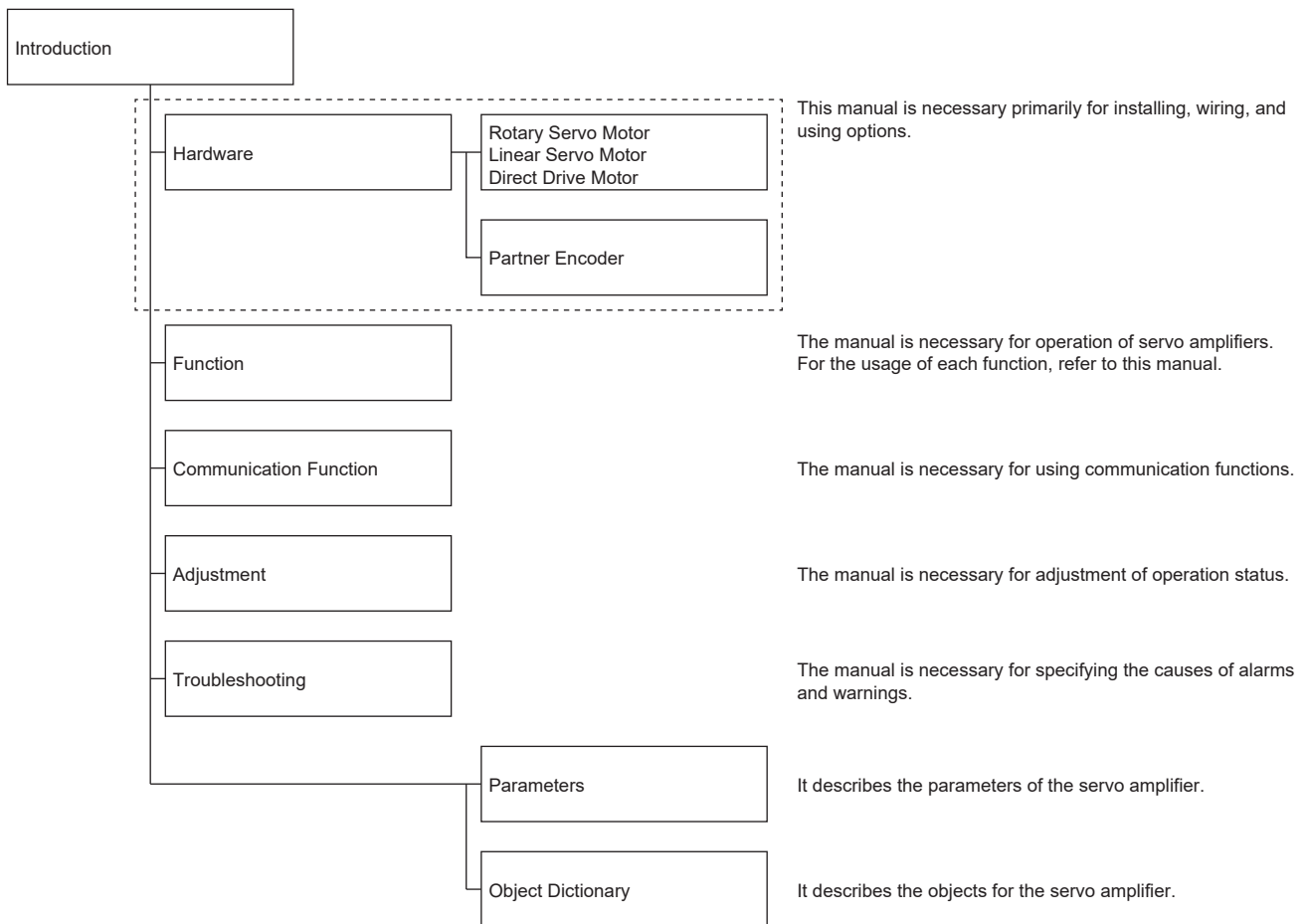
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### CAUTION

- To prevent injury, only professional engineers with knowledge of the product should dispose of the product.
  - To avoid a burn when heating the secondary side to 300 °C or more in order to demagnetize it, allow the secondary side to adequately cool before touching it.
-

# ABOUT THE MANUAL

If using the servo for the first time, prepare and use the following related manuals to ensure that the servo is used safely. For the related manuals, refer to the User's Manual (Introduction).



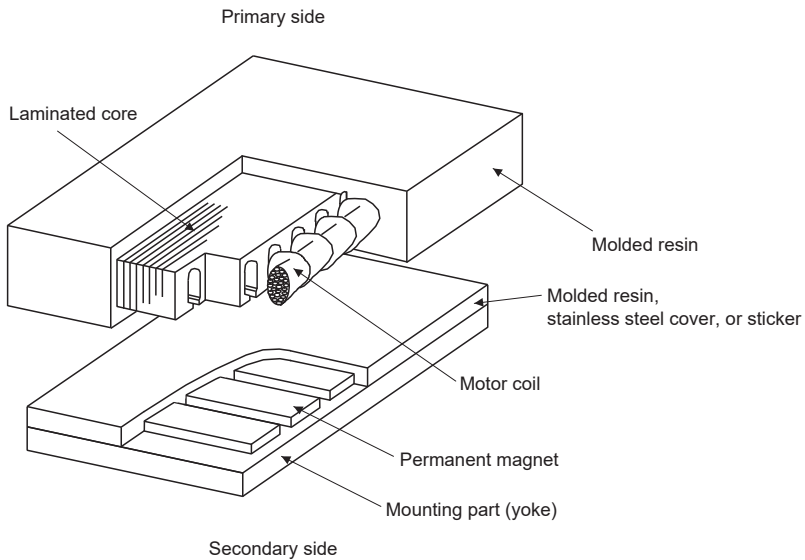
## Global standards and regulations

Compliance with the indicated global standards and regulations is current as of the release date of this manual. Some standards and regulations may have been modified or withdrawn.

# HANDLING THE LINEAR SERVO MOTOR

## Structure of the linear servo motor

The linear servo motor consists of a primary side made up of an iron core and coil and a secondary side made up of a mounting part (yoke) and a permanent magnet. (excluding coreless type LM-U2 series)



### ■Primary side

The primary side contains a magnet wire wound around the iron core of the motor and is covered with molded resin. There may be differences in appearance depending on the product.

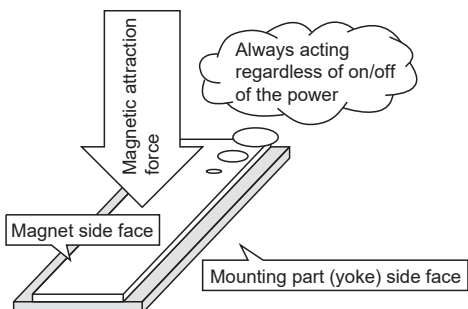
### ■Secondary side

The secondary side has a permanent magnet on the mounting part (yoke) and is covered by molded resin, a stainless steel cover, or sticker.

## Magnetic attraction force

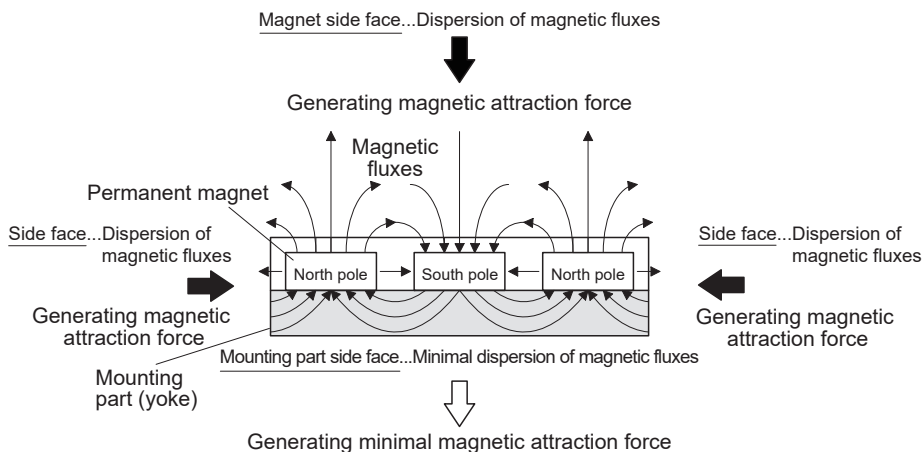
The secondary side of the linear servo motor contains a strong permanent magnet, so a magnetic attraction force (the force by which a magnet attracts magnetic materials) is generated toward magnetic materials such as iron.

This magnetic attraction force is always generated regardless of whether the linear servo motor power is on/off.



The magnetic fluxes generated by the permanent magnet are dispersed into the air from the magnet face side (the side facing the primary side), and most of said fluxes do not leak to the mounting part (yoke) surface side due to its structure.

Because of this, the magnetic attraction force occurs mainly on the magnet face side of the secondary side and barely occurs on the mounting part (yoke) surface side.

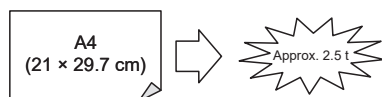


The permanent magnet used for the linear servo motor is very strong.

When an A4-sized iron sheet is fully attracted, the magnetic attraction force becomes as high as 2.5 t. Exercise sufficient caution when handling the product.

Magnetic attraction force  $\approx 400$  [kPa]

If an A4-size iron sheet is fully attracted . . .



## For safety

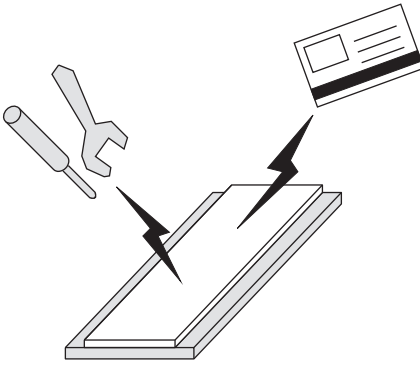
The magnetic attraction force is in inverse proportion to the square of the distance between magnetic materials, and said force drastically increases when the distance becomes small.

When mounting the secondary side of the linear side motor, ensure that the distance from nearby magnetic materials is sufficient and securely fix said magnetic materials into place.

If a problem is suspected with the product, stop using it immediately.

## Notes on handling

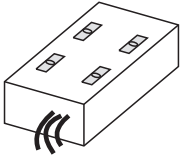
- Only professional engineers with knowledge of the product should handle it.
- Individuals using a medical device such as a pacemaker must keep a distance from the product and equipment.
- Do not wear metal items such as watches, earrings, necklaces, etc.
- Use non-magnetic tools.
- Do not place magnetic cards, watches, portable phones, etc. close to the motor.
- Do not process or strike the product.
- Place signage stating "Caution - Strong magnetic field", etc. In addition, take measures that make the location of the product known in the surrounding area.



## Disposal of the linear servo motor

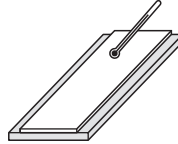
- The primary side must be discarded as industrial waste.
- The secondary side must be discarded as industrial waste after it is demagnetized by being heating to 300 °C or more.
- Do not leave the product unpacked when it is not in use.

Primary side



⇒ Discard as industrial waste.

Secondary side



⇒ After demagnetizing over 300 °C, discard as industrial waste.

## CABLES USED FOR WIRING

Cables mentioned in this manual are selected based on an ambient temperature of 40 °C.

## U.S. CUSTOMARY UNITS

U.S. customary units are not shown in this manual. Convert the values if necessary according to the following table.

Quantity	SI (metric) unit	U.S. customary unit
Mass	1 [kg]	2.2046 [lb]
Length	1 [mm]	0.03937 [inch]
Torque	1 [N·m]	141.6 [oz·inch]
Moment of inertia	1 [(× 10 <sup>-4</sup> kg·m <sup>2</sup> )]	5.4675 [oz·inch <sup>2</sup> ]
Load (thrust load/axial load)	1 [N]	0.2248 [lbf]
Temperature	N [°C] × 9/5 + 32	N [°F]

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# 1 HANDLING THE LINEAR SERVO MOTOR

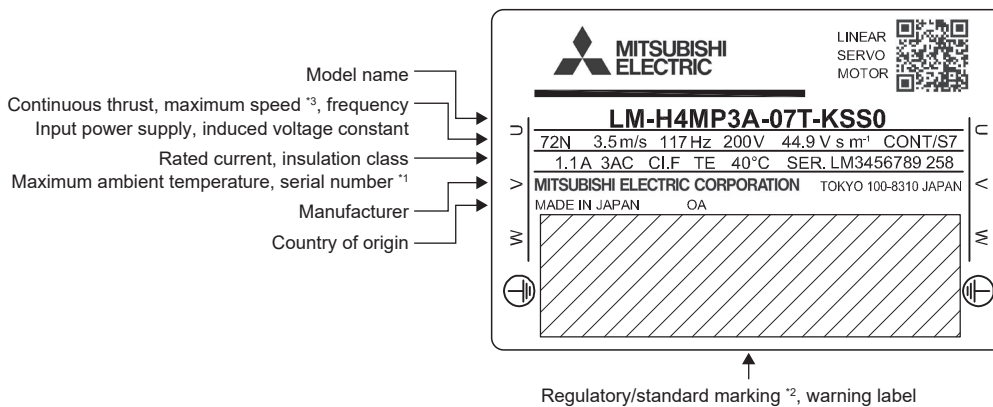
The linear servo motor uses a strong magnet on the secondary side. Incorrect handling is extremely dangerous and may cause serious accidents. Please read this chapter and thoroughly understand the contents before using the motor and be sure to handle the motor carefully.

## 1.1 Rating plate

The following shows an example of the rating plate for explanation of each item.

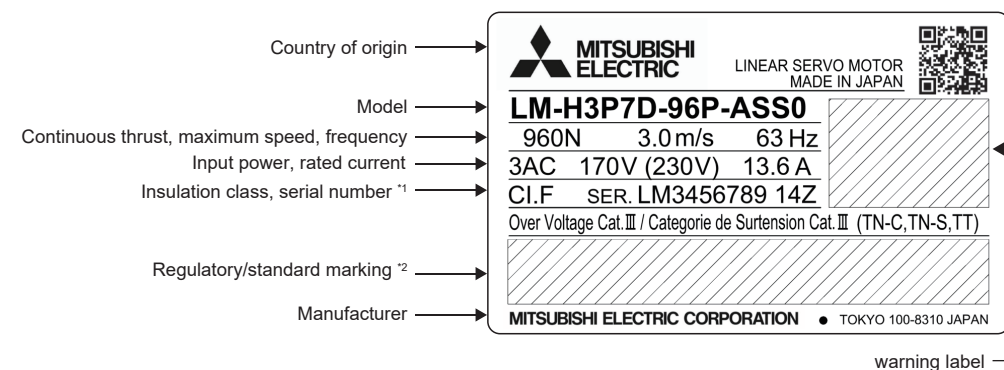
### Primary side (coil)

#### ■LM-H4M series



- \*1 The production year and month of the primary side of the linear servo motor are indicated in the serial number on the rating plate. The date of manufacture is indicated by the last two digits of the year and a digit or letter representing the month [1 to 9, X (10), Y (11), Z (12)].  
For January 2012, the serial number would be "SER. \_\_\_\_\_ 121".
- \*2 Products that have been certified by a third-party certification body as compliant with standards display a certification mark. The design of the mark varies depending on the certification body.
- \*3 It indicates the maximum speed in the continuous running range.

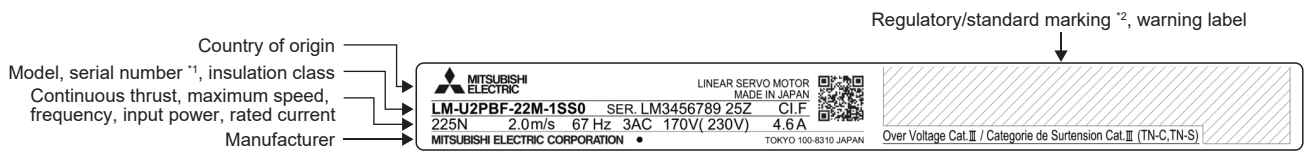
#### ■LM-H3/LM-F/LM-K2 series



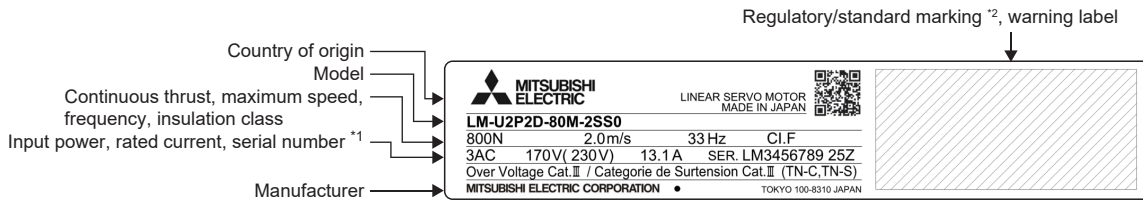
- \*1 The production year and month of the primary side of the linear servo motor are indicated in the serial number on the rating plate. The date of manufacture is indicated by the last two digits of the year and a digit or letter representing the month [1 to 9, X (10), Y (11), Z (12)].  
For January 2012, the serial number would be "SER. \_\_\_\_\_ 121".
- \*2 Products that have been certified by a third-party certification body as compliant with standards display a certification mark. The design of the mark varies depending on the certification body.

## ■LM-U2 series

- LM-U2PA\_/LM-U2PB\_series



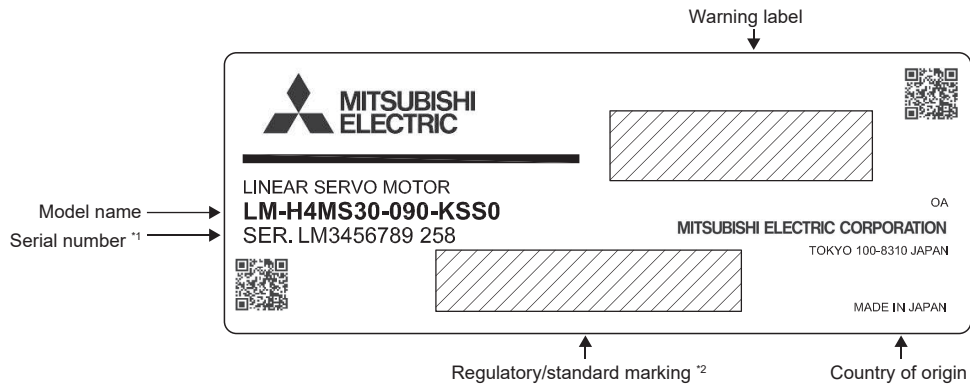
- LM-U2P2\_series



- \*1 The production year and month of the primary side of the linear servo motor are indicated in the serial number on the rating plate. The date of manufacture is indicated by the last two digits of the year and a digit or letter representing the month [1 to 9, X (10), Y (11), Z (12)].  
For January 2012, the serial number would be "SER. \_\_\_\_\_ 121".
- \*2 Products that have been certified by a third-party certification body as compliant with standards display a certification mark. The design of the mark varies depending on the certification body.

## Secondary side (magnet)

### ■LM-H4M series

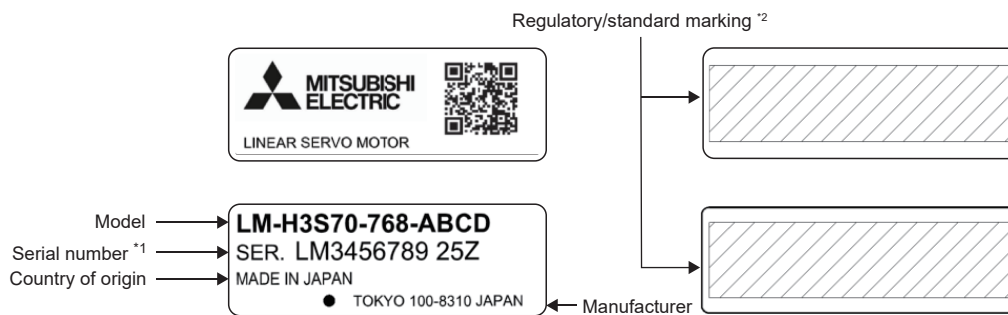


\*1 The production year and month of the secondary side of the linear servo motor are indicated in the serial number on the rating plate. The date of manufacture is indicated by the last two digits of the year and a digit or letter representing the month [1 to 9, X (10), Y (11), Z (12)].

For January 2012, the serial number would be "SER. \_\_\_\_\_ 121".

\*2 Products that have been certified by a third-party certification body as compliant with standards display a certification mark. The design of the mark varies depending on the certification body.

### ■LM-H3/LM-U2/LM-F/LM-K2 series








\*1 The production year and month of the secondary side of the linear servo motor are indicated in the serial number on the rating plate. The date of manufacture is indicated by the last two digits of the year and a digit or letter representing the month [1 to 9, X (10), Y (11), Z (12)].






For January 2012, the serial number would be "SER. \_\_\_\_\_ 121".

\*2 Products that have been certified by a third-party certification body as compliant with standards display a certification mark. The design of the mark varies depending on the certification body.






# 1.2 Environment

Item	Operation	Storage/transportation
Ambient temperature	0 °C to 60 °C (non-freezing) *1	-15 °C to 70 °C (non-freezing)
Ambient humidity	10 %RH to 80 %RH (non-condensing)	10 %RH to 90 %RH (non-condensing)
Ambience	Indoors (no direct sunlight); no corrosive gas, inflammable gas, oil mist or dust	
Altitude	2000 m or less *2	
Vibration resistance	LM-H4M series  Page 38 Standard specifications LM-H3 series  Page 62 Standard specifications list LM-U2 series  Page 73 Standard specifications list LM-F series  Page 86 Standard specifications list LM-K2 series  Page 97 Standard specifications list	

\*1 Refer to the following for restrictions on the ambient temperature.

- LM-H4M series
  -  Page 41 Derating
- LM-H3 series
  -  Page 64 Derating
- LM-U2 series
  -  Page 76 Derating
- LM-F series
  -  Page 88 Derating
- LM-K2 series
  -  Page 99 Derating

\*2 Refer to the following for restrictions on using this product at an altitude exceeding 1000 m and up to 2000 m.

- LM-H4M series
  -  Page 41 Derating
- LM-H3 series
  -  Page 64 Derating
- LM-U2 series
  -  Page 76 Derating
- LM-F series
  -  Page 88 Derating
- LM-K2 series
  -  Page 99 Derating

# 1.3 Design instructions

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## Precautions

- Although a dynamic brake can be applied by the servo amplifier, the coasting distance becomes longer when the mass of the moving part is heavy or when the speed is high. This is highly dangerous and may result in a collision into the stroke end. Install an anti-collision mechanism such as an air brake or an electric/mechanical stopper such as a shock absorber to reduce the shock of moving parts. (No linear servo motor with an electromagnetic brake is available.)
- The magnetic attraction force operating between the primary and secondary sides is always in operation even when the linear servo motor power is not turned on. As such, the machine must be designed with sufficient rigidity to support the magnetic attraction force and maintain the accuracy.
- Since the running load increases in proportion to the magnetic attraction force due to friction, arrange to reduce friction as much as possible by precisely installing the linear guide, etc.
- When the linear servo motor is used on a vertical axis, provide a drop prevention system to prevent free fall at servo-off by using a spring or a counter balance.
- Install the linear servo motor so that the thrust operates on the center of gravity of the moving part. When the thrust does not operate on the center of gravity of the moving part, a moment occurs.
- If magnetic powders such as iron shavings are present, they may stick to the permanent magnet on the secondary side and cause a malfunction. In such an environment, take measures to prevent the adhesion and entry of magnetic powders.
- While both the linear encoder and the linear servo motor should be oil and dust proofed, oil and dust proofing are especially important for the linear encoder. For details, contact the manufacturer of the linear encoder being used.
- Do not allow the primary side to come into contact with the stopper. Doing so may damage the primary side. Arrange the system so that only the table attached to the primary side comes into contact with the stopper.
- Do not use the screw holes of the linear servo motor for any purpose other than for machine installation.
- For installation, use all of the screw holes provided on the linear servo motor.
- If it is assumed that a power failure or product malfunction may result in a hazardous situation, provide an external brake system for holding purposes to prevent such hazards.
- Provide adequate protection to prevent an unexpected restart after an instantaneous power failure.
- Arrange for the primary and secondary side to satisfy the mounting dimensions.
- When using a linear guide as the base, check the specifications and determine the processing accuracy. For details, contact the manufacturer of the linear guide being used.
- The movable range of the linear servo motor should be equal to or less than the effective measurement length of the linear encoder.
- For the stopper, use shock-absorbing material such as polyurethane rubber.
- Conditions where cutting fluid or lubricating oil are constantly applied or where condensation occurs for an extended period of time due to the effects of oil-mist lubrication, over-cooling, or excessive humidity may result in the deterioration of the insulation on the linear servo motor. Provide measures such as oil proofing, a dust proof cover, or condensation prevention to protect the linear servo motor.
- Consider the installation work when designing the system. For details of installation, refer to the following and the "Installation" section in the chapter for the linear servo motor series being used.

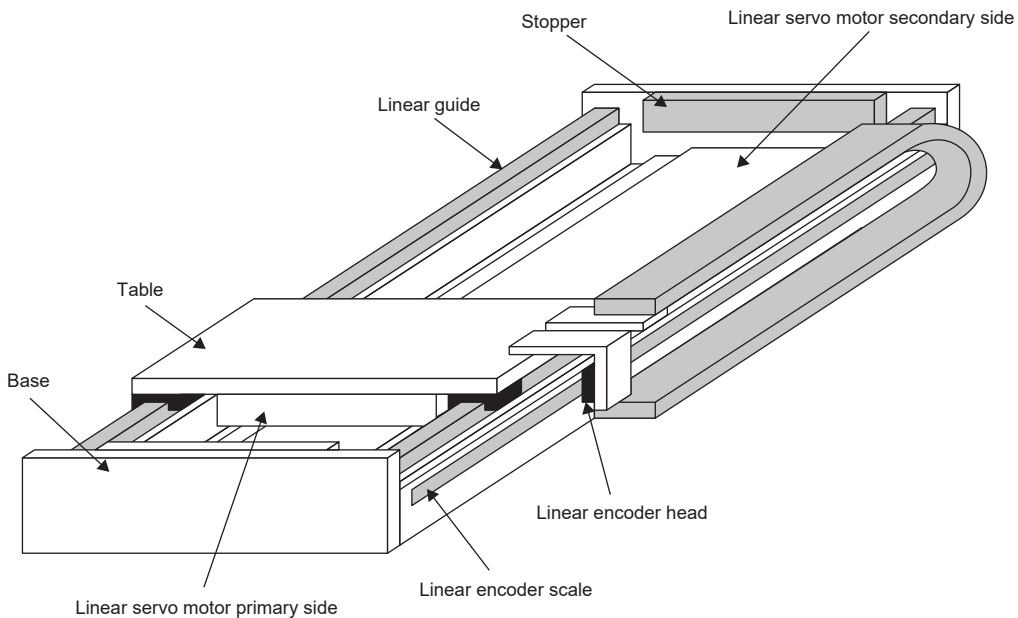
### Page 17 Instructions on installation

- For high-accuracy positioning, ensure that the rigidity of the machines has been maximized and increase the mechanical resonance points.
- To ensure that the rigidity of the machines is maximized, adopt an integrated structure for the base. When it is necessary to use bolts, etc. as a fastener, use thick bolts with short neck dimensions. Make the pitch dimension of bolt holes as small as possible.
- Make the moving parts as light as possible, and make the base parts heavy and sturdy.
- When loading works, etc. on the table, make the center of gravity as low as possible. Additionally, the position of the center of gravity should be between the two linear guides.
- Since the movement or accuracy of the machine may be adversely affected, arrange for the center of thrust of the linear servo motor and the center of gravity of the moving object to be closer with one another.

- When the mounting rigidity of the linear encoder is insufficient, the feedback signal may be disturbed by the machine vibration, and the desired performance may not be achieved. Furthermore, as the same condition also applies in cases where the linear encoder is susceptible to electric noise, arrange or install the linear encoder in a way that minimizes exposure to vibration and electric noise.
- Establish a structure that can withstand high speeds and high acceleration/deceleration.

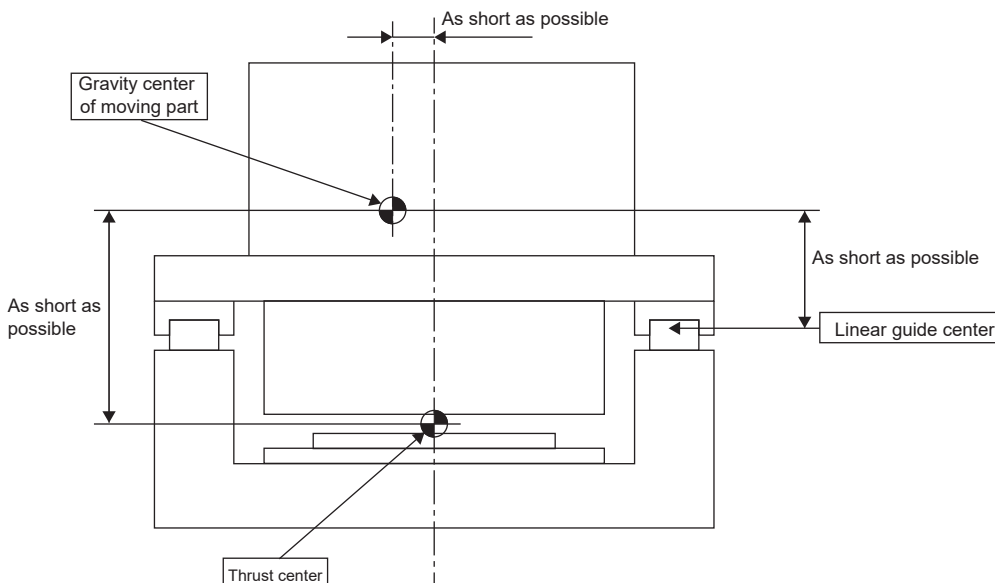
## Basic structure for sliders incorporating the linear servo motor

The following figure shows an example of the basic structure for a linear slider.



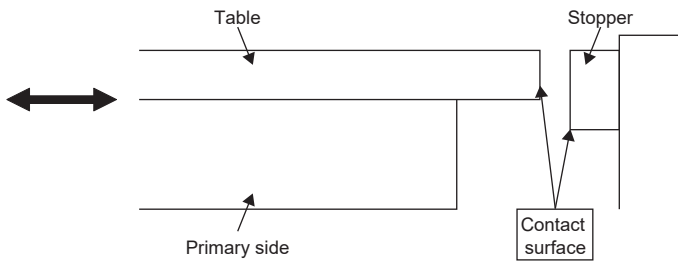
## Instructions on the structure of the linear slider

Instructions on the structure of the linear slider are shown in the following figure.



## Stopper

As shown in the following figure, arrange the system so that only the table attached to the primary side comes into contact with the stopper.



## Linear encoder

While both the linear encoder and the linear servo motor should be oil and dust proofed, oil and dust proofing are especially important for the linear encoder.

For details, contact the manufacturer of the linear encoder being used.

## Linear guide

Precisely install the linear guide.

For details, contact the manufacturer of the linear guide being used.

# 1.4 Instructions on installation

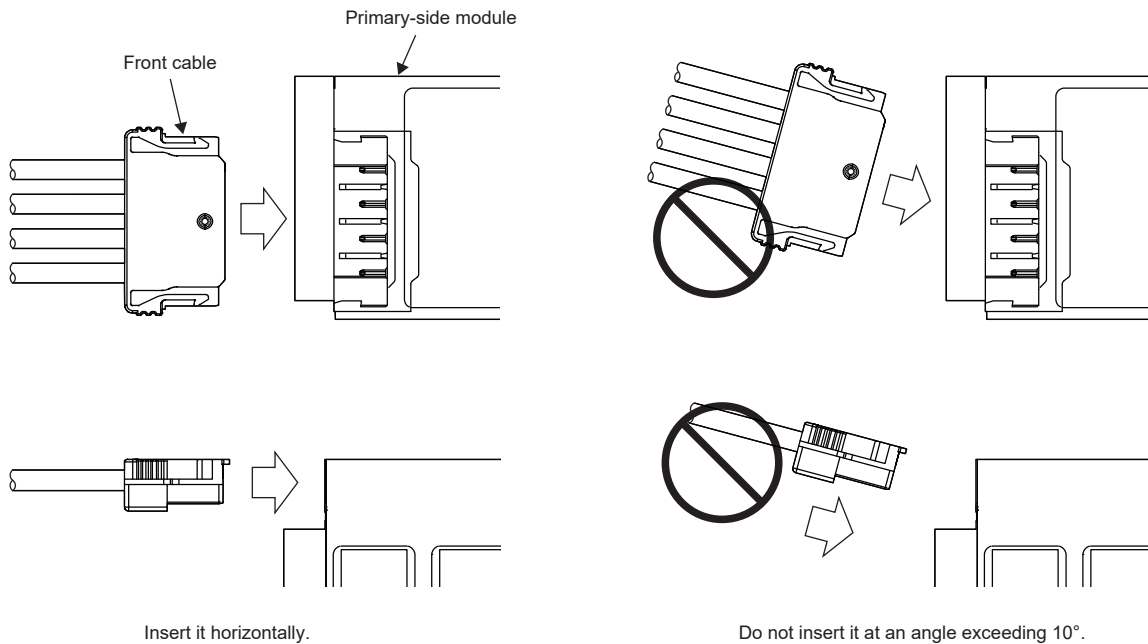
Instructions on the use of lifting machines such as cranes when installing the linear servo motor are shown below.

## Precautions

- The cables should not be damaged, stressed, loaded, or pinched.
- Install the linear servo motor on incombustible material. Installing the linear servo motor either directly on or near combustibles may lead to smoke or a fire.
- Provide adequate protection so as to prevent conductive matter (such as screws and metal fragments) and combustible matter (such as oil) from entering the linear servo motor.
- The linear servo motor may become hot depending on the operating method. Take safety measures such as providing covers.
- Machine operators and workers installing linear servo motors are not allowed to wear or carry electronic devices (such as watches, calculators, and personal computers) or carry magnetic recording media (such as IC cards and magnetic cards) when working close to the secondary side. The magnetic effect of such items may cause operation failure or malfunction.
- Securely fix the linear servo motor to the machine. If attached insecurely, the motor may come off during operation.
- Do not overtighten the eyebolts of the linear servo motor. Tightening too hard may damage the tap.
- Do not stack in excess of the specified number of product packages.
- Do not carry the linear servo motor by the cables or connectors. Doing so may damage the linear servo motor.
- When installing the linear servo motor, follow the user's manual and install the motor in a place that can support its weight.
- When installing the secondary side, use non-magnetic tools.
- Securely fix the linear servo motor to the machine. If attached insecurely, the motor may come off during operation.
- The travel direction of the linear servo motor and the linear encoder must match. Failing to do so may cause the linear servo motor to operate unexpectedly.
- To prevent a connection failure, malfunction, or similar problem, do not strike the connector.
- Use the product within the specified environment. For details of the environment, refer to the specifications for the linear servo motor series being used.
- To prevent rust, do not touch the linear servo motor with bare hands.
- The primary side and secondary side of the linear servo motor may be damaged if they are dropped or struck.
- Do not install or operate a servo amplifier or linear servo motor that is missing parts or is damaged.
- The permanent magnet on the secondary side of the linear servo motor generates a magnetic attraction force against magnetic materials. Therefore, individuals using a medical device such as a pacemaker must check with the medical device manufacturer regarding whether they can work in such an environment.
- When in the original packing state (inside the cardboard box) that it was in when shipped from Mitsubishi Electric, the magnet on the secondary side does not have any serious impact on the outside environment. However, do not place magnetic materials (including the primary side, other secondary sides, and tools) close to the secondary side until the linear servo motor is assembled to the machine. Be cautious in the workplace and its surroundings.
- When installing the linear servo motor and working near the linear servo motor, use non-magnetic tools. Such tools are necessary to ensure safety and improve workability. In particular, exercise care when installing the primary side after installation of the secondary side is complete. For which screws to use, refer to the "Dimensions" section in the chapter for the linear servo motor series being used.
- Do not get on the equipment or put a heavy load on it.
- Do not drop or strike the linear servo motor.
- To prevent a fire or injury from occurring in case of an earthquake or other natural disasters, securely install, mount, and wire the linear servo motor in accordance with the user's manual.
- To prevent an electric shock or a fire, do not disassemble, repair, or modify the product. Disassembled, repaired, and/or modified products are not covered under warranty.
- Keep the cumulative pitch error of the mounting screw holes to within  $\pm 0.2$  mm ( $\pm 0.1$  mm for the LM-K2 series). When two or more secondary sides are installed, clearance may be left between the secondary sides depending on the installing method and the number of secondary sides.
- When multiple personnel are working simultaneously, confirm that the area of the product containing moving parts is free of

personnel before turning on the power. When personnel are present in the area containing moving parts, provide an interlock to ensure that the equipment does not move.

- During installation, be sure to remove any iron powder or similar debris attached to the product.
- When using the primary side of the LM-H4M series in a connected configuration, always check that the relay connector is properly inserted. Improper insertion of the relay connector may lead to motor failure. Before connecting the servo amplifier, check the continuity of the U/V/W terminals between the front cable and the terminating motor. Do not use the  $\ominus$  terminal.
- When inserting the front cable into the primary-side module, insert the front cable horizontally as shown in the following diagram, and do not insert it at an angle. Failure to do so may cause malfunction.

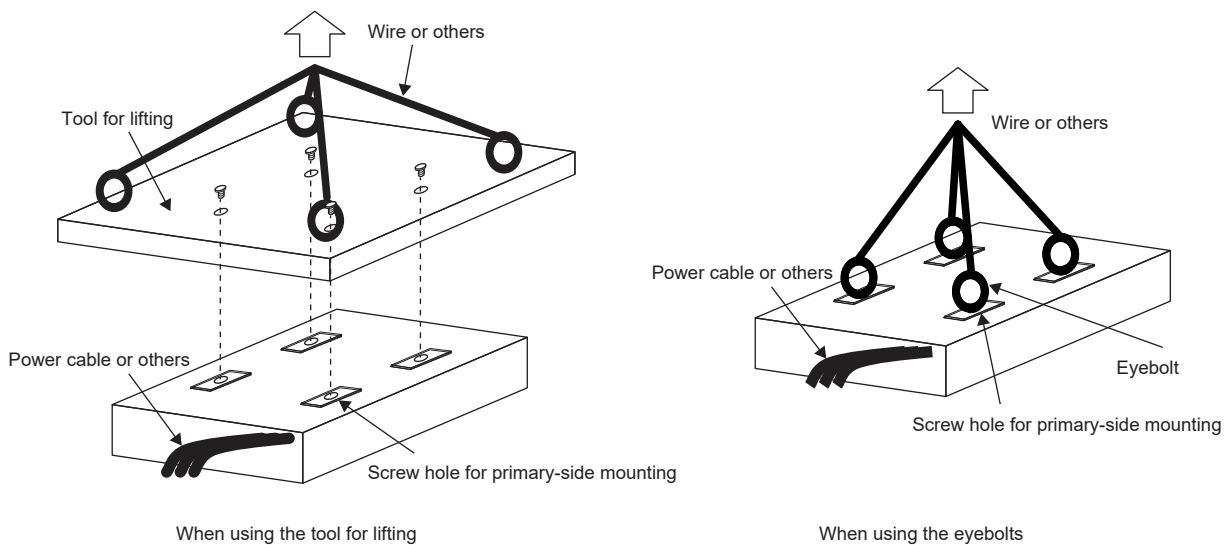


## Primary side (coil)

To lift the primary side, either attach a lifting tool to the primary side or attach eyebolts to the screw holes used for primary-side mounting as shown in the following figure.

When lifting, ensure that the wire does not apply stress to the mold part or the power supply cable, etc.

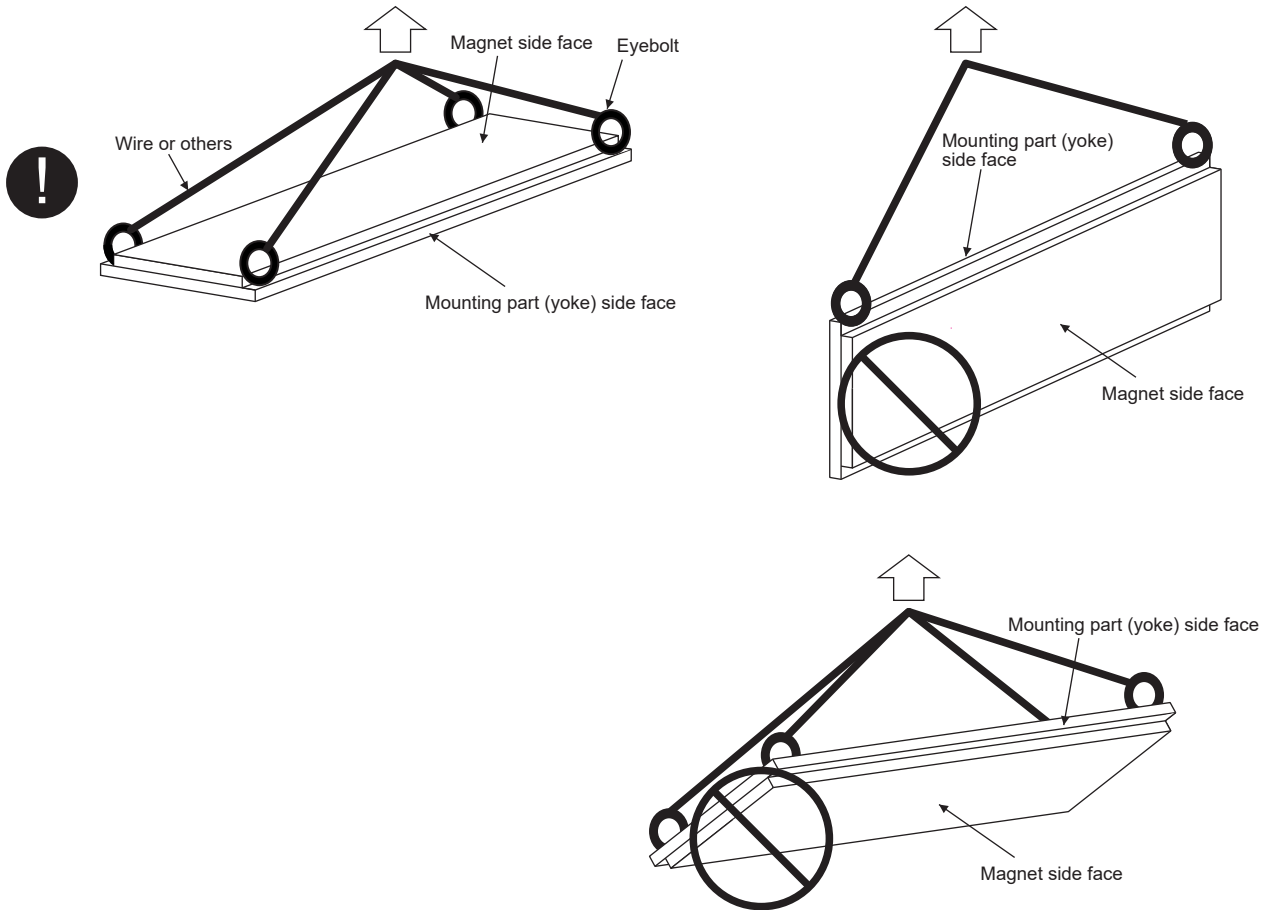
Set the lifting points (two or more) on both longitudinal ends.



## Secondary side (magnet)

To lift the secondary side, attach eyebolts to the screw holes used for secondary-side mounting as shown in the following figure.

To avoid danger due to the magnetic attraction force when lifting the secondary side, ensure that the magnet face side is directed upward and set four or more lifting points.



# 1.5 Instructions on storage

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## Precautions

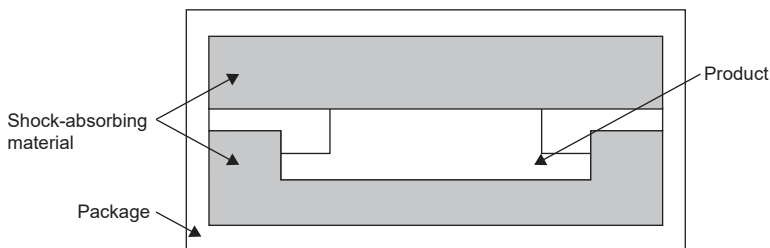
Note the following when storing the linear servo motor for an extended period of time (guideline: three or more months).

- Always store the linear servo motor indoors in a clean and dry place.
- When storing in a dusty and humid area, take measures such as covering the whole product.
- Although the linear servo motor has been rust-proofed with paint and rust prevention oil before shipment, rust may appear if the linear servo motor is stored in poor conditions for an extended period of time. If the servo motor is to be stored for longer than six months, re-apply rust prevention oil again to machined surfaces.
- When the product has been stored for an extended period of time, contact your local sales office.
- Be sure to strictly maintain the storage requirements (ambient temperature and humidity, etc.).
- Store the product in an environment that is protected from rain water, low in dust, and free of oil and chemical adhesion.
- Do not apply a shock to the servo amplifier or linear servo motor.
- If the insulation resistance of the magnet wire decreases, reconsider how the equipment is being stored.
- Ensure that the product is stored with each side facing the proper direction.
- Do not leave the product (primary or secondary-side) unpacked when it is not in use. If the product is not fixed into place on the machine or equipment, store it correctly in the packing box that it came in.

## Storage method

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- Correctly store the linear servo motor inside the packing box it came in.



- When storing the secondary side, place signage stating "Handle with care - Strong magnetic field" or similar on the packing box or storage shelf, and also take measures that make the storage location known in the surrounding area.
- Do not use a deformed packing box.
- For details of the storage environment requirements, refer to the following.

☞ Page 13 Environment

- When lifting the product using a hoisting attachment, do not apply shock and stress to the mold part.

# 1.6 Instructions on disposal

---

## Precautions

- The servo amplifier and the primary side of the linear servo motor must be disposed in accordance with "DISPOSAL OF WASTE".
- Since the secondary side of the linear servo motor uses a permanent magnet, demagnetize the entire secondary side by heating it to 300 °C or more, then dispose of it in accordance with "DISPOSAL OF WASTE".
- The permanent magnet on the secondary side of the linear servo motor generates a magnetic attraction force against magnetic materials. Therefore, individuals using a medical device such as a pacemaker must check with the medical device manufacturer regarding whether they can work in such an environment.
- Exercise caution against the magnetic force from the secondary side during and after disassembly, and until the secondary side has been demagnetized.
- When disassembling and disposing of the linear servo motor, do not place magnetic materials (including the primary side, other secondary sides, and tools) close to the secondary side.
- Use non-magnetic tools when disassembling and disposing of the linear servo motor, and when working near the motor. Such tools are necessary to ensure safety and improve workability.

# 2 INSPECTION

The linear servo motor is able to function as a motor after it is mounted in (built-in) the equipment. The IP rating is IP00. Perform the following inspections and cleaning.

## Precautions

- The linear servo motor is structurally unrepairable. If the linear servo motor is damaged, it must be replaced.
- To prevent a malfunction, do not perform an insulation resistance test (megger test) on the linear servo motor.
- Customers must not disassemble and/or repair the equipment.
- Discoloration of the molded resin of the linear servo motor may occur. Although the chance of malfunction due to discoloration is slim, still inspect the molded resin portion.
- If a stainless steel magnet protective cover is used for the secondary side, damage or deformation may occur if the cover is strongly pressed or if magnetic material is attached to it. Exercise special care with the end part of the product as it is easily deformed.

## 2.1 Inspections of the primary side (coil)

### Attachment of water and oil

Check that the primary and secondary side of the linear servo motor are not wet with water or oil. If the linear servo motor is wet, a malfunction may occur due to deterioration of the insulation on the primary side. Establish a mechanical structure in which water and oil do not become attached to the linear servo motor.

### Molded resin

Check the molded resin on the primary side for fragmentations, breakages, and cracks. If fragmentations, breakages, and cracks are found, replace the primary side as a malfunction may occur due to deterioration of the insulation.

### Scratches on the surface that faces the secondary side (magnet)

Check for scratches on the primary-side surface facing the secondary side. If there are scratches on the primary-side surface facing the secondary side, replace the primary side. If scratches appear on the primary side due to foreign matter caught in the empty clearance between the primary and secondary side, remove the foreign matter, then establish a mechanical structure that prevents such matter from entering the clearance.

### Looseness of mounting screws

Check the mounting screws on the primary side for looseness. If the mounting screws on the primary side are loose, tighten the applicable screws.

### Scratches and cracks on the linear servo motor cables

Check for scratches and cracks on the linear servo motor cables. If the linear servo motor cables have any scratches and cracks, replace the applicable cables. It is important to perform periodic inspections, especially when the cables are moved during operation.

## 2.2 Inspections of the secondary side (magnet)

### Attachment of water and oil

Check that the primary and secondary side of the linear servo motor are not wet with water or oil. If the linear servo motor is wet, a malfunction may occur due to deterioration of the insulation on the primary side. Establish a mechanical structure in which water and oil do not become attached to the linear servo motor.

### Exposure and levitation of the magnet

Check if the magnet on the secondary side is exposed or levitated. If the magnet on the secondary side is exposed or levitated, replace the secondary side immediately.

### Magnet protective cover

The secondary-side surface is covered with molded resin, a stainless steel cover, or sticker to protect the magnet.

- If foreign matter such as dust is attached to the surface, gently clean the molded resin and stainless steel cover with a cloth soaked in acetone and the sticker with a dry cloth.
- Check the molded resin on the secondary side for fragmentations, breakages, and cracks. If fragmentations, breakages, and cracks are found, replace the secondary side.
- Check for scratches on the molded resin of the secondary side. If the magnet is exposed due to scratches on the molded resin of the secondary side, replace the secondary side. If scratches appear on the secondary side due to foreign matter caught in the empty clearance between the primary and secondary side, remove the foreign matter, then establish a mechanical structure that prevents such matter from entering the clearance.

### Looseness of mounting screws

Check the mounting screws on the secondary side for looseness. If the mounting screws on the secondary side are loose, tighten the applicable screws.

## 2.3 Inspections of the linear encoder

It may become necessary to inspect the linear encoder. For information regarding inspections of the linear encoder, contact the manufacturer of the linear encoder being used.

# 3 REPLACEMENT OF THE LINEAR SERVO MOTOR IN THE ABSOLUTE POSITION DETECTION SYSTEM

## 3.1 Replacement of the primary side (coil) or secondary side (magnet)

After replacing the primary side or the secondary side, perform magnetic pole detection again.

## 3.2 Replacement of the linear encoder

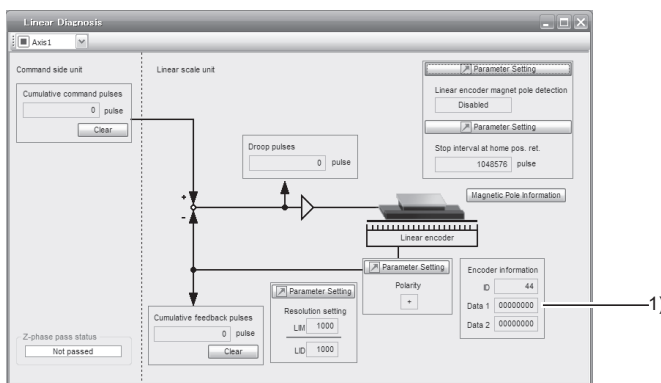
After replacing the linear encoder, perform magnetic pole detection and homing.

### Method for checking the mounting position of the linear encoder

1. Before replacing the linear encoder, check the encoder information using MR Configurator2 with the linear servo motor fixed at the specified position.
2. When replacing the linear encoder, ensure that the position mismatch before and after replacement is  $\pm 0.1$  mm.
3. After replacing the linear encoder, check the encoder information again using MR Configurator2 with the linear servo motor fixed at the specified position.
4. Confirm that the value converted from the difference of the encoder information (resolution unit) is  $\pm 0.1$  mm or less both before and after replacement of the linear encoder.

### Method for viewing encoder information using MR Configurator2

1. After confirming that the computer is connected with the servo amplifier, select "Diagnosis", then select "Linear diagnosis". The following window will appear.



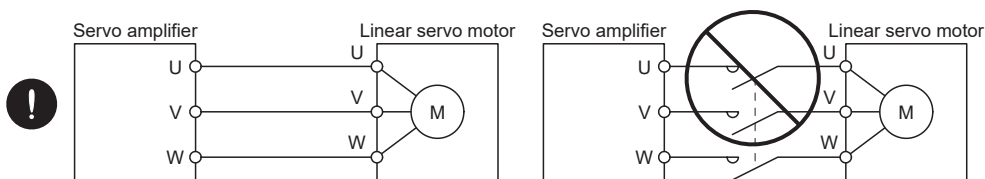
2. The encoder information data ("1") can be viewed here.



# 4 CONNECTING THE SERVO AMPLIFIER AND LINEAR SERVO MOTOR

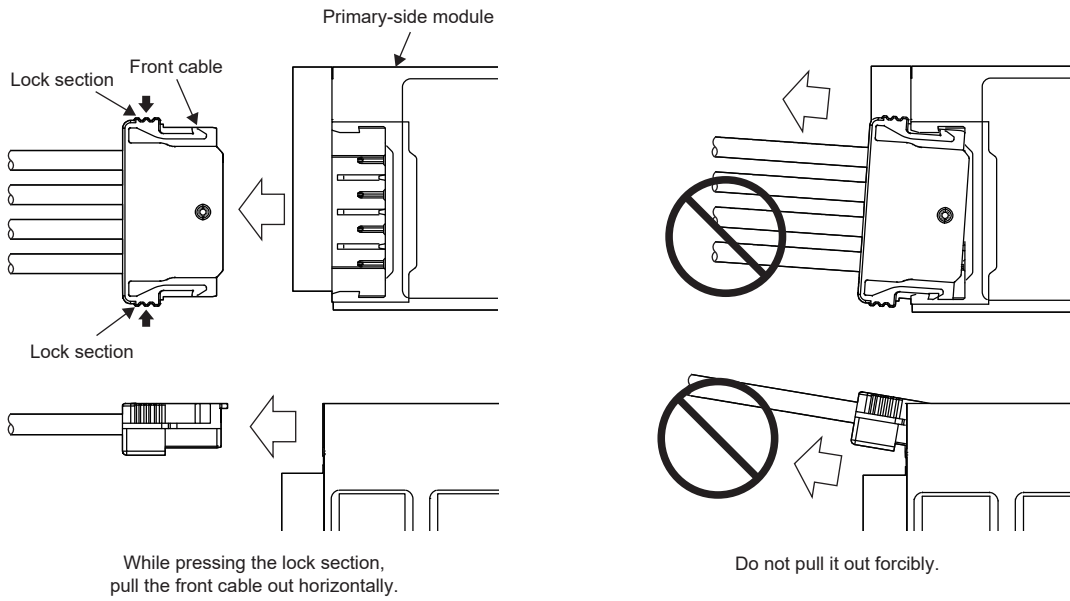
## Precautions

- Insulate the conductive parts of the terminals.
- Performance is not guaranteed if the specified servo amplifier and linear servo motor are not used together in combination. If the combination used is not the specified combination, the servo amplifier or linear servo motor may be damaged or may operate unexpectedly.
- The equipment must be installed in the specified direction.
- Do not install or operate any linear servo motor that is missing parts or is damaged.
- Do not modify the linear servo motor.
- To prevent the linear servo motor from operating unexpectedly, wire the equipment correctly and securely.
- Make sure to connect the cables and connectors by using the fixing screws and the locking mechanism. Failing to do so may cause the cables and connectors to disconnect during operation.
- Do not install a power capacitor, surge killer, or radio noise filter (optional FR-BIF(-H)) on the servo amplifier output side.
- To avoid a linear servo motor malfunction, connect the wires to the correct phase terminals (U/V/W) of the servo amplifier and the linear servo motor.
- To prevent abnormal operation and malfunction, connect the servo amplifier power outputs (U/V/W) to the linear servo motor power inputs (U/V/W) directly. Do not connect a magnetic contactor or the like between the servo amplifier power output and the linear servo motor power input.



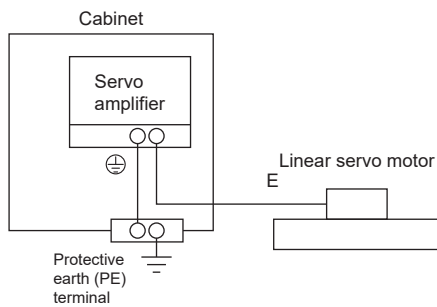
- To prevent a malfunction, do not connect the AC power supply directly to the linear servo motor.
- When the wires are not properly secured to the terminal block, the wires and terminal block may generate heat because of the poor contact. Be sure to secure the wires with the specified torque.
- Cables such as the power cable that extends from the primary side cannot withstand being bent for an extended period of time. Avoid bending the cables by fixing them to the moving part, etc. In addition, wire the servo amplifier using cables that can withstand being bent for an extended period of time.
- Use the linear servo motor and the servo amplifier in the specified combination.
- To prevent malfunction, eliminate static electricity before wiring, switch operation, or similar operations.
- To prevent failure and malfunction, only the power/signal specified in the user's manual should be connected to each terminal.
- We recommend using HIV wires to connect the servo amplifier to the linear servo motor. Therefore, the recommended wire sizes may differ from those of wires used for previous generation linear servo motors.

- When removing the front cable from the primary-side module, pull the front cable out while pressing the lock section. Do not pull the front cable out at an angle as shown in the following diagram. Doing so may cause malfunction.



# 4.1 Precautions for wiring

To ground the linear servo motor, connect the grounding lead wire to the servo amplifier, then connect the wire from the servo amplifier to the ground via the protective earth (PE) terminal of the cabinet. Do not connect the wire directly to the protective earth (PE) terminal of the cabinet.



## Precautions

- To avoid a linear servo motor malfunction, connect the wires to the correct phase terminals (U/V/W) of the servo amplifier and the linear servo motor.
- To prevent a malfunction, do not connect the AC power supply directly to the linear servo motor.

# 4.2 Servo motor power supply cable wiring diagrams

To wire to the servo amplifier, use connectors packed with the servo amplifier or optional connectors.

For details on wiring the connectors, refer to "Explanation of power supply system" in the User's Manual (Hardware) for the servo amplifier being used.

Refer to the following for information about which wires to use for wiring.

☞ Page 34 Wire selection example

## LM-H4M series



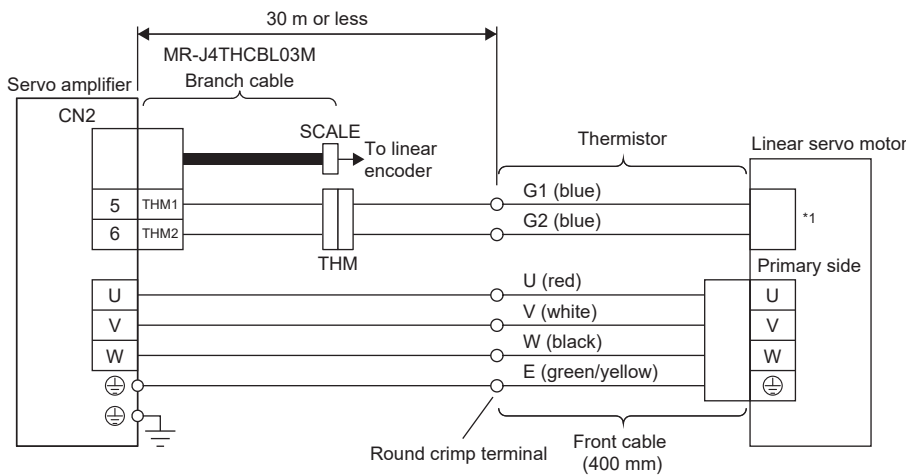
If a front cable longer than 400 mm is required, contact your local sales office.

### With thermistor

For details of the cables and connectors to be connected to CN2, refer to the following manual.

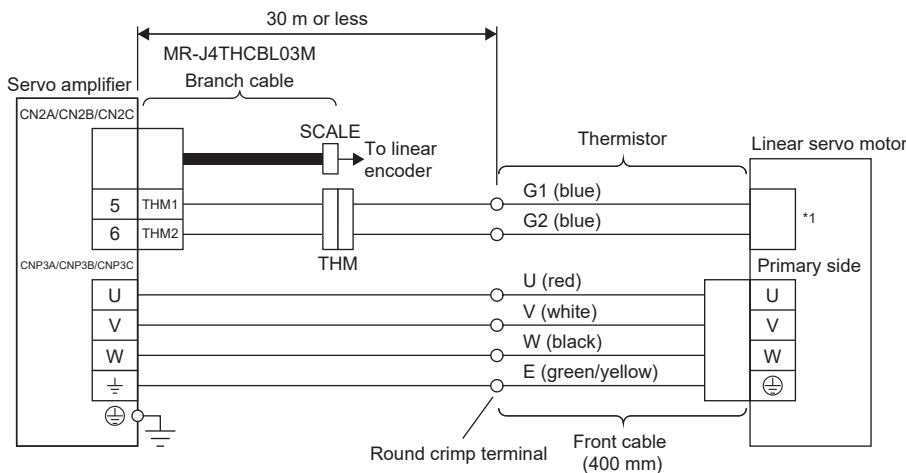
📖 MR-J5 Partner's Encoder User's Manual

#### ■Connecting with the MR-J5\_ servo amplifier



\*1 The thermistor (G1/G2) has no polarity.

#### ■Connecting with the MR-J5W\_ servo amplifier



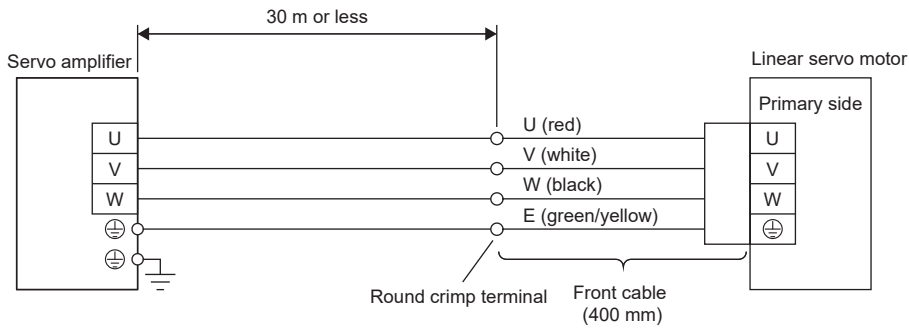
\*1 The thermistor (G1/G2) has no polarity.

## Without thermistor

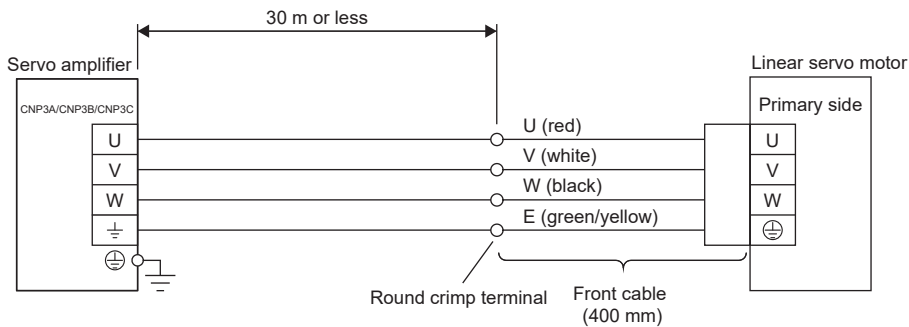
### Point

When using the servo amplifier without the thermistor, changing the servo parameters is required. Refer to "Settings when connecting the LM-H4M series" in the User's Manual (Hardware) for the servo amplifier being used.

### ■Connecting with the MR-J5\_ servo amplifier



### ■Connecting with the MR-J5W\_ servo amplifier



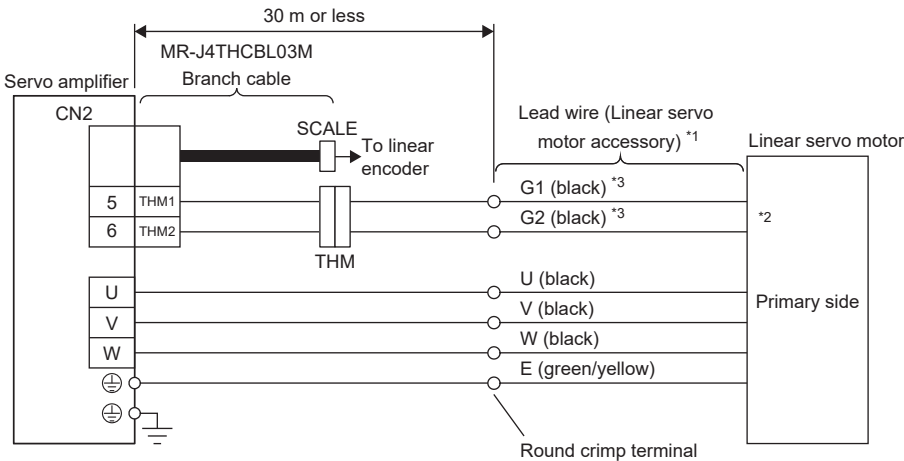
# LM-H3/LM-U2/LM-K2 series

## For servo amplifiers with THM1 and THM2 on CN2

For details of which cables and connectors to connect to CN2, refer to the following manual.

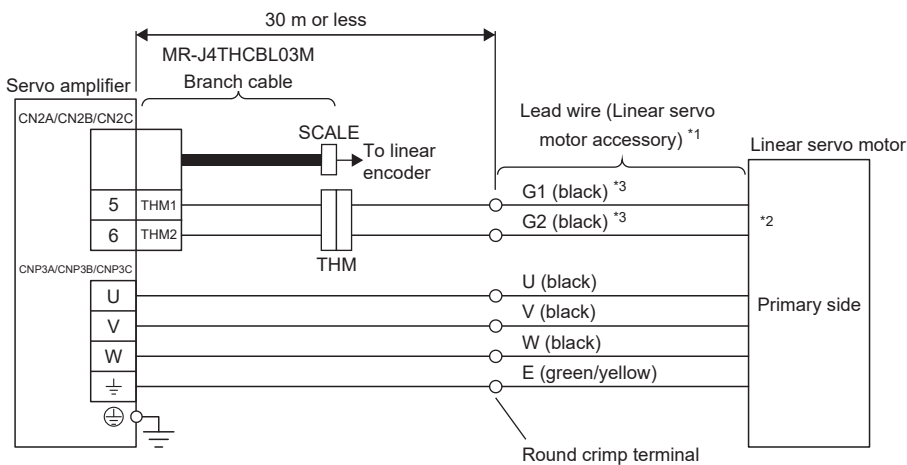
MR-J5 Partner's Encoder User's Manual

### ■Connecting with the MR-J5\_ servo amplifier



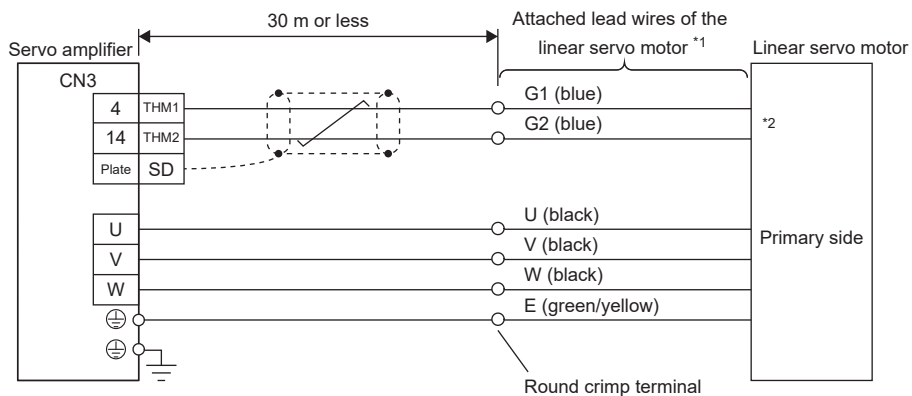
- \*1 The signal names (U/V/W/E/G1/G2) are attached on the lead wires.
- \*2 There is no polarity for the thermistor (G1/G2).
- \*3 For the LM-H3 series, the color is blue.

### ■Connecting with the MR-J5W\_ servo amplifier



- \*1 The signal names (U/V/W/E/G1/G2) are attached on the lead wires.
- \*2 There is no polarity for the thermistor (G1/G2).
- \*3 For the LM-H3 series, the color is blue.

## For servo amplifiers with THM1 and THM2 on CN3



\*1 The signal names (U/V/W/E/G1/G2) are attached on the lead wires.

\*2 There is no polarity for the thermistor (G1/G2).

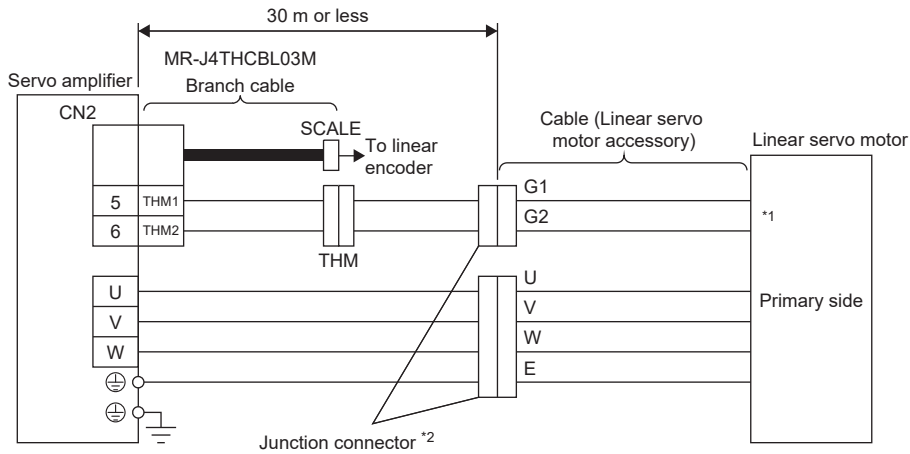
# LM-F series

Junction connectors should be prepared by the customer.

## Connecting with the MR-J5\_ servo amplifier

For details of which cables and connectors to connect to CN2, refer to the following manual.

📖 MR-J5 Partner's Encoder User's Manual



\*1 There is no polarity for the thermistor (G1/G2).

\*2 Refer to the following.

📖 Page 33 Junction connector

### ■ Junction connector

Linear servo motor (primary side)	Connector for power supply	Thermistor connector
LM-FP2B-06M-1SS0 LM-FP2D-12M-1SS0 LM-FP2F-18M-1SS0	Cable receptacle: D/MS3101A18-10S Cable clamp: D/MS3057-10A (Fujikura)	Cable receptacle: D/MS3101A14S-9S Cable clamp: D/MS3057-6A (Fujikura)
LM-FP4B-12M-1SS0 LM-FP4D-24M-1SS0	Cable receptacle: D/MS3101A24-22S Cable clamp: D/MS3057-16A (Fujikura)	

## 4.3 Wire selection example

When cables are fabricated by the customer, wires should be selected in accordance with the application. Selection requirements for the wire size are as follows.

- Construction requirements: Single suspended wire
- Wiring length: 30 m or less

The following shows examples of the wire sizes to select when using HIV wires.

### LM-H4M series

#### Wire size selection examples

LM-H4M series linear servo motor (primary side)		Wire [mm <sup>2</sup> ]		
		For power/grounding (U/V/W/⊕)	For thermistor (G1/G2)	
LM-H4MP3A-07T-KSS0		1.25 (AWG 16)	0.2 (AWG 24)	
LM-H4MP3B-14T-KSS0	Standard combination			
	Increased thrust/speed combination			
LM-H4MP3C-21T-KSS0	Standard combination			
	Increased thrust/speed combination			
LM-H4MP3D-28T-KSS0	Standard combination			
	Increased thrust/speed combination			
LM-H4MP3E-36T-KSS0	Standard combination			
	Increased thrust/speed combination			
LM-H4MP3F-43T-KSS0	Standard combination			2 (AWG 14)
	Increased thrust/speed combination			
LM-H4MP3G-50T-KSS0				
LM-H4MP3H-57T-KSS0				

# LM-H3/LM-U2/LM-F/LM-K2 series

## Wire size selection examples

### ■Wire size selection example 1 (HIV wire)

Linear servo motor (primary side)	Wire [mm <sup>2</sup> ]	
	For power/grounding (U/V/W/E)	For thermistor (G1/G2)
LM-H3P2A-07P-BSS0	1.25 (AWG 16)	0.2 (AWG 24)
LM-H3P3A-12P-CSS0		
LM-H3P3B-24P-CSS0		
LM-H3P3C-36P-CSS0		
LM-H3P3D-48P-CSS0	2 (AWG 14)	
LM-H3P7A-24P-ASS0	1.25 (AWG 16)	
LM-H3P7B-48P-ASS0	2 (AWG 14)	
LM-H3P7C-72P-ASS0	2 (AWG 14)	
LM-H3P7D-96P-ASS0	3.5 (AWG 12)	
LM-U2PAB-05M-0SS0	1.25 (AWG 16)	
LM-U2PAD-10M-0SS0		
LM-U2PAF-15M-0SS0		
LM-U2PBB-07M-1SS0		
LM-U2PBD-15M-1SS0		
LM-U2PBF-22M-1SS0		
LM-U2P2B-40M-2SS0		
LM-U2P2C-60M-2SS0	3.5 (AWG 12)	
LM-U2P2D-80M-2SS0	5.5 (AWG 10)	
LM-K2P1A-01M-2SS1	1.25 (AWG 16)	
LM-K2P1C-03M-2SS1	2 (AWG 14)	
LM-K2P2A-02M-1SS1	1.25 (AWG 16)	
LM-K2P2C-07M-1SS1	3.5 (AWG 12)	
LM-K2P2E-12M-1SS1	5.5 (AWG 10)	
LM-K2P3C-14M-1SS1	3.5 (AWG 12)	
LM-K2P3E-24M-1SS1	5.5 (AWG 10)	

### ■Wire size selection example 2 (HIV wire)

LM-F series linear servo motor (primary side)		Wire [mm <sup>2</sup> ]	
		For power/grounding (U/V/W/E)	For thermistor (G1/G2)
LM-FP2B-06M-1SS0	Natural cooling	2 (AWG 14)	0.2 (AWG 24)
	Liquid cooling		
LM-FP2D-12M-1SS0	Natural cooling	2 (AWG 14)	
	Liquid cooling	3.5 (AWG 12)	
LM-FP2F-18M-1SS0	Natural cooling	2 (AWG 14)	
	Liquid cooling	3.5 (AWG 12) <sup>*1</sup>	
LM-FP4B-12M-1SS0	Natural cooling	5.5 (AWG 10)	
	Liquid cooling		
LM-FP4D-24M-1SS0	Natural cooling		
	Liquid cooling		

\*1 When wiring to the linear servo motor power connector, use wires that have a heat resistance of 105 °C or more.

# 5 LM-H4M SERIES

## 5.1 Model name designation

### Primary-side model name designation

#### Precautions

When purchasing the primary side, order it using the purchase model.

#### Connection model

##### ■Primary side (coil)

The following describes what each block of a model name indicates. Not all combinations of the symbols are available.

LM - H 4 M P 3 A - 0 7 T - K S S 0

Symbol	Dimension [mm]	Continuous thrust [N]	Number of primary-side modules
A - 07	70	72	1
B - 14	130	144	2
C - 21	190	216	3
D - 28	250	288	4
E - 36	310	360	5
F - 43	370	432	6
G - 50	430	504	7
H - 57	490	576	8

\*1 The length includes the end blocks.

#### Purchase model

##### ■Primary side (coil)

LM - H 4 M P 3 A - 0 7 T - H S T - K S S 0

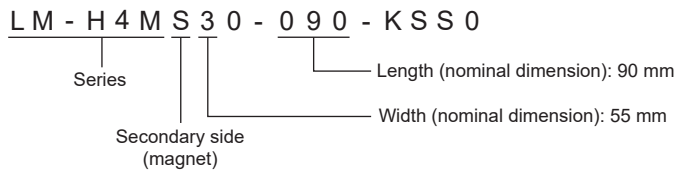
Symbol	Set name	Thermistor
HST	Front set with thermistor	Included
HS	Front set	None
RS0	Relay set	-

#### Category

Model name	Application	Example
Connection model	Use when writing servo amplifier parameters	LM-H4MP3E-36T-KSS0 (5-module connected model)
Purchase model	Use when purchasing the product	LM-H4MP3A-07T-HS-KSS0 (Front set model)

# Secondary-side model name designation

## Secondary side (magnet)



## 5.2 Standard specifications

### Standard specifications list

Number of primary-side modules		1	2	3	4	5	6	7	8
Connection model Primary side (coil) LM-H4M_		P3A-07T-KSS0	P3B-14T-KSS0	P3C-21T-KSS0	P3D-28T-KSS0	P3E-36T-KSS0	P3F-43T-KSS0	P3G-50T-KSS0	P3H-57T-KSS0
Model name Secondary side (magnet) LM-H4M_		S30-090-KSS0							
Power supply capacity [kVA]		Refer to "Power supply capacity and generated loss" in the User's Manual (Hardware) for the servo amplifier being used.							
Cooling method		Natural cooling							
Thrust	Continuous <sup>*2</sup> <sup>*4</sup> <sup>*5</sup> [N]	72	120 (144)	180 (216)	230 (288)	360	360 (432)	504	576
	Maximum <sup>*5</sup> [N]	180	300 (360)	500 (540)	630 (720)	900	1080	1260	1440
Maximum speed	Continuous running range <sup>*5</sup> [m/s]	3.5	3.0 (3.5)	3.5	3.5	3.5	3.0 (3.5)	3.5	3.5
	Short-duration running range <sup>*1</sup> <sup>*5</sup> [m/s]	5.0	5.0	5.0	5.0	3.5 (5.0)	3.0 (5.0)	5.0	5.0
Magnetic attraction force [N]		650	1300	1950	2600	3250	3900	4550	5200
Rated current <sup>*5</sup> [A]		1.1	1.7 (2.1)	2.6 (3.2)	3.2 (4.2)	5.3	5.3 (6.3)	7.4	8.4
Maximum current <sup>*5</sup> [A]		3.6	5.4 (7.2)	8.8 (10.0)	11.2 (14.4)	17.8	20.5	24.6	28.0
Recommended load to motor mass ratio <sup>*5</sup> <sup>*6</sup>	3 m/s or less	50 times or less	28 times or less (50 times or less)	34 times or less (50 times or less)	50 times or less	50 times or less			
	More than 3 m/s	19 times or less	9 times or less (17 times or less)	11 times or less (42 times or less)	32 times or less				
Thermistor		External (included with the front set with thermistor) <sup>*7</sup>							
Insulation class		155 (F)							
Structure		Open (IP rating: IP00 <sup>*3</sup> )							
Vibration resistance [m/s <sup>2</sup> ]		49							
Mass	Primary side <sup>*8</sup> [kg]	0.61	1.1	1.6	2.2	2.7	3.2	3.7	4.3
	Secondary side [kg]	0.25							

\*1 The actual maximum speed of the linear servo motor is the lower value between the maximum speed of the linear servo motor and the rated speed of the linear encoder.

\*2 The continuous thrust values in the table apply when an aluminum board (table) with the dimensions (L [mm] × W [mm] × H [mm]) shown below is mounted on the primary side. (The dimensions shown are for reference purposes only.)

LM-H4MP3A-07T-KSS0: 150 × 100 × 10

LM-H4MP3B-14T-KSS0: 254 × 254 × 25

LM-H4MP3C-21T-KSS0: 254 × 254 × 25

LM-H4MP3D-28T-KSS0: 336 × 315 × 30

LM-H4MP3E-36T-KSS0: 480 × 315 × 40

LM-H4MP3F-43T-KSS0: 480 × 315 × 40

LM-H4MP3G-50T-KSS0: 624 × 315 × 40

LM-H4MP3H-57T-KSS0: 624 × 315 × 40

\*3 IP classifies the degree of protection provided against the intrusion of solid objects and water in electrical enclosures.

\*4 Use the linear servo motor with 70 % or less of the effective load ratio when it is servo-locked or if there is faint reciprocating motion.

\*5 The values in parentheses indicate those under conditions of increased thrust and speed.

\*6 This indicates the ratio of the load mass to the primary side mass of the linear servo motor. If the load to motor mass ratio exceeds the specified value, contact your local sales office.

\*7 Linear servo motors without a thermistor are also supported. If a thermistor is required, purchase a front set with thermistor. If a thermistor is not required, purchase a front set. Refer to the following for details.

☞ Page 44 Configuration

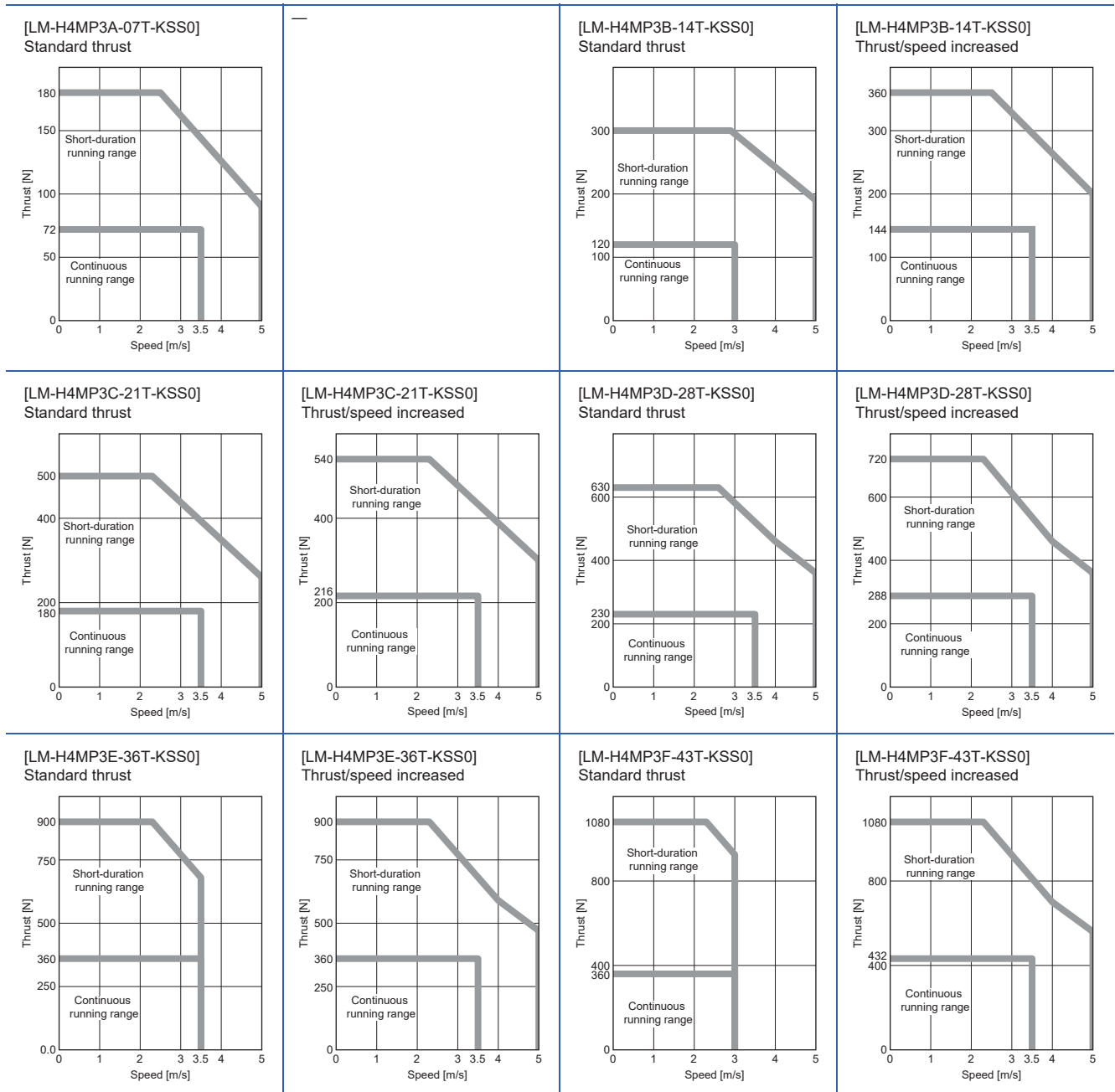
\*8 The mass includes the end blocks.

# Thrust characteristics

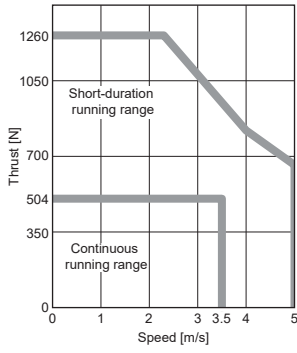
The following shows the thrust characteristic when the power supply input of the servo amplifier is 3-phase 200 V AC. The continuous/maximum thrust and maximum speed of the linear servo motor are specified based on the rated voltage and frequency applied by the combined servo amplifier.

For the thrust characteristics at 1-phase 200 V AC, contact your local sales office.

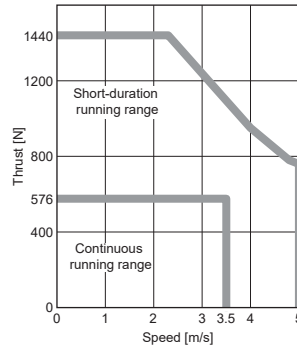
— : 3-phase 200 V AC



[LM-H4MP3G-50T-KSS0]  
Standard thrust



[LM-H4MP3H-57T-KSS0]  
Standard thrust



## 5.3 Derating

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The derating conditions are reference values. Since the temperature rise value of the linear servo motor changes depending on operation conditions such as speed, install a thermistor on the actual machine and confirm that [AL. 0E2 Servo motor overheat warning] or [AL. 046 Servo motor overheat] does not occur before use. If a thermistor is not installed, periodically confirm that there is no abnormal temperature rise of the linear servo motor during operation.

If a warning or alarm occurs, consider taking the following measures:

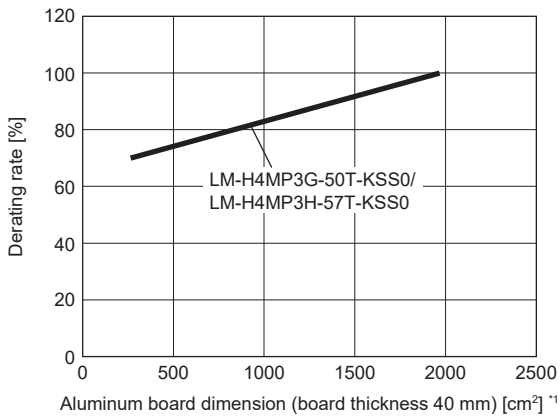
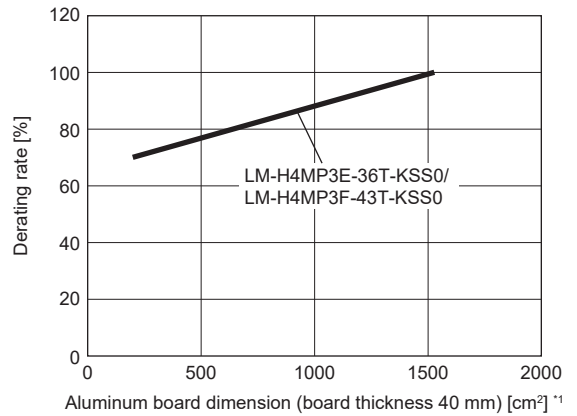
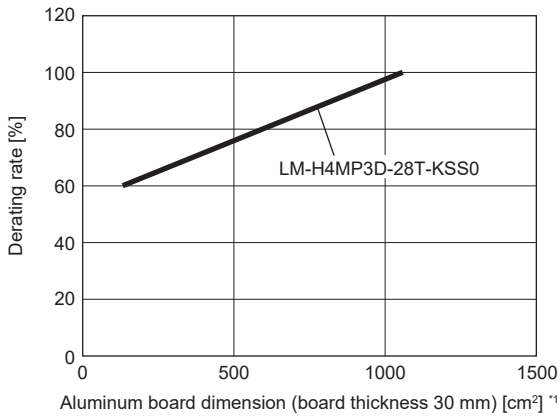
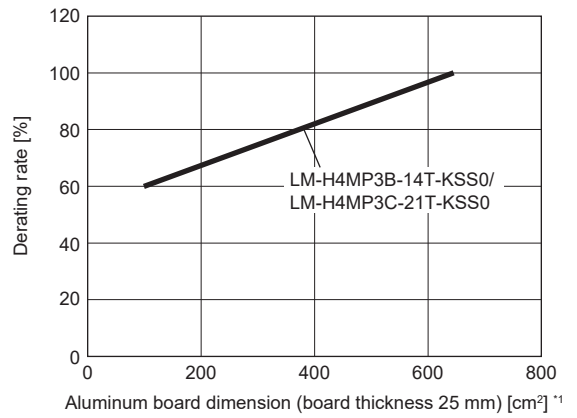
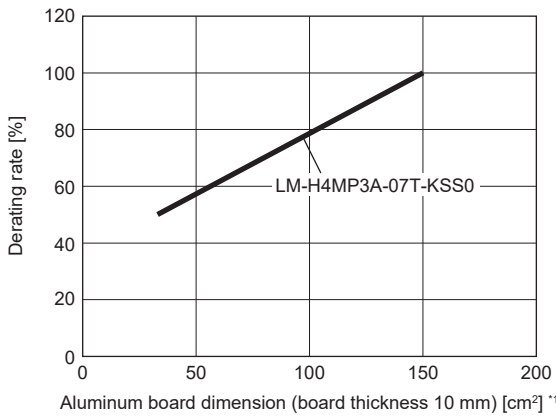
- Lower the effective load ratio of the linear servo motor.
- Review the heat dissipation conditions.

To use this product under conditions with multiple derating, calculate the multiplication of each derating rate, and use at the calculated derating rate or lower.

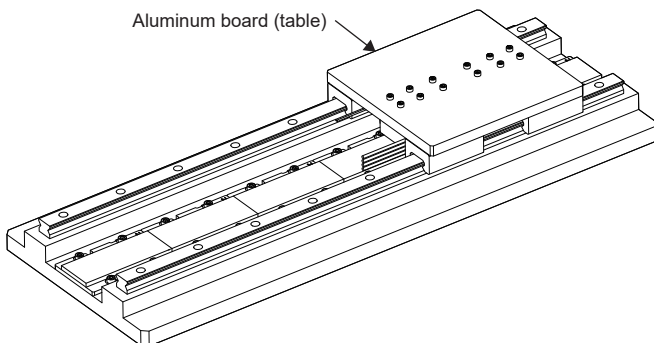
# Restrictions on the aluminum board (table) size

When mounting the product on a machine smaller than the specified aluminum board described in the reference below, use it at the derating rate according to the conditions shown in this section.

☞ Page 38 Standard specifications list

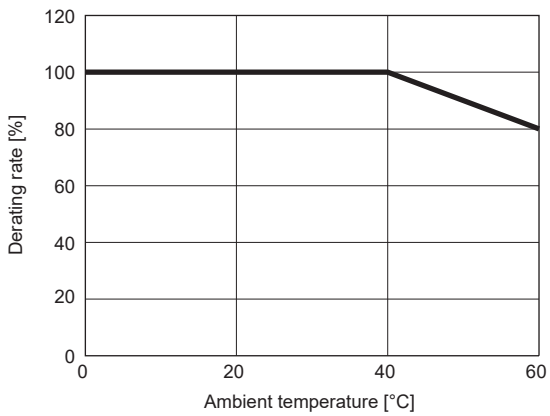


\*1 The aluminum board corresponds to the section indicated in the following figure.



## Restrictions on the ambient temperature

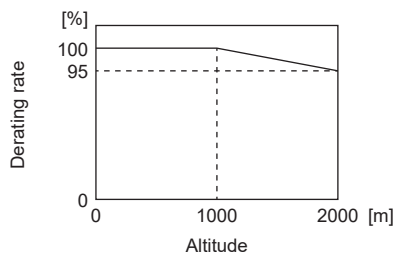
When using this product in an environment with a high ambient temperature, derate the product in accordance with the following conditions:



5

## Restrictions on the altitude

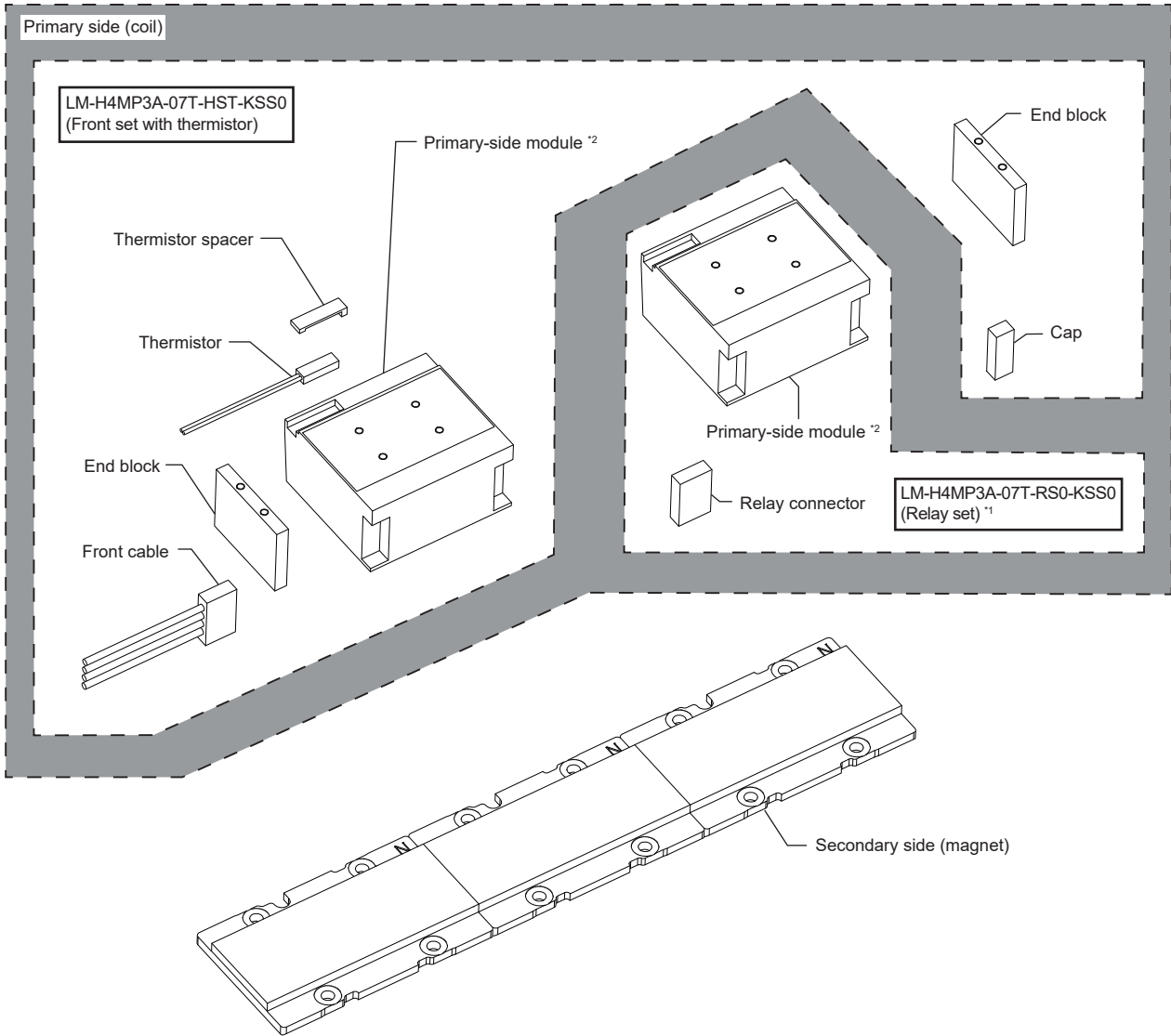
When using this product at an altitude between 1000 m and 2000 m, derate the product in accordance with the following conditions:



# 5.4 Configuration

## With thermistor

The following figure shows LM-H4MP3B-14T-KSS0 (with thermistor).



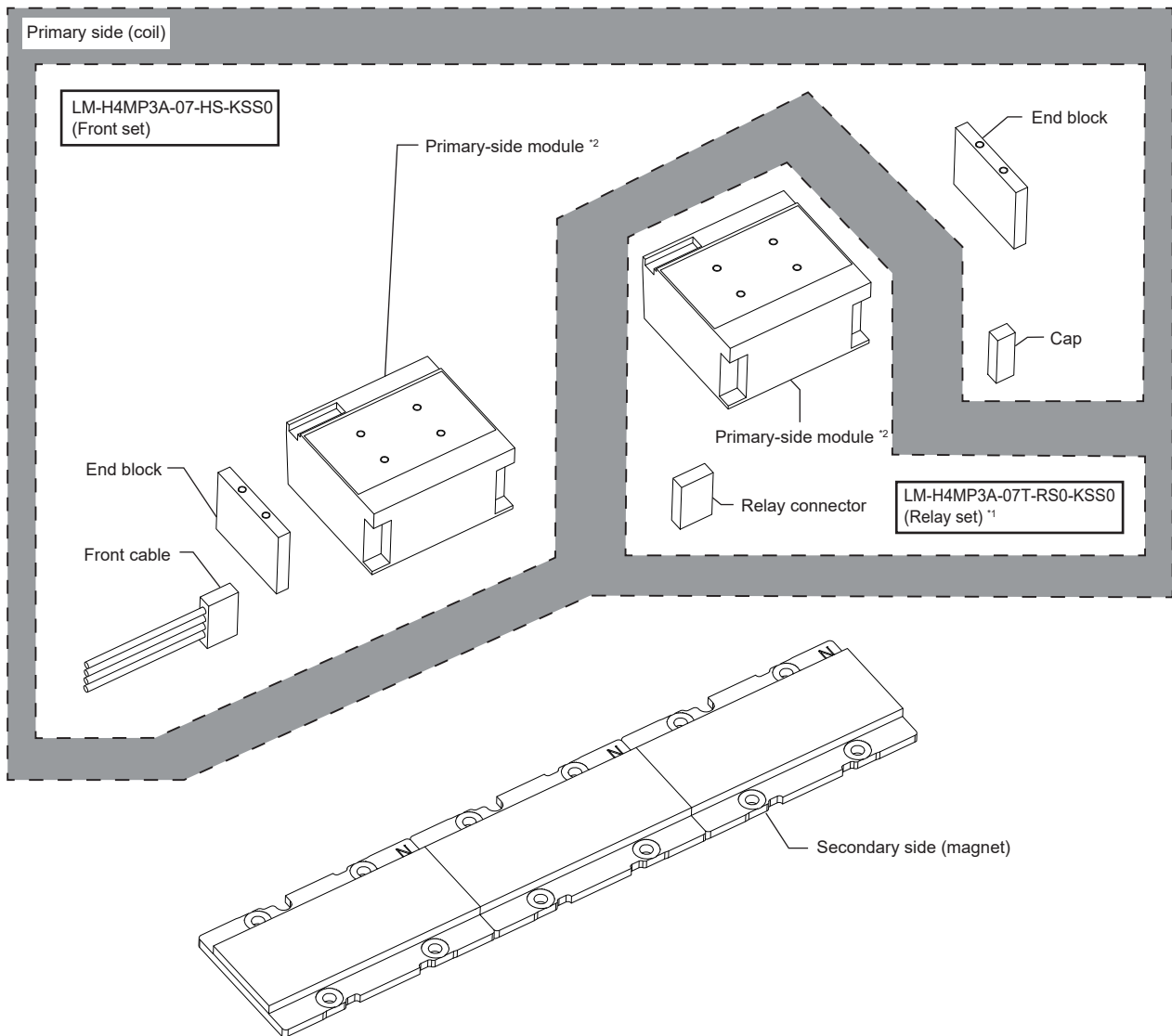
\*1 Number of required LM-H4MP3A-07T-RS0-KSS0 (Relay set)

Connection model	Number of primary-side modules	Number of required LM-H4MP3A-07T-RS0-KSS0 (Relay set)
LM-H4MP3A-07T-KSS0	1	0
LM-H4MP3B-14T-KSS0	2	1
LM-H4MP3C-21T-KSS0	3	2
LM-H4MP3D-28T-KSS0	4	3
LM-H4MP3E-36T-KSS0	5	4
LM-H4MP3F-43T-KSS0	6	5
LM-H4MP3G-50T-KSS0	7	6
LM-H4MP3H-57T-KSS0	8	7

\*2 The primary-side modules included in the front set with thermistor and relay set are identical.

# Without thermistor

The following figure shows LM-H4MP3B-14T-KSS0 (without thermistor).



5

\*1 Number of required LM-H4MP3A-07T-RS0-KSS0 (Relay set)

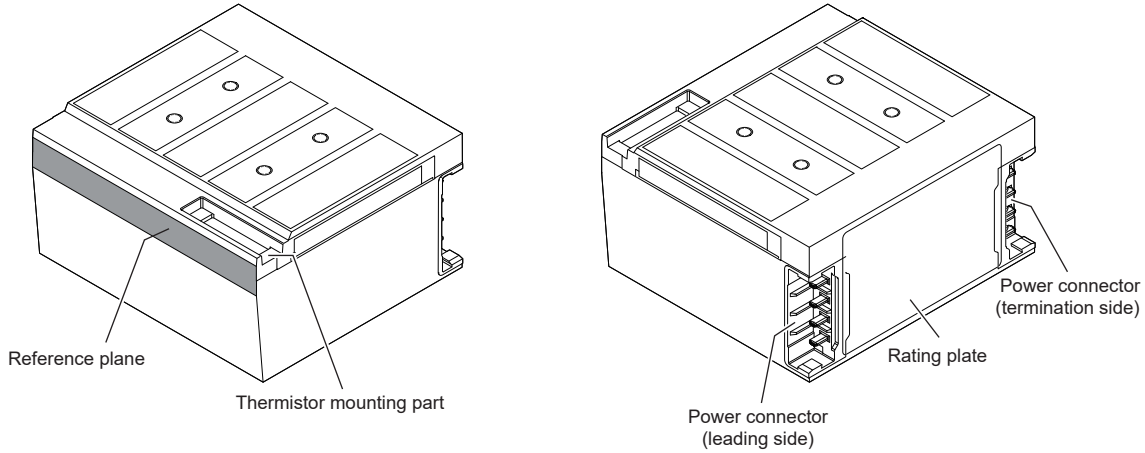
Connection model	Number of primary-side modules	Number of required LM-H4MP3A-07T-RS0-KSS0 (Relay set)
LM-H4MP3A-07T-KSS0	1	0
LM-H4MP3B-14T-KSS0	2	1
LM-H4MP3C-21T-KSS0	3	2
LM-H4MP3D-28T-KSS0	4	3
LM-H4MP3E-36T-KSS0	5	4
LM-H4MP3F-43T-KSS0	6	5
LM-H4MP3G-50T-KSS0	7	6
LM-H4MP3H-57T-KSS0	8	7

\*2 The primary-side modules included in the front set and relay set are identical.

# 5.5 Installation

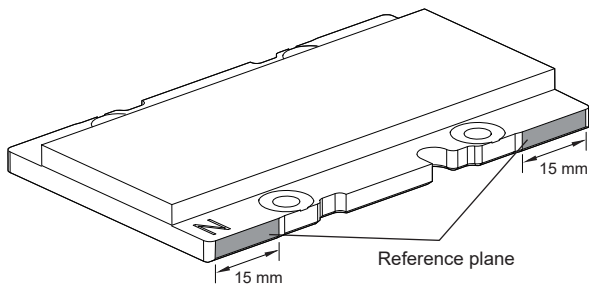
## Part name

### Primary-side module



Name	Application
Reference plane	Install the primary-side module using this plane as a reference.
Thermistor mounting part	When using a thermistor, mount the thermistor and thermistor spacer.
Power connector (leading side)	Insert the front cable. A cap is inserted when shipped.
Power connector (termination side)	Insert either a relay connector or a cap. A cap is inserted in the shipped state. Do not insert the front cable included with the front set with thermistor or the front set. If the front cable needs to be connected to the power connector (termination side), use a cable manufactured by Mitsubishi Electric System Service Co., Ltd. For details, contact your local sales office.
Rating plate	Displays the model name and the positions of U/V/W/⊕ on the power connector.

### Secondary side (magnet)



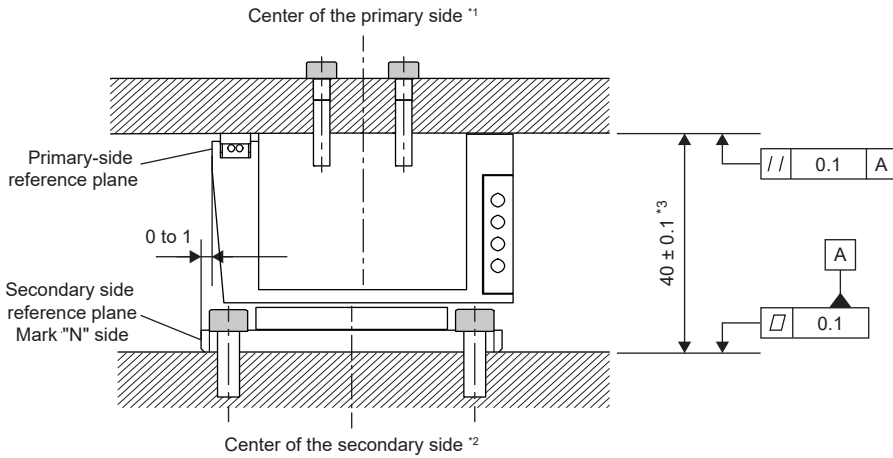
Name	Application
Reference plane	Install the secondary side (magnet) using this plane as a reference.

# Mounting method

## Installation dimensions

The following shows the installation dimensions of LM-H4M.

These dimensional tolerances apply to all connected primary and secondary sides.



[Unit: mm]

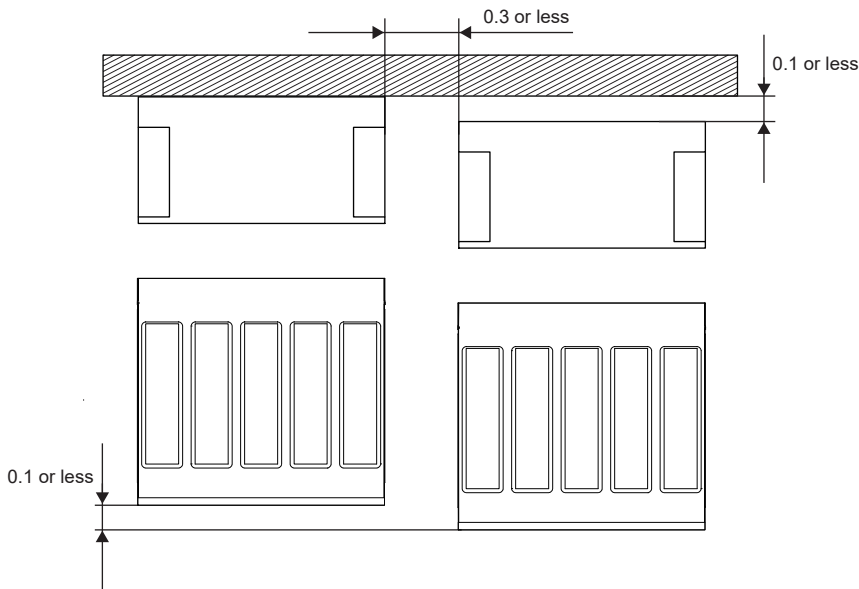
\*1 The center of the primary side is located at the center of the mounting screw pitch.

\*2 The center of the secondary side is located at the center of the mounting screw pitch.

\*3 The dimension  $40 \pm 0.1$  indicates (height of primary side) + (height of secondary side) + (length of empty clearance: 0.85 mm).

## Allowable installation tolerance

The following shows the allowable installation tolerance between primary-side modules.



[Unit: mm]

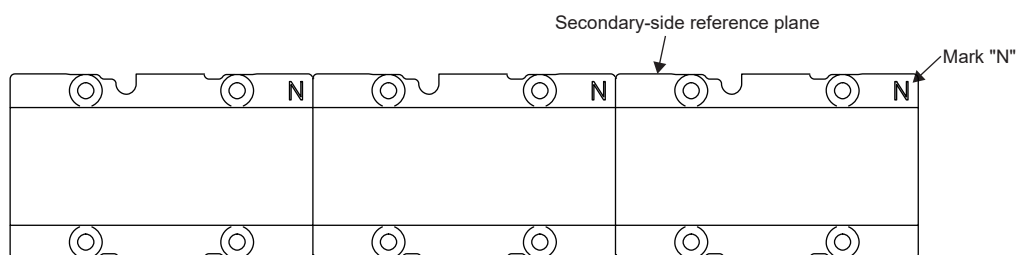
# Installation of the secondary side (magnet)

## Precautions

- If mounting an additional secondary side with a secondary side already set, first set the additional side so that it is distanced from the already mounted one, then slide the additional side to mount it in its specified position as shown in this section.
- Keep the cumulative pitch error of the mounting screw holes to within  $\pm 0.2$  mm. When two or more secondary sides are installed, clearance may be left between the secondary sides depending on the installing method and the number of secondary sides. In such cases, insert shims during installation and remove them after the secondary sides are fixed.

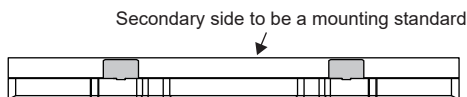
## Procedure

When using multiple secondary sides, arrange them so that the mark "N" attached to each side all share the same orientation to keep the layout of magnetic poles.



In addition, use the following procedure when mounting the secondary sides to decrease the clearance between them.

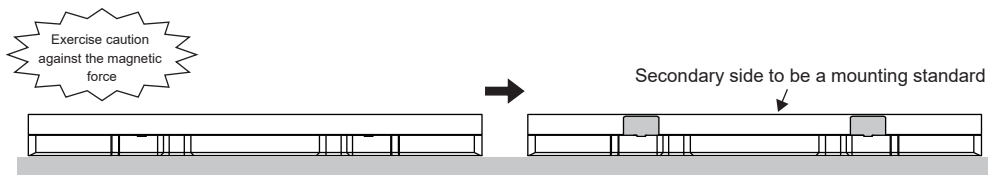
1. Use bolts to securely fix the secondary side that will be used as the mounting standard into place.



2. Set the next secondary side on the installation surface. Then, while aligning it to the reference plane, push it towards the secondary side to be a mounting standard. Ensure that the newly installed secondary side is in close contact with the already installed secondary side without any misalignment.

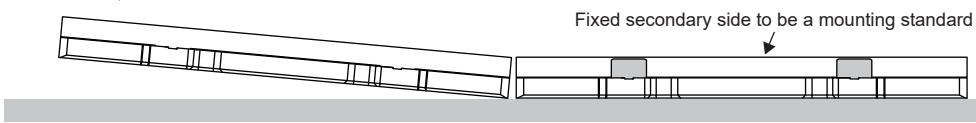
## Precautions

Take care to avoid pinching your fingers.

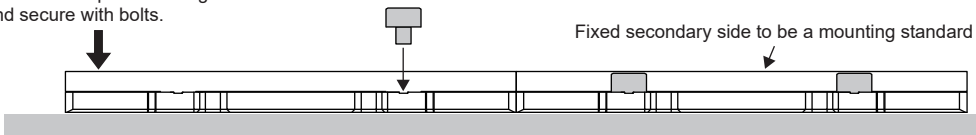


3. To maintain accuracy and prevent tilting caused by magnetic attraction from adjacent secondary sides, hold the secondary side in place while securely fastening it with bolts.

It may tilt.



Hold down to prevent tilting and secure with bolts.



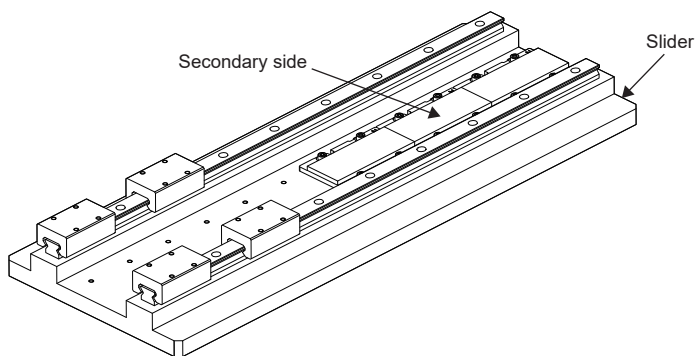
# Installation of the primary side (coil)

## Precautions

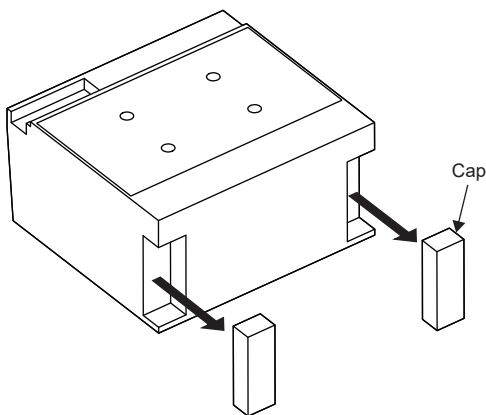
- We recommend mounting the primary side in a position where no secondary side is present. If the primary side must be mounted over the secondary side, use cranes that can fully withstand the load of the attraction force, etc.
- When sliding the primary side over the secondary side after installing, take precautions against the attraction force that is generated.
- When two or more primary sides are installed, gaps may occur between the primary sides depending on the installing method and the number of primary sides.
- Ensure sufficient workspace to attach the relay connector from the side.

## Procedure

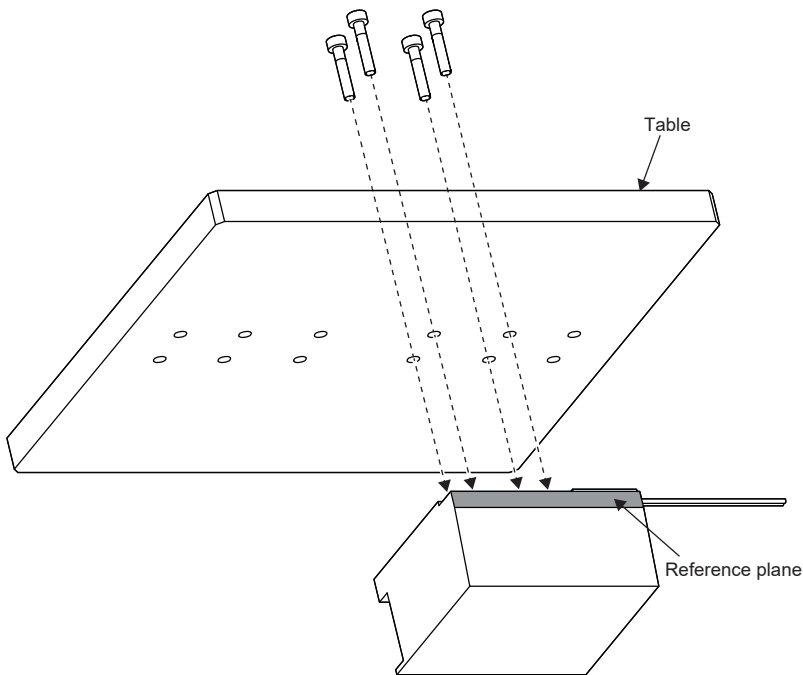
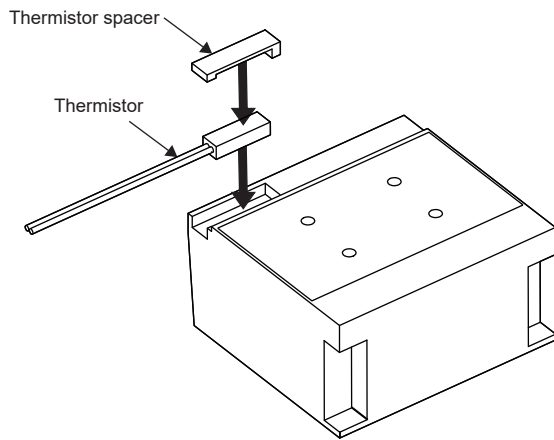
1. Install some of the secondary sides onto the slider.



2. Remove the cap from the primary-side module. Keep the removed cap for use in step 8.

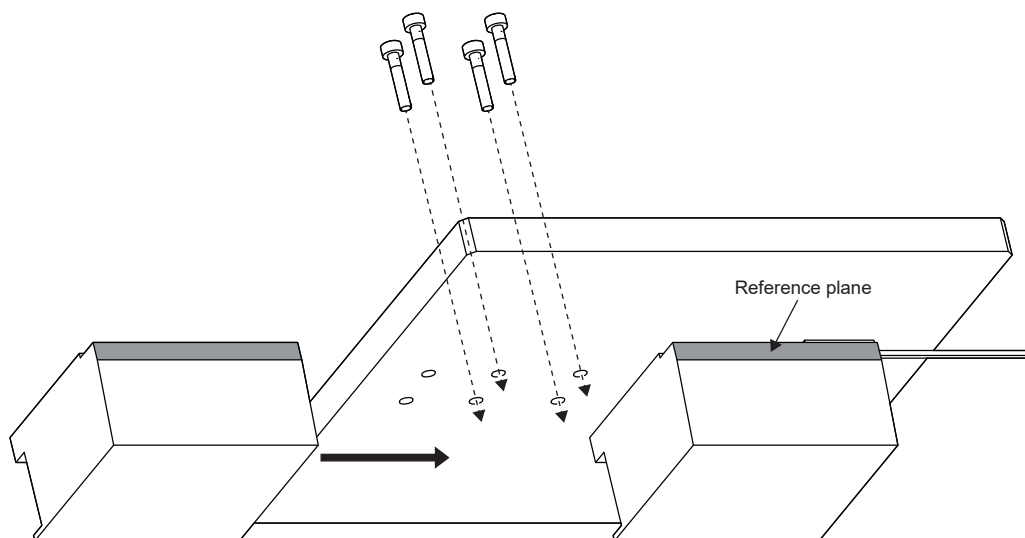


- 3.** When using a thermistor, install the thermistor in the thermistor mounting part and fix it with the thermistor spacer. Route the thermistor lead wire straight through the groove, avoiding pinching it between the table and the spacer. Install the leading primary-side module onto the table while using the reference plane as a reference.
- Recommended tightening torque: 1.25 N•m (permissible range: 1.1 N•m to 1.4 N•m)
  - Thread engagement length of mounting bolts: 5 mm or more



4. When mounting multiple primary-side modules, press them to the front primary-side module while using the reference plane as a reference. Refer to the following for the allowable installation tolerance during installation.

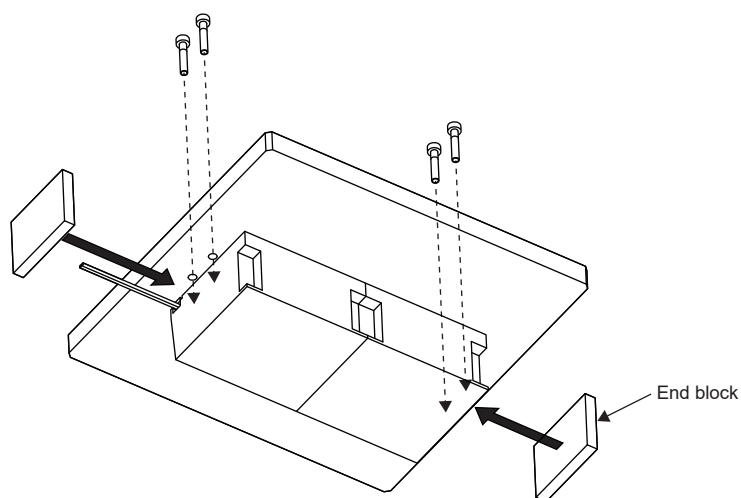
☞ Page 47 Allowable installation tolerance



5. While pressing the end blocks against the primary-side module, mount the end blocks onto the table.

### Precautions

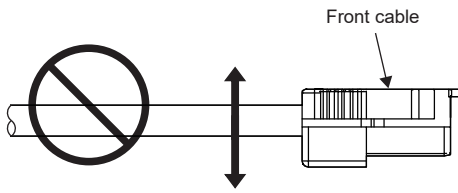
Any gap between the primary-side module and the end blocks may affect the characteristics of the linear servo motor.



6. Insert the front cable into the front primary-side module securely until it clicks. When using multiple primary side modules, attach the relay connector as well. Slide the locking part of the relay connector until it engages firmly. When the relay connector is locked, it will be in the state shown in the figure below.

**Point**

Do not bend the front cable in the direction shown in the figure when routing it.



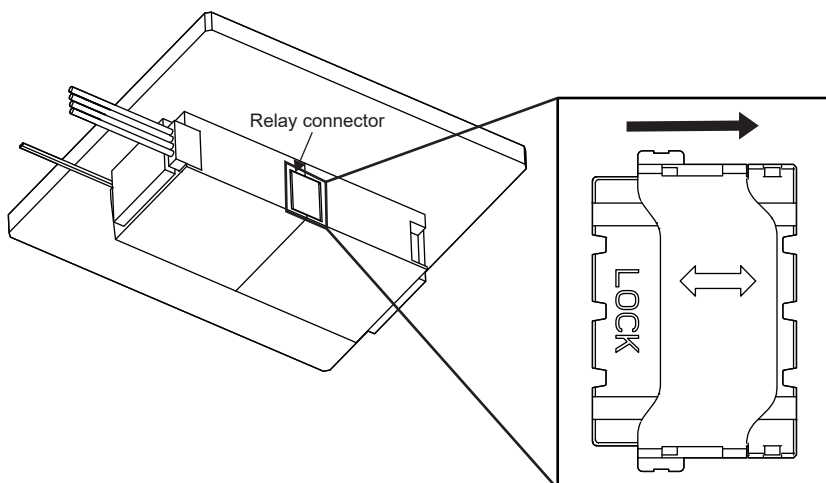
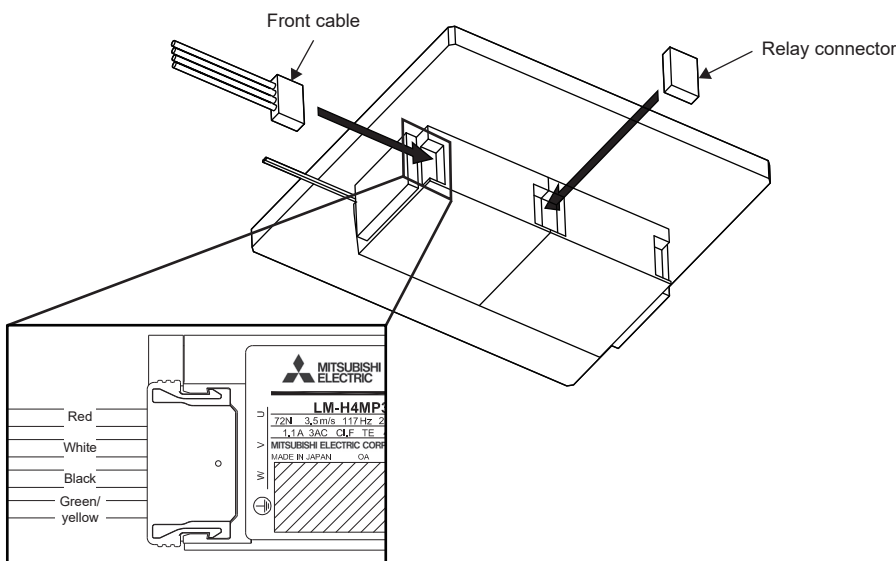
When removing the front cable from the primary-side module, release the lock at both ends and use one of the following methods:

- Use a jig to remove the front cable.
- Remove the primary-side module from the table first before removing the front cable.

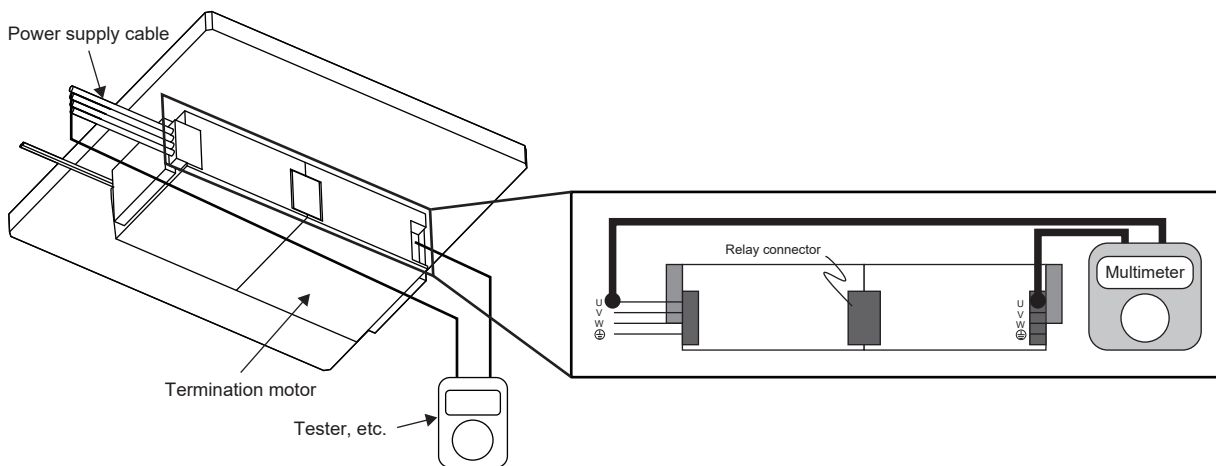
Refer to the following for the removal method.

➡ Page 26 CONNECTING THE SERVO AMPLIFIER AND LINEAR SERVO MOTOR

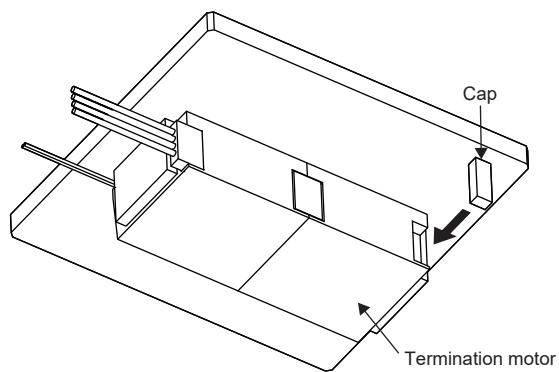
If the front cable needs to be connected to the power connector (termination side), use a cable manufactured by Mitsubishi Electric System Service Co., Ltd. For details, contact your local sales office.



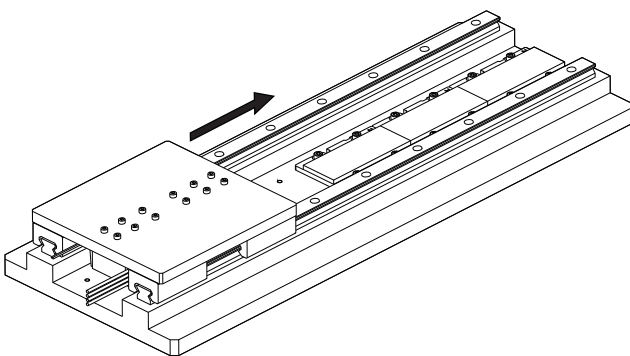
7. Check the continuity between the power cable and the termination motor using a tester or similar tool. Use any one of the U, V, or W terminals to check continuity. Do not use the  $\oplus$  terminal to check continuity.



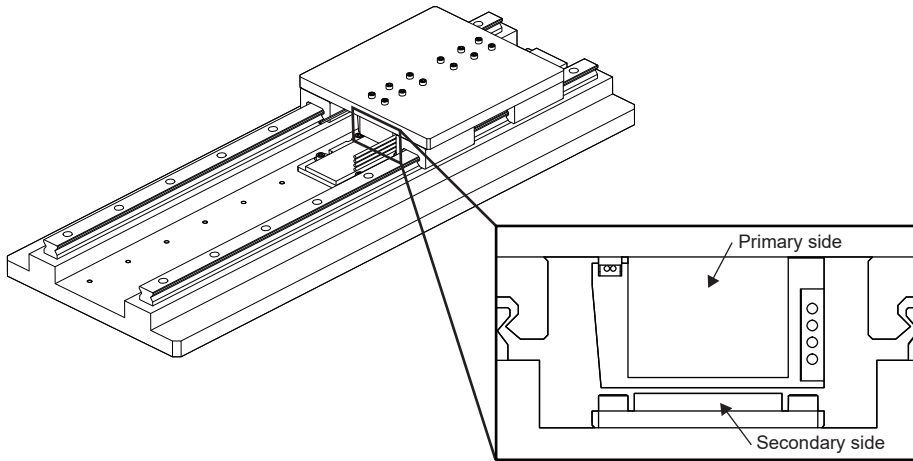
8. Insert the cap removed in step 1 into the termination motor until it clicks securely.



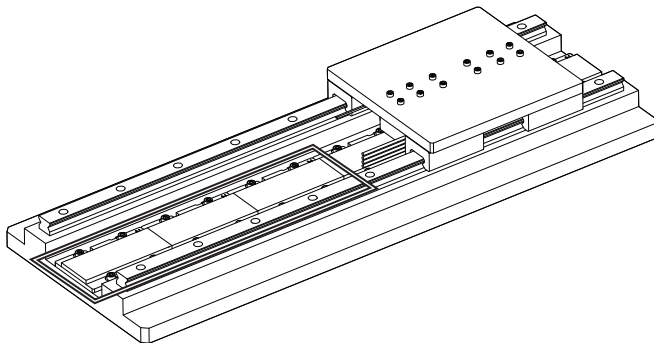
9. Move the table on which the primary side is installed onto the already installed secondary side.



**10.** Ensure that the primary and secondary sides do not come into contact.



**11.** Install the remaining secondary sides. Ensure again that the primary and secondary sides do not come into contact.



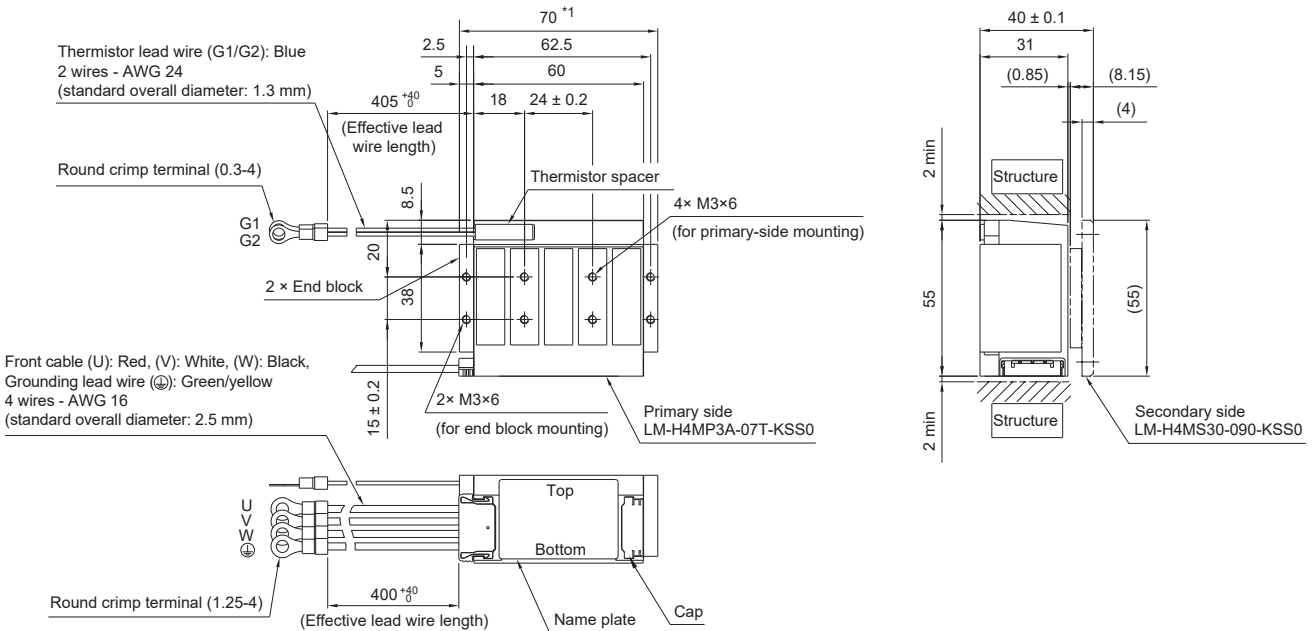
## 5.6 External dimensions

### External dimensions of the primary side (coil)

- The recommended tightening torque for mounting bolts on the primary side is 1.25 N•m (permissible range: 1.1 N•m to 1.4 N•m).
- Ensure a clearance of at least 2 mm on each side between the primary side surface and the structure.
- Take measures to prevent foreign objects from being caught between the primary and secondary sides.
- Ensure that the thread engagement length of the mounting bolts is 5 mm or more.
- The power lead wires, grounding lead wires, and thermistor lead wires are for fixed wiring. Securely fix them to the structure. The recommended minimum bending radius for the lead wire is six times or more (reference value) the standard overall diameter of the lead wire. Consider the speed of the linear servo motor and the flexing radius when selecting the cable to use for the moving part.

#### LM-H4MP3A-07T-KSS0

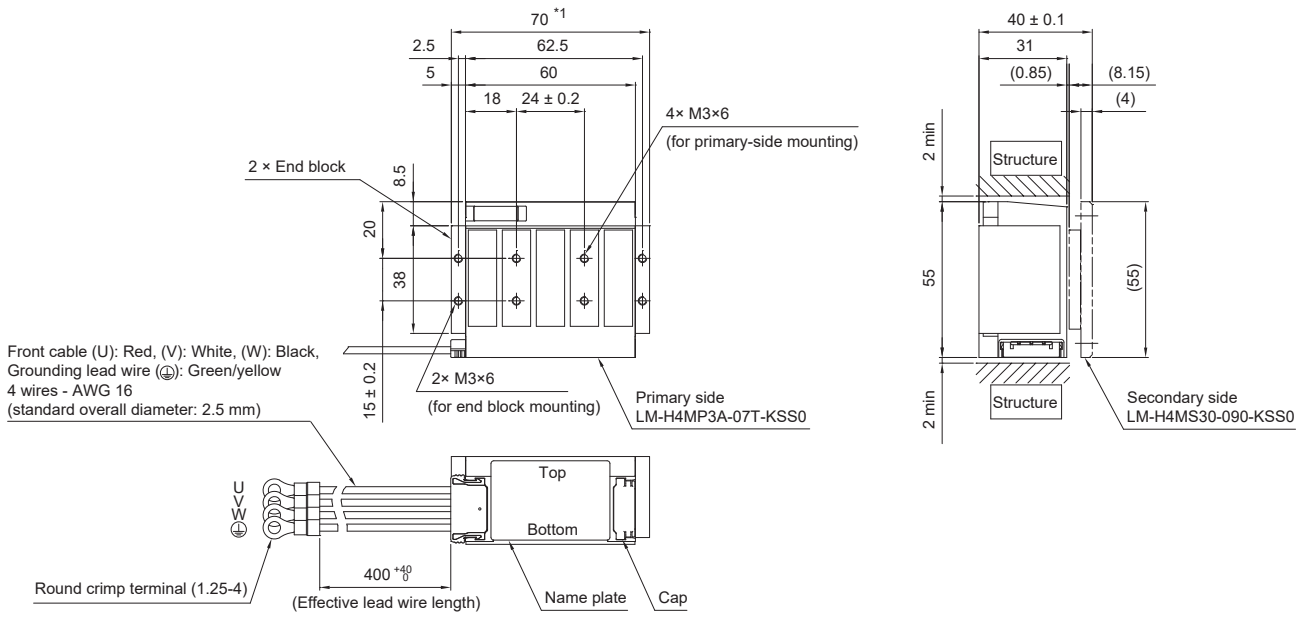
##### ■With thermistor



[Unit: mm]

\*1 The length includes the end blocks.

■ Without thermistor

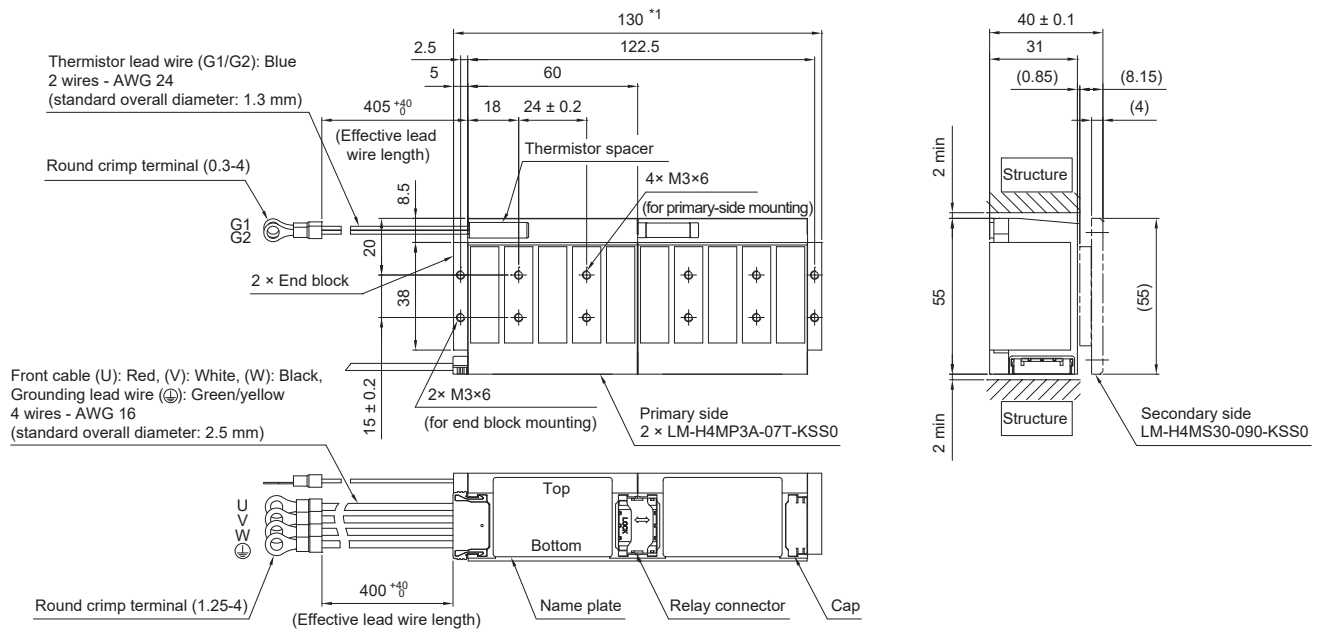


[Unit: mm]

\*1 The length includes the end blocks.

# LM-H4MP3B-14T-KSS0

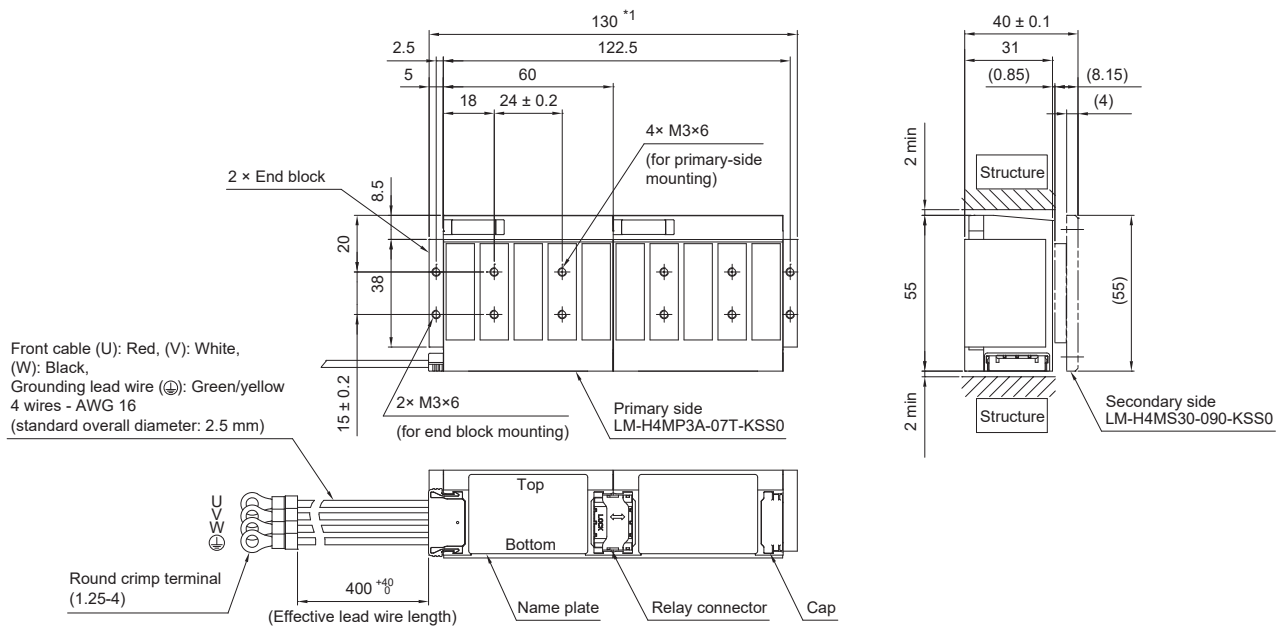
## ■With thermistor



[Unit: mm]

\*1 The length includes the end blocks.

## ■Without thermistor



[Unit: mm]

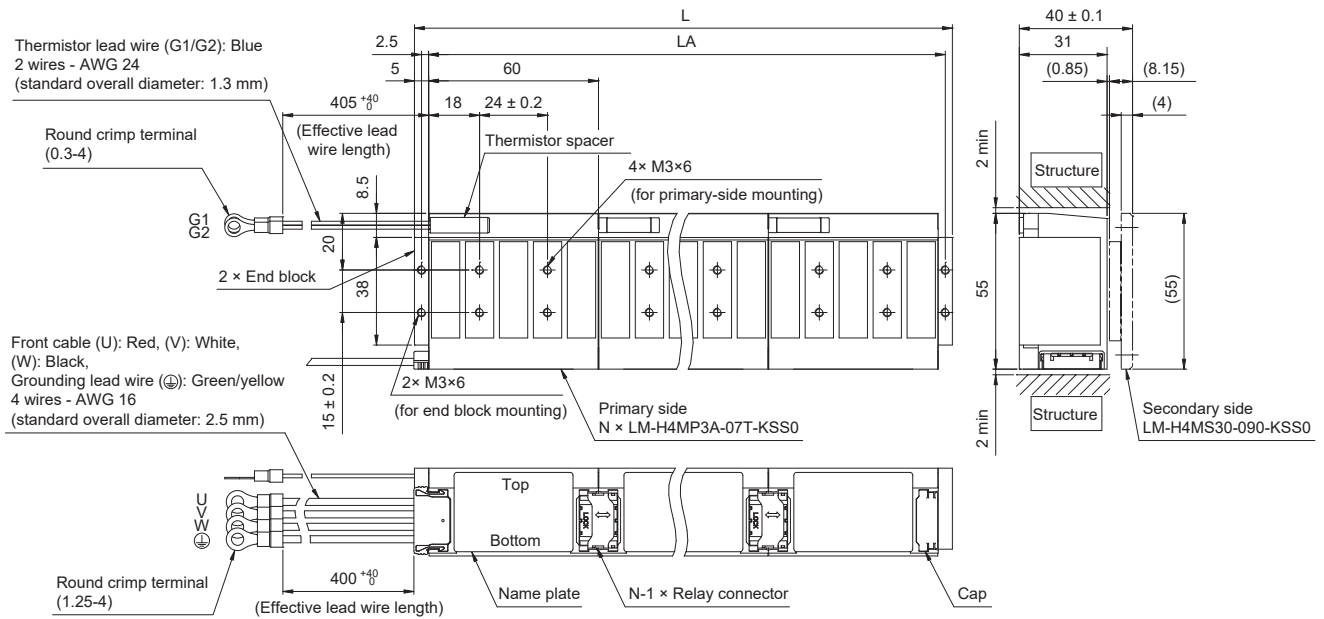
\*1 The length includes the end blocks.

**LM-H4MP3C-21T-KSS0/LM-H4MP3D-28T-KSS0/LM-H4MP3E-36T-KSS0/LM-H4MP3F-43T-KSS0/LM-H4MP3G-50T-KSS0/LM-H4MP3H-57T-KSS0**

**■With thermistor**

Model name	Variable dimensions		
	N	L	LA
LM-H4MP3C-21T-KSS0	3	190 *1	182.5
LM-H4MP3D-28T-KSS0	4	250 *1	242.5
LM-H4MP3E-36T-KSS0	5	310 *1	302.5
LM-H4MP3F-43T-KSS0	6	370 *1	362.5
LM-H4MP3G-50T-KSS0	7	430 *1	422.5
LM-H4MP3H-57T-KSS0	8	490 *1	482.5

\*1 The length includes the end blocks.

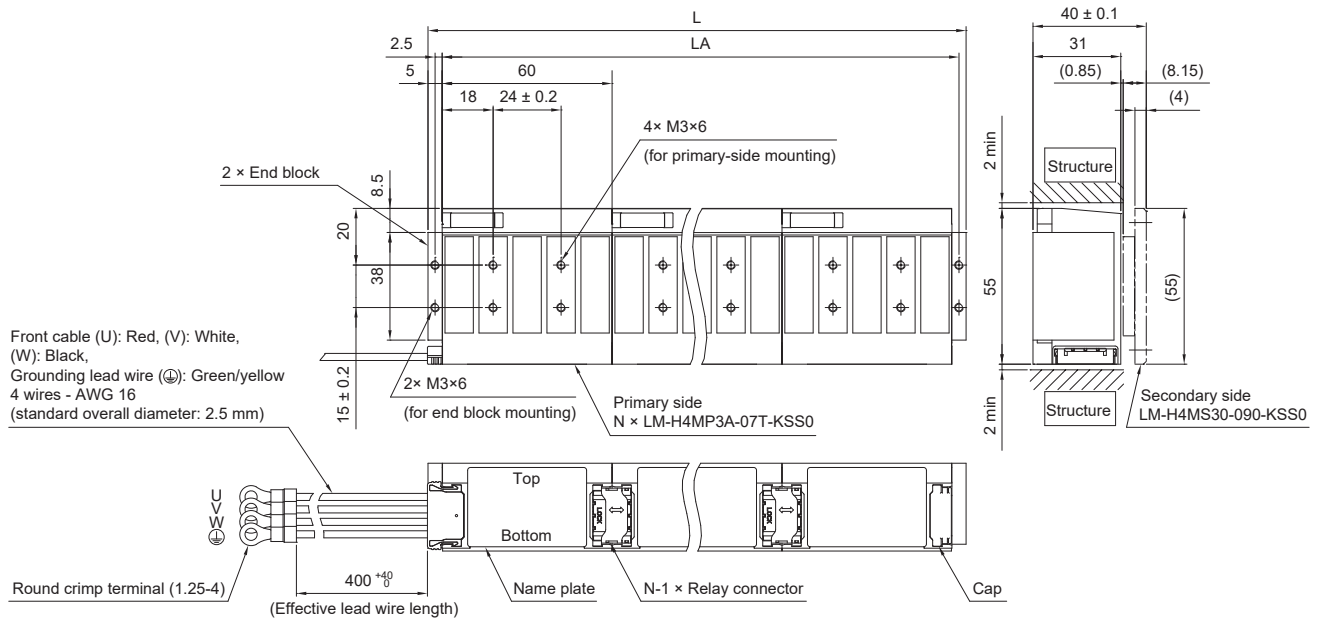


[Unit: mm]

## ■Without thermistor

Model name	Variable dimensions		
	N	L	LA
LM-H4MP3C-21T-KSS0	3	190 *1	182.5
LM-H4MP3D-28T-KSS0	4	250 *1	242.5
LM-H4MP3E-36T-KSS0	5	310 *1	302.5
LM-H4MP3F-43T-KSS0	6	370 *1	362.5
LM-H4MP3G-50T-KSS0	7	430 *1	422.5
LM-H4MP3H-57T-KSS0	8	490 *1	482.5

\*1 The length includes the end block.

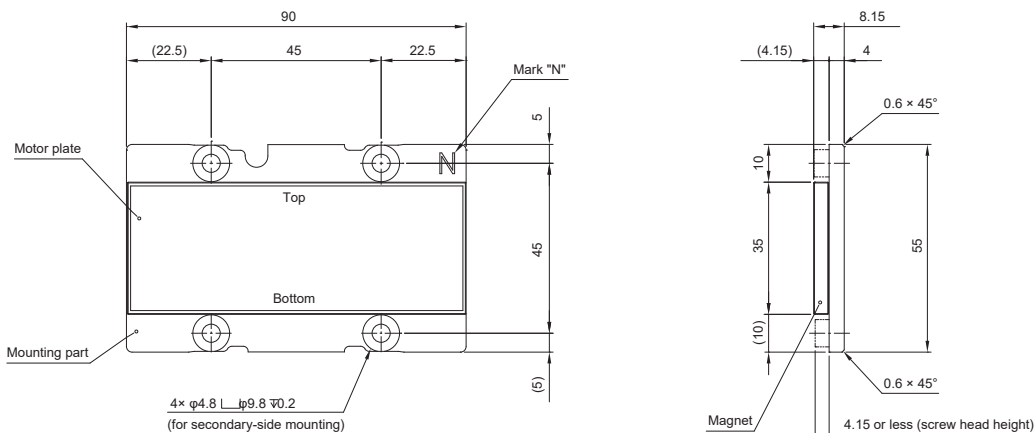


[Unit: mm]

## External dimensions of the secondary side (magnet)

- Electroless nickel plating has been applied to the mounting part.
- Take measures to prevent foreign objects from being caught between the primary and secondary sides.

### LM-H4MS30-090-KSS0



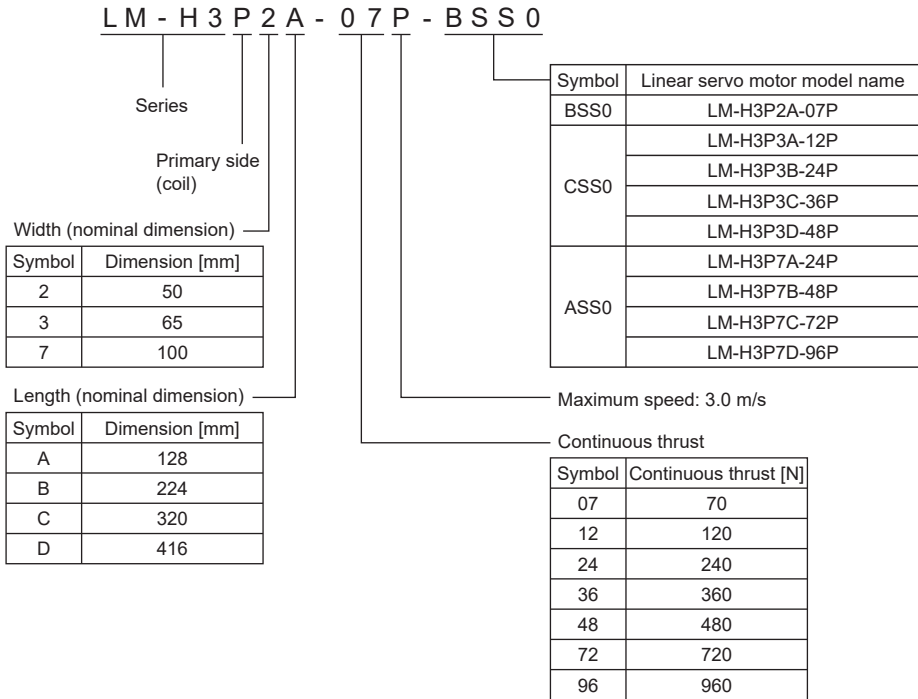
[Unit: mm]

# 6 LM-H3 SERIES

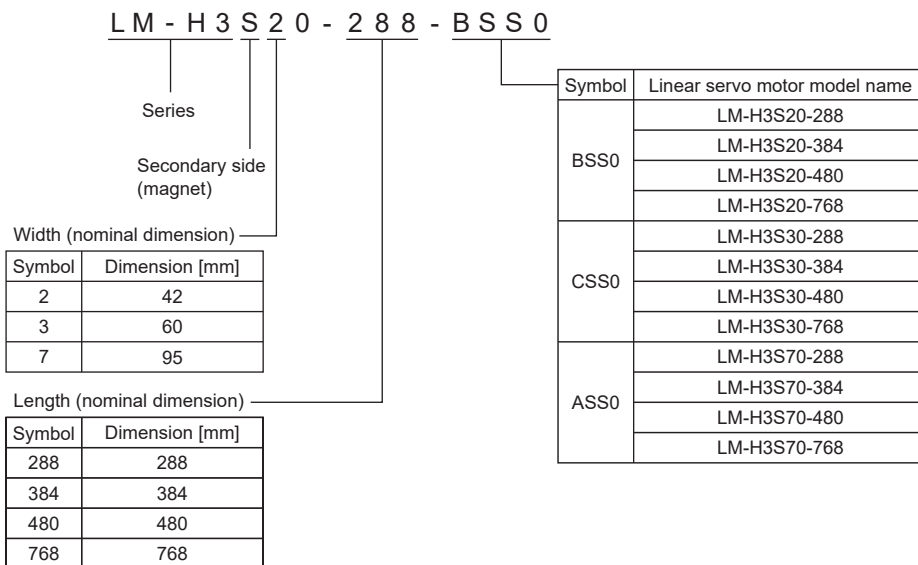
## 6.1 Model name designation

### Primary side (coil)

The following describes what each block of a model name indicates. Not all combinations of the symbols are available.



### Secondary side (magnet)



## 6.2 Standard specifications

### Standard specifications list

Linear servo motor (primary side) LM-H3_		P2A-07P-BSS0	P3A-12P-CSS0	P3B-24P-CSS0	P3C-36P-CSS0	P3D-48P-CSS0	P7A-24P-ASS0	P7B-48P-ASS0	P7C-72P-ASS0	P7D-96P-ASS0	
Linear servo motor (secondary side) LM-H3_		S20-288-BSS0 S20-384-BSS0 S20-480-BSS0 S20-768-BSS0	S30-288-CSS0 S30-384-CSS0 S30-480-CSS0 S30-768-CSS0				S70-288-ASS0 S70-384-ASS0 S70-480-ASS0 S70-768-ASS0				
Power supply capacity [kVA]		Refer to "Power supply capacity and generated loss" in the User's Manual (Hardware) for the servo amplifier being used.									
Cooling method		Natural cooling									
Thrust	Continuous <sup>*2 *4</sup> [N]	70	120	240	360	480	240	480	720	960	
	Maximum [N]	175	300	600	900	1200	600	1200	1800	2400	
Maximum speed <sup>*1</sup> [m/s]		3.0									
Magnetic attraction force [N]		630	1100	2200	3300	4400	2200	4400	6600	8800	
Rated current [A]		1.8	1.7	3.4	5.1	6.8	3.4	6.8	10.2	13.6	
Maximum current [A]		5.8	5.0	9.9	14.9	19.8	9.6	19.1	28.6	38.1	
Recommended load to motor mass ratio		35 times or less the mass of the linear servo motor primary side									
Thermistor		Built-in									
Insulation class		155 (F)									
Structure		Open (IP rating: IP00 <sup>*3</sup> )									
Vibration resistance [m/s <sup>2</sup> ]		49									
Mass	Primary side [kg]	0.9	1.3	2.3	3.3	4.3	2.2	3.9	5.6	7.3	
	Secondary side [kg]	0.7 (288 mm/pc) 0.9 (384 mm/pc) 1.1 (480 mm/pc) 1.8 (768 mm/pc)	1.0 (288 mm/pc) 1.4 (384 mm/pc) 1.7 (480 mm/pc) 2.7 (768 mm/pc)				2.8 (288 mm/pc) 3.7 (384 mm/pc) 4.7 (480 mm/pc) 7.4 (768 mm/pc)				

\*1 The actual maximum speed of the linear servo motor is the lower value between the maximum speed of the linear servo motor and the rated speed of the linear encoder.

\*2 The continuous thrust values in the table apply when an aluminum board (table) with the dimensions (L [mm] × W [mm] × H [mm]) shown below is mounted on the primary side. (The dimensions shown are for reference purposes only)

LM-H3P2A-07P-BSS0: 192 × 225 × 30

LM-H3P3A-12P-CSS0: 192 × 315 × 30

LM-H3P3B-24P-CSS0: 336 × 315 × 30

LM-H3P3C-36P-CSS0: 480 × 315 × 40

LM-H3P3D-48P-CSS0: 624 × 315 × 40

LM-H3P7A-24P-ASS0: 192 × 495 × 30

LM-H3P7B-48P-ASS0: 336 × 495 × 40

LM-H3P7C-72P-ASS0: 480 × 495 × 40

LM-H3P7D-96P-ASS0: 624 × 495 × 40

\*3 IP classifies the degree of protection provided against the intrusion of solid objects and water in electrical enclosures.

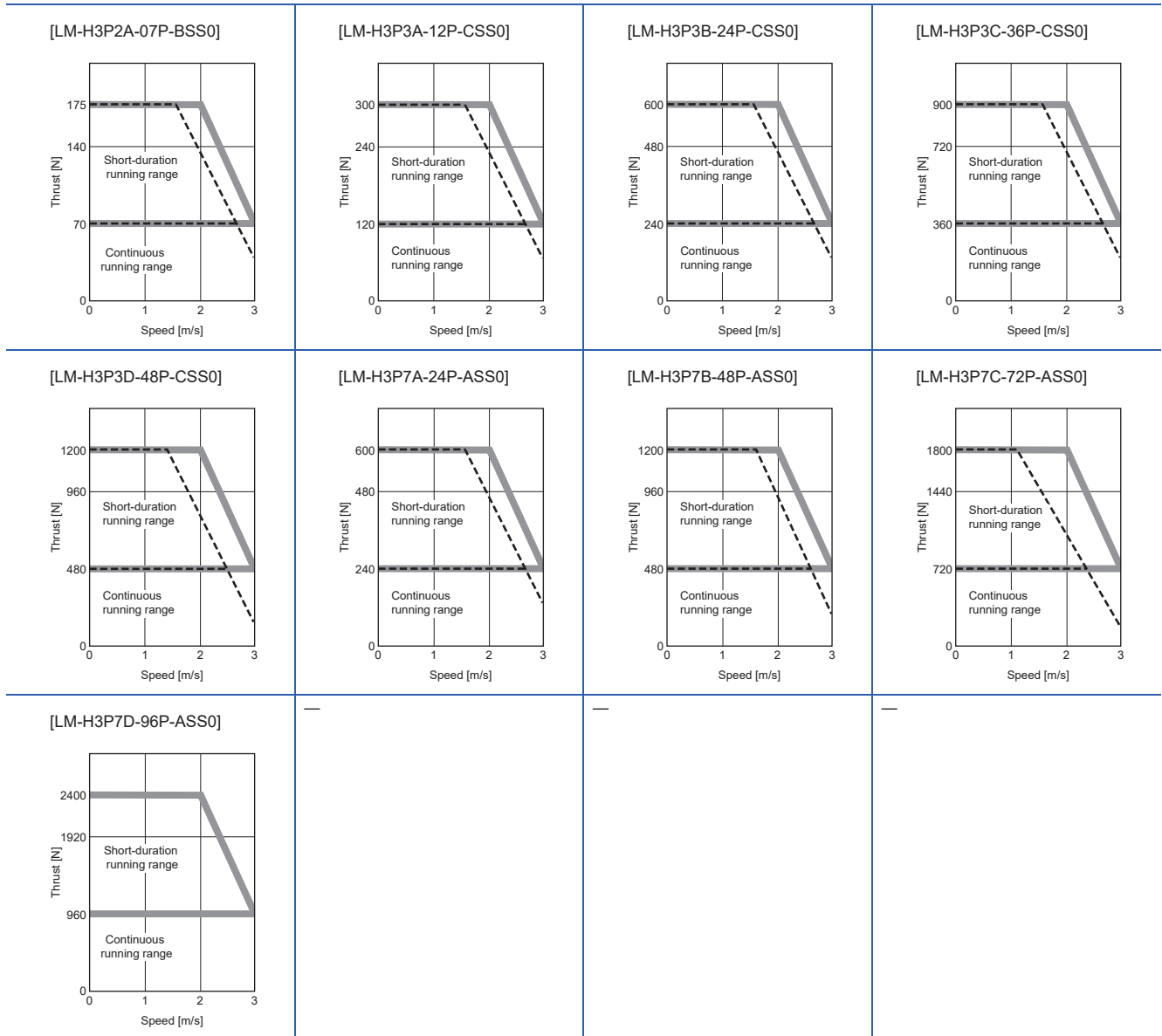
\*4 Use the linear servo motor with 70 % or less of the effective load ratio when it is servo-locked or if there is faint reciprocating motion.

# Thrust characteristics

The following shows the thrust characteristic when the power supply input of the servo amplifier is 3-phase 200 V AC or 1-phase 200 V AC.

The continuous/maximum thrust and maximum speed of the linear servo motor are specified based on the rated voltage and frequency applied by the combined servo amplifier.

- : 3-phase 200 V AC
- : 1-phase 200 V AC



## 6.3 Derating

The derating conditions are reference values. As the temperature rise value of the linear servo motor changes depending on operation conditions such as speed, confirm that [AL. 0E2 Servo motor overheat warning] and [AL. 046 Servo motor overheat] do not occur on the actual machine before use.

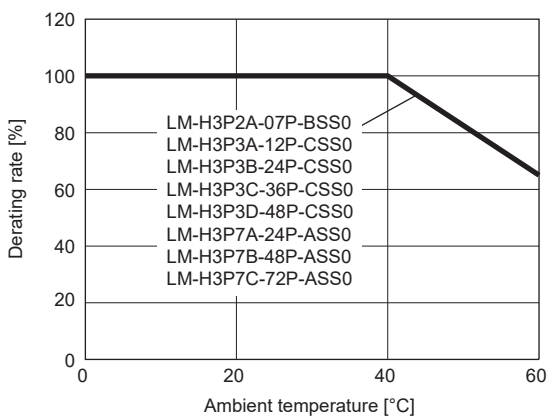
If a warning or alarm occurs, consider taking the following measures:

- Lower the effective load ratio of the linear servo motor.
- Review the heat dissipation conditions.

To use this product under conditions with multiple derating, calculate the multiplication of each derating rate, and use at the calculated derating rate or lower.

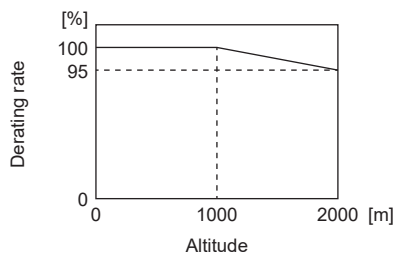
### Restrictions on the ambient temperature

When using this product in an environment with a high ambient temperature, derate the product in accordance with the following conditions:



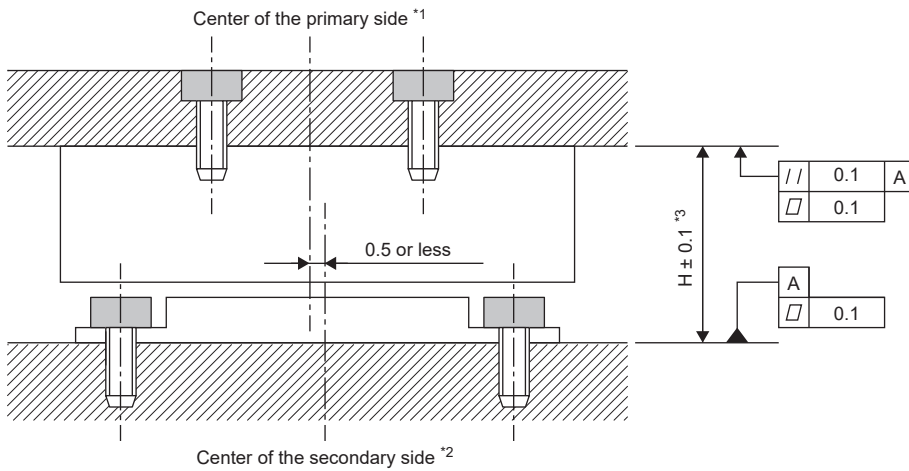
### Restrictions on the altitude

When using this product at an altitude between 1000 m and 2000 m, derate the product in accordance with the following conditions:



# 6.4 Installation

## Fitting method



[Unit: mm]

- \*1 The locations of the center of the primary side are shown below.  
 LM-H3P2\_ \_ : the position of the center mounting screw  
 LM-H3P3\_ \_ : the center of the mounting screw pitch  
 LM-H3P7\_ \_ : the position of the center mounting screw
- \*2 The center of the secondary side is located at the center of the mounting screw pitch.
- \*3 H length indicates (height of primary side) + (height of secondary side) + (length of empty clearance: 0.7 mm).  
 LM-H3P2\_ \_ : H = 43.0 mm  
 LM-H3P3\_ \_ : H = 43.0 mm  
 LM-H3P7\_ \_ : H = 48.0 mm

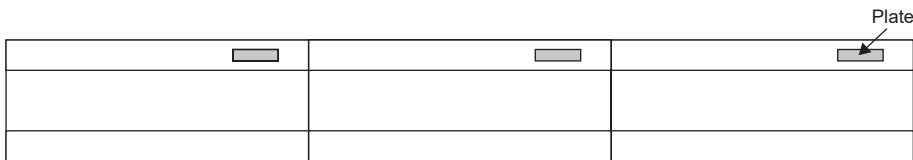
# Installation of the secondary side (magnet)

## Precautions

- The secondary side contains a strong magnet. Because an attraction force occurs between the surrounding magnetic materials or other secondary sides, be very careful not to get your hands or other body parts caught.
- If mounting an additional secondary side with a secondary side already set, first set the additional side so that it is distanced from the already mounted one, then slide the additional side to mount it in its specified position as shown in this section.
- Keep the cumulative pitch error of the mounting screw holes to within  $\pm 0.2$  mm. When two or more secondary sides are installed, clearance may be left between the secondary sides depending on the installing method and the number of secondary sides.

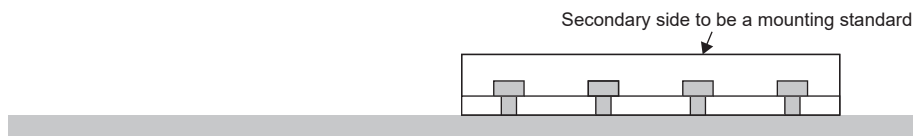
## Procedure

When using multiple secondary sides, arrange them so that the name plate attached to each side all share the same orientation to keep the layout of magnetic poles.



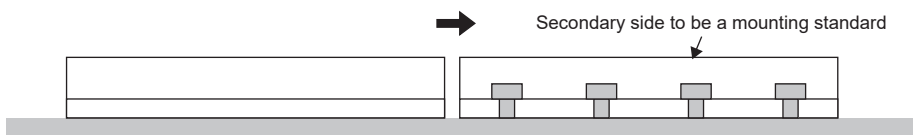
In addition, use the following procedure when mounting the secondary sides to decrease the clearance between them.

1. Use bolts to securely fix the secondary side that will be used as the mounting standard into place.

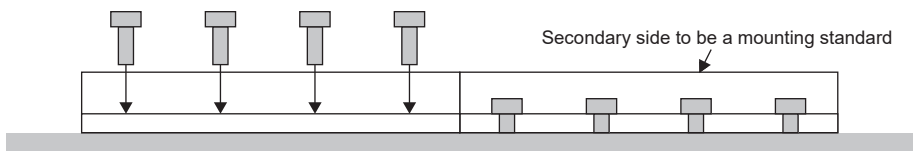


YouTube video

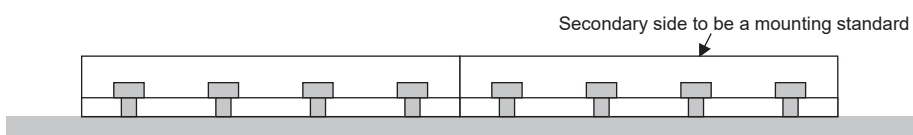
2. Set the next secondary side on the mounting face and press it toward the secondary side to be a mounting standard.



3. Use bolts to temporarily fix the added secondary side and position it.



4. Use bolts to securely fix the added secondary side into place.



# Installation of the primary side (coil)

## Precautions

- We recommend mounting the primary side in a position where no secondary side is present. If the primary side must be mounted over the secondary side, use material handling equipment such as cranes that can fully withstand the load of the attraction force, etc.
- When sliding the primary side over the secondary side after installing, take precautions against the attraction force that is generated.

## Procedure

1. Mount a portion of the secondary sides.

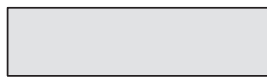


YouTube video

2. Mount the primary side in a position where no secondary side is present.



3. Move the primary side over the mounted secondary side. Confirm that the primary and secondary sides are not touching each other.



4. Mount the rest of the secondary sides. Confirm that the primary and secondary sides are not touching each other.

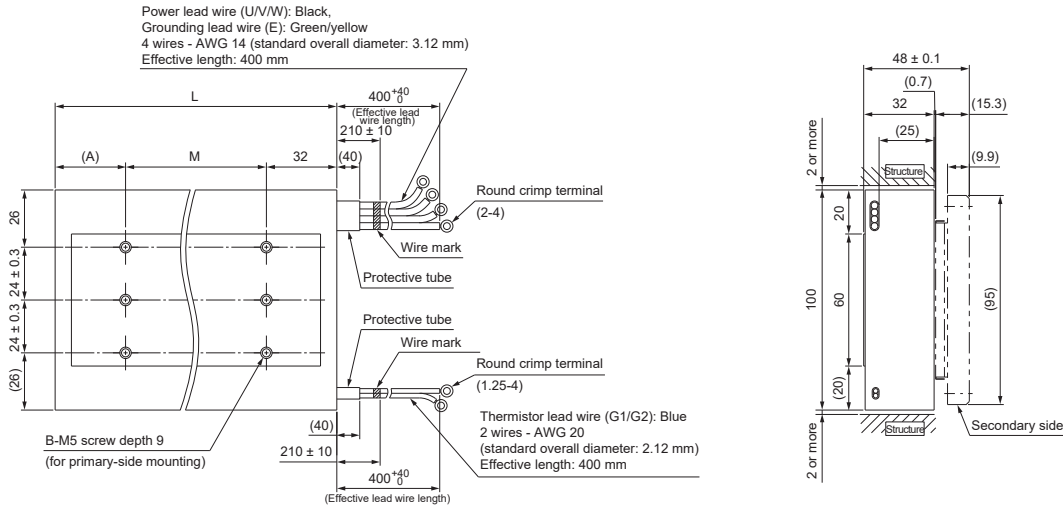




## LM-H3P7A-24P-ASS0/LM-H3P7B-48P-ASS0/LM-H3P7C-72P-ASS0/LM-H3P7D-96P-ASS0

Model name	Variable dimensions			
	L	M	A	B
LM-H3P7A-24P-ASS0	128	64 *1	32	6
LM-H3P7B-48P-ASS0	224	2 × 64 (= 128) *1	64	9
LM-H3P7C-72P-ASS0	320	4 × 64 (= 256) *1	32	15
LM-H3P7D-96P-ASS0	416	5 × 64 (= 320) *1	64	18

\*1 The pitch tolerance of the holes at both ends is  $\pm 0.3$ .



[Unit: mm]

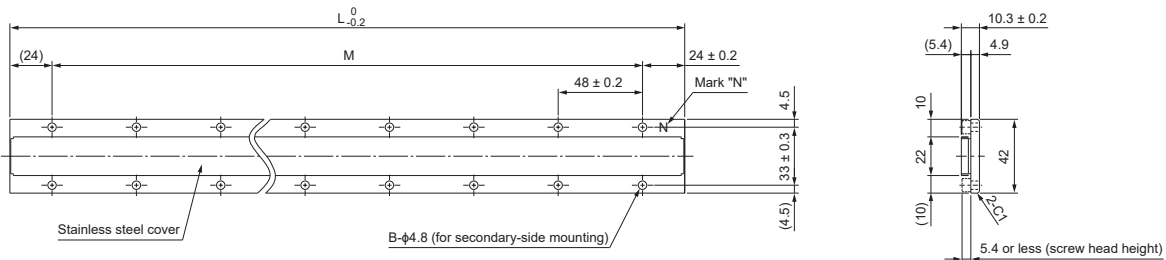
## Secondary-side (magnet) dimensions

When mounting the secondary side, use hexagon socket head cap screws with a screw head height of 5.4 mm or less.

## LM-H3S20-288-BSS0/LM-H3S20-384-BSS0/LM-H3S20-480-BSS0/LM-H3S20-768-BSS0

Model name	Variable dimensions		
	L	M	B
LM-H3S20-288-BSS0	288	5 × 48 (= 240) *1	12
LM-H3S20-384-BSS0	384	7 × 48 (= 336) *1	16
LM-H3S20-480-BSS0	480	9 × 48 (= 432) *1	20
LM-H3S20-768-BSS0	768	15 × 48 (= 720) *1	32

\*1 The pitch tolerance of the holes at both ends is  $\pm 0.2$ .

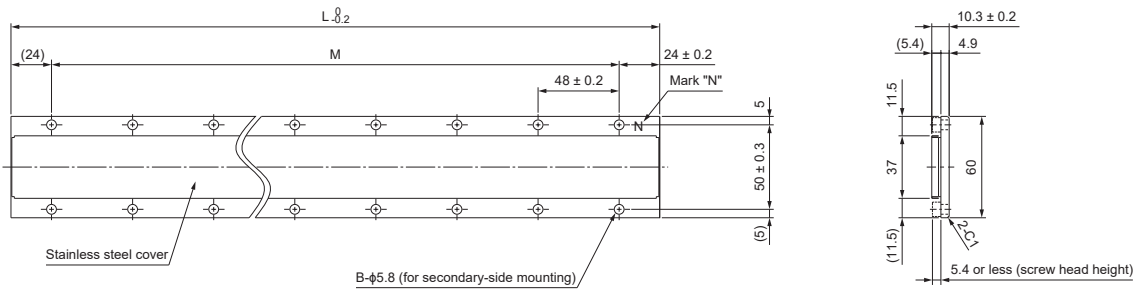


[Unit: mm]

## LM-H3S30-288-CSS0/LM-H3S30-384-CSS0/LM-H3S30-480-CSS0/LM-H3S30-768-CSS0

Model name	Variable dimensions		
	L	M	B
LM-H3S30-288-CSS0	288	5 × 48 (= 240) *1	12
LM-H3S30-384-CSS0	384	7 × 48 (= 336) *1	16
LM-H3S30-480-CSS0	480	9 × 48 (= 432) *1	20
LM-H3S30-768-CSS0	768	15 × 48 (= 720) *1	32

\*1 The pitch tolerance of the holes at both ends is  $\pm 0.2$ .

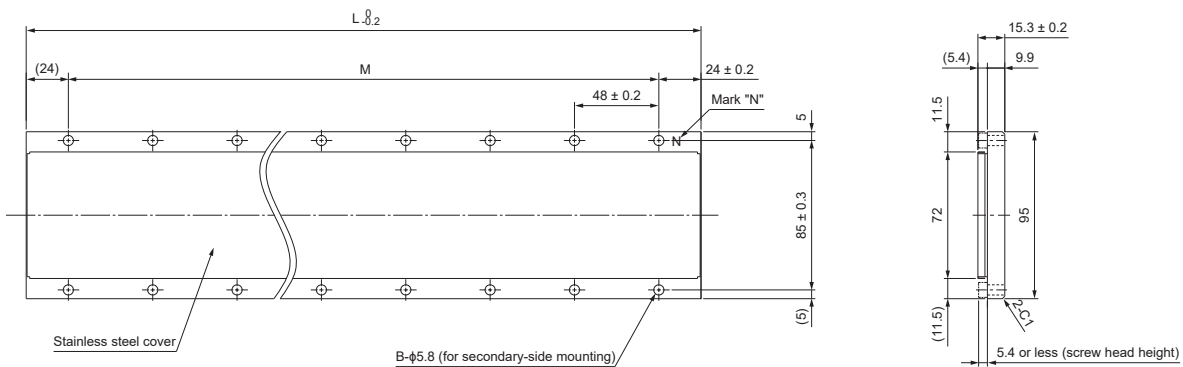


[Unit: mm]

## LM-H3S70-288-ASS0/LM-H3S70-384-ASS0/LM-H3S70-480-ASS0/LM-H3S70-768-ASS0

Model name	Variable dimensions		
	L	M	B
LM-H3S70-288-ASS0	288	5 × 48 (= 240) *1	12
LM-H3S70-384-ASS0	384	7 × 48 (= 336) *1	16
LM-H3S70-480-ASS0	480	9 × 48 (= 432) *1	20
LM-H3S70-768-ASS0	768	15 × 48 (= 720) *1	32

\*1 The pitch tolerance of the holes at both ends is  $\pm 0.2$ .



[Unit: mm]

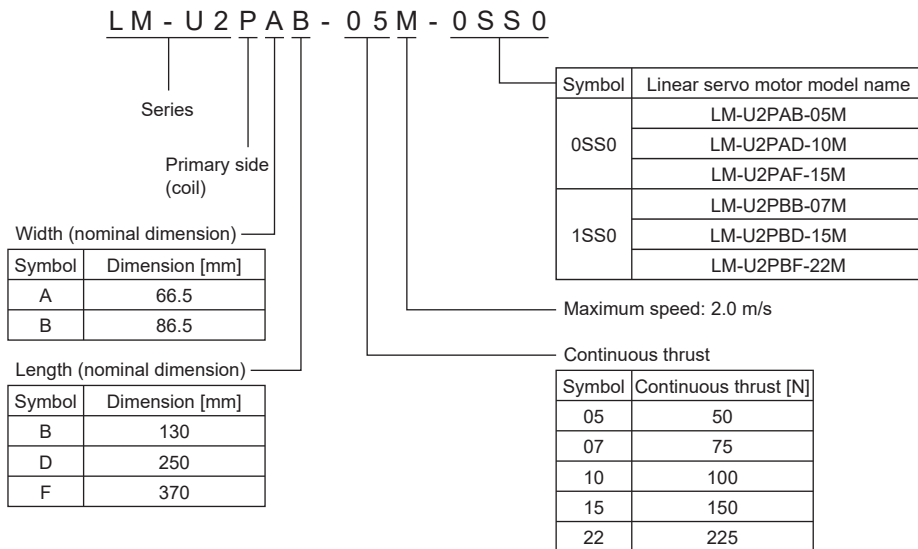
# 7 LM-U2 SERIES

## 7.1 Model name designation

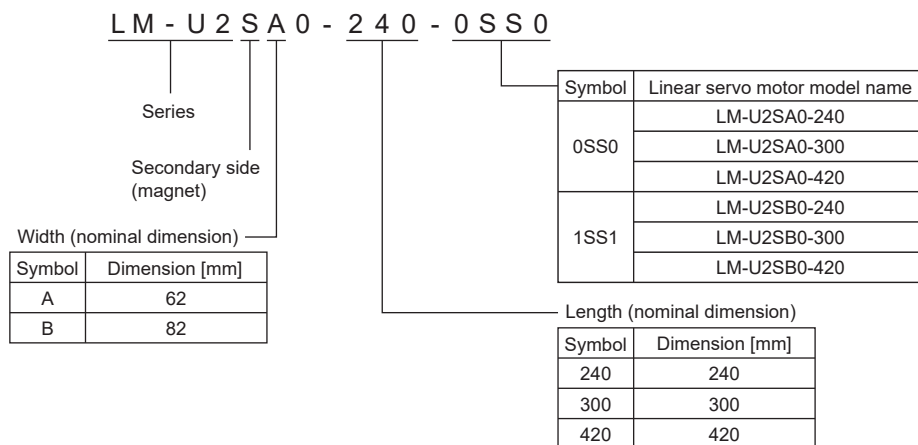
### Medium thrust series

The following describes what each block of a model name indicates. Not all combinations of the symbols are available.

#### Primary side (coil)



#### Secondary side (magnet)



# Large thrust series

## Primary side (coil)

LM - U 2 P 2 B - 4 0 M - 2 S S 0

Series

Primary side  
(coil)

Maximum speed: 2.0 m/s

Continuous thrust

Symbol	Continuous thrust [N]
40	400
60	600
80	800

Length (nominal dimension)

Symbol	Dimension [mm]
B	286
C	406
D	526

## Secondary side (magnet)

LM - U 2 S 2 0 - 3 0 0 - 2 S S 1

Series

Secondary side (magnet)

Length (nominal dimension)

Symbol	Dimension [mm]
300	300
480	480

## 7.2 Standard specifications

### Standard specifications list

Linear servo motor (primary side) LM-U2_		PAB-05M-0SS0	PAD-10M-0SS0	PAF-15M-0SS0	PBB-07M-1SS0	PBD-15M-1SS0	PBF-22M-1SS0
Linear servo motor (secondary side) LM-U2_		SA0-240-0SS0 SA0-300-0SS0 SA0-420-0SS0			SB0-240-1SS1 SB0-300-1SS1 SB0-420-1SS1		
Power supply capacity [kVA]		Refer to "Power supply capacity and generated loss" in the User's Manual (Hardware) for the servo amplifier being used.					
Cooling method		Natural cooling					
Thrust	Continuous <sup>*2 *4</sup> [N]	50	100	150	75	150	225
	Maximum [N]	150	300	450	225	450	675
Maximum speed <sup>*1</sup> [m/s]		2.0					
Magnetic attraction force [N]		0					
Rated current [A]		0.9	1.9	2.7	1.5	3.0	4.6
Maximum current [A]		2.7	5.5	8.3	4.5	8.9	13.7
Recommended load to motor mass ratio		30 times or less the mass of the linear servo motor primary side					
Thermistor		Built-in					
Insulation class		155 (F)					
Structure		Open (IP rating: IP00 <sup>*3</sup> )					
Vibration resistance [m/s <sup>2</sup> ]		49					
Mass	Primary side [kg]	0.3	0.6	0.8	0.4	0.8	1.1
	Secondary side [kg]	2.0 (240 mm/pc) 2.5 (300 mm/pc) 3.5 (420 mm/pc)			2.6 (240 mm/pc) 3.2 (300 mm/pc) 4.5 (420 mm/pc)		
Linear servo motor (primary side) LM-U2_		P2B-40M-2SS0		P2C-60M-2SS0		P2D-80M-2SS0	
Linear servo motor (secondary side) LM-U2_		S20-300-2SS1 S20-480-2SS1					
Power supply capacity [kVA]		Refer to "Power supply capacity and generated loss" in the User's Manual (Hardware) for the servo amplifier being used.					
Cooling method		Natural cooling					
Thrust	Continuous <sup>*2 *4</sup> [N]	400		600		800	
	Maximum [N]	1600		2400		3200	
Maximum speed <sup>*1</sup> [m/s]		2.0					
Magnetic attraction force [N]		0					
Rated current [A]		6.6		9.8		13.1	
Maximum current [A]		26.7		40.3		53.7	
Recommended load to motor mass ratio		30 times or less the mass of the linear servo motor primary side					
Thermistor		Built-in					
Insulation class		155 (F)					
Structure		Open (IP rating: IP00 <sup>*3</sup> )					
Vibration resistance [m/s <sup>2</sup> ]		49					
Mass	Primary side [kg]	2.9		4.2		5.5	
	Secondary side [kg]	9.6 (300 mm/pc) 15.3 (480 mm/pc)					

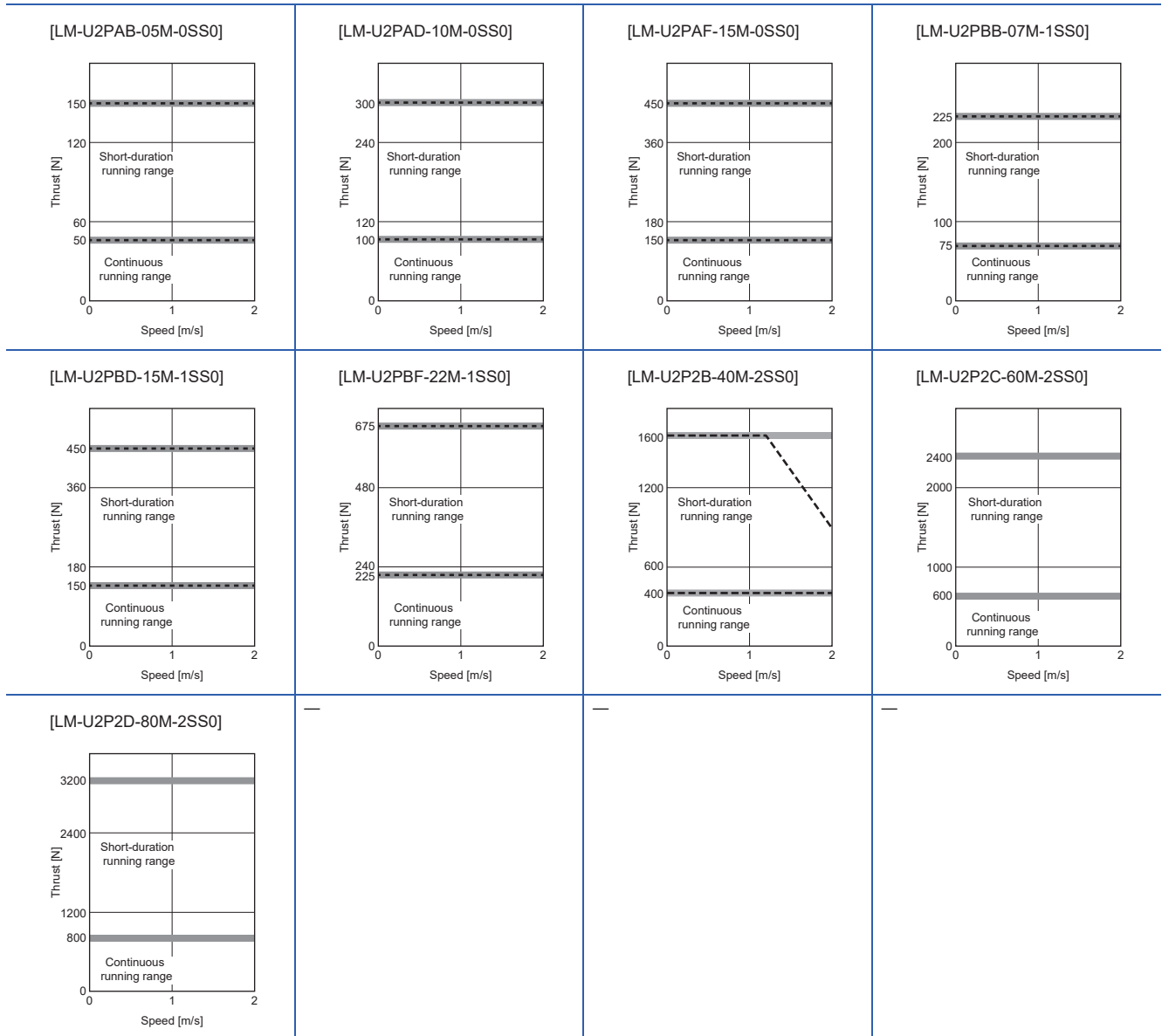
- \*1 The actual maximum speed of the linear servo motor is the lower value between the maximum speed of the linear servo motor and the rated speed of the linear encoder.
- \*2 The continuous thrust values in the table apply when an aluminum board (table) with the dimensions (L [mm] × W [mm] × H [mm]) shown below is mounted on the primary side. (The dimensions shown are for reference purposes only)
  - LM-U2PAB-05M-0SS0: 300 × 400 × 15
  - LM-U2PAD-10M-0SS0: 400 × 500 × 15
  - LM-U2PAF-15M-0SS0: 500 × 600 × 15
  - LM-U2PBB-07M-1SS0: 300 × 400 × 15
  - LM-U2PBD-15M-1SS0: 400 × 500 × 15
  - LM-U2PBF-22M-1SS0: 500 × 600 × 15
  - LM-U2P2B-40M-2SS0: 900 × 800 × 12
  - LM-U2P2C-60M-2SS0: 900 × 800 × 12
  - LM-U2P2D-80M-2SS0: 990 × 800 × 12
- \*3 IP classifies the degree of protection provided against the intrusion of solid objects and water in electrical enclosures.
- \*4 Use the linear servo motor with 70 % or less of the effective load ratio when it is servo-locked or if there is faint reciprocating motion.

# Thrust characteristics

The following shows the thrust characteristic when the power supply input of the servo amplifier is 3-phase 200 V AC or 1-phase 200 V AC.

The continuous/maximum thrust and maximum speed of the linear servo motor are specified based on the rated voltage and frequency applied by the combined servo amplifier.

- : 3-phase 200 V AC
- : 1-phase 200 V AC



## 7.3 Derating

The derating conditions are reference values. As the temperature rise value of the linear servo motor changes depending on operation conditions such as speed, confirm that [AL. 0E2 Servo motor overheat warning] and [AL. 046 Servo motor overheat] do not occur on the actual machine before use.

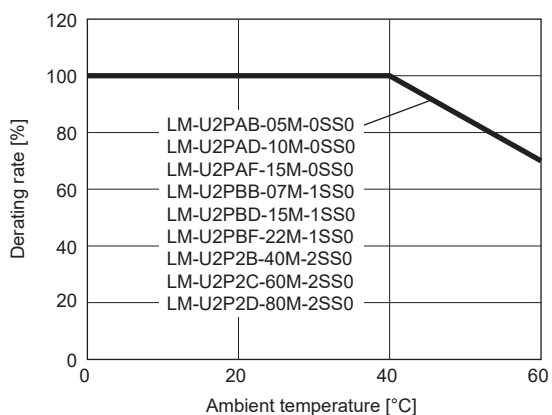
If a warning or alarm occurs, consider taking the following measures:

- Lower the effective load ratio of the linear servo motor.
- Review the heat dissipation conditions.

To use this product under conditions with multiple derating, calculate the multiplication of each derating rate, and use at the calculated derating rate or lower.

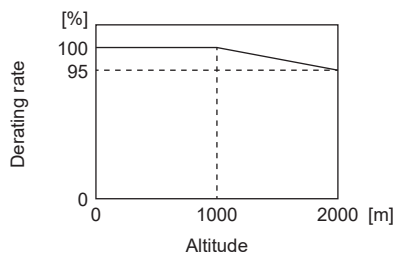
### Restrictions on the ambient temperature

When using this product in an environment with a high ambient temperature, derate the product in accordance with the following conditions:



### Restrictions on the altitude

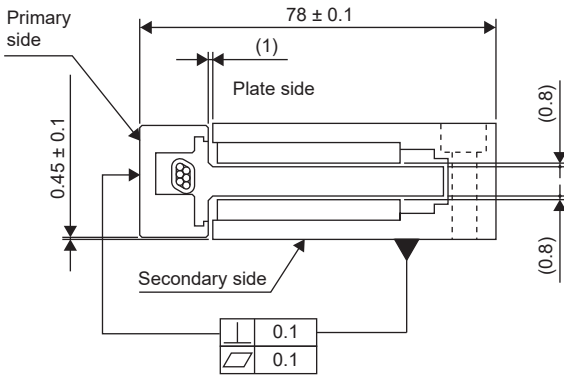
When using this product at an altitude between 1000 m and 2000 m, derate the product in accordance with the following conditions:



# 7.4 Installation

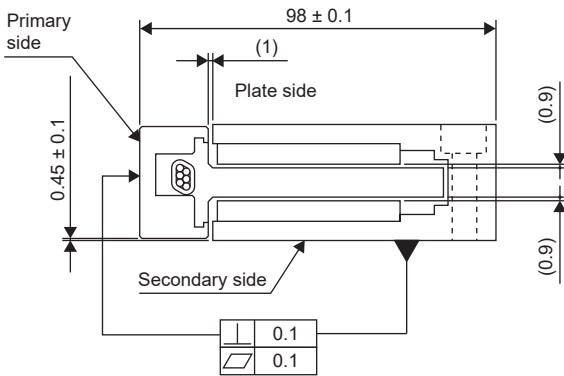
## Mounting dimensions

### LM-U2PAB-05M-0SS0/LM-U2PAD-10M-0SS0/LM-U2PAF-15M-0SS0



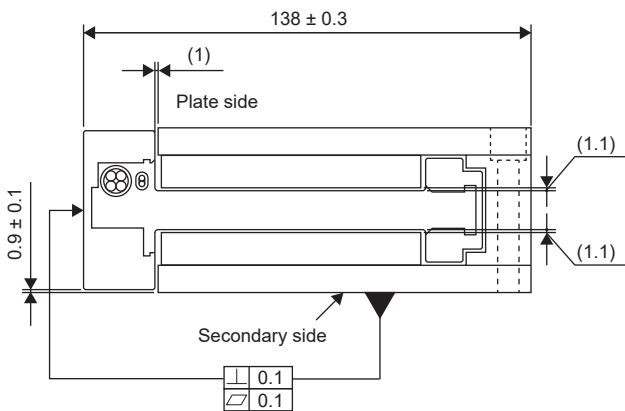
[Unit: mm]

### LM-U2PBB-07M-1SS0/LM-U2PBD-15M-1SS0/LM-U2PBF-22M-1SS0



[Unit: mm]

### LM-U2P2B-40M-2SS0/LM-U2P2C-60M-2SS0/LM-U2P2D-80M-2SS0



[Unit: mm]

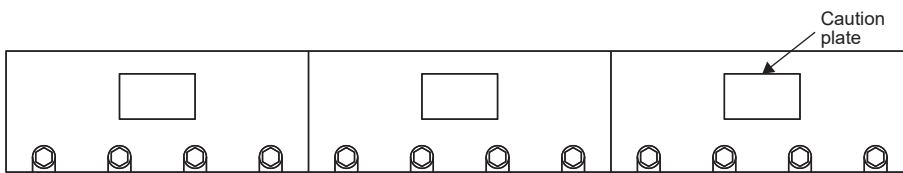
# Installation of the secondary side (magnet)

## Precautions

- The secondary side contains a strong magnet. Because an attraction force occurs between the surrounding magnetic materials or other secondary sides, be very careful not to get your hands or other body parts caught.
- If mounting an additional secondary side with a secondary side already set, first set the additional side so that it is distanced from the already mounted one, then slide the additional side to mount it in its specified position as shown in this section.
- Keep the cumulative pitch error of the mounting screw holes to within  $\pm 0.2$  mm. When two or more secondary sides are installed, clearance may be left between the secondary sides depending on the installing method and the number of secondary sides.

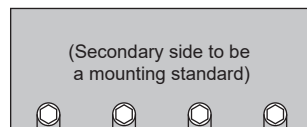
## Procedure

When using multiple secondary sides, arrange them so that the caution plate attached to each side all share the same orientation to keep the layout of magnetic poles.

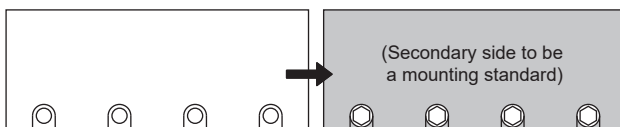


In addition, use the following procedure when mounting the secondary sides to decrease the clearance between them.

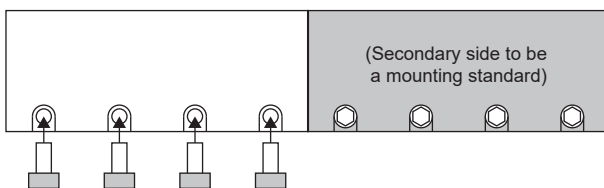
1. Use bolts to fix the secondary side that will be used as the mounting standard into place.



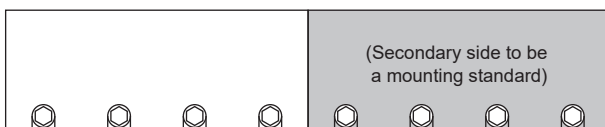
2. Set the next secondary side on the mounting face and press it toward the secondary side to be a mounting standard.



3. Use bolts to temporarily fix the added secondary side and position it.

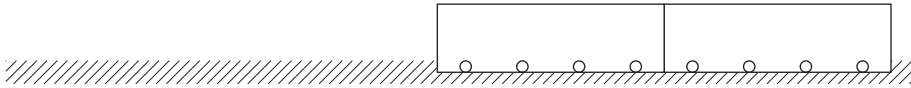


4. Use bolts to securely fix the added secondary side into place.

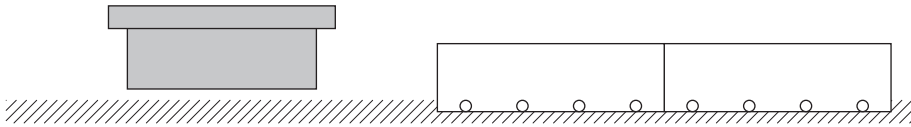


## Installation of the primary side (coil)

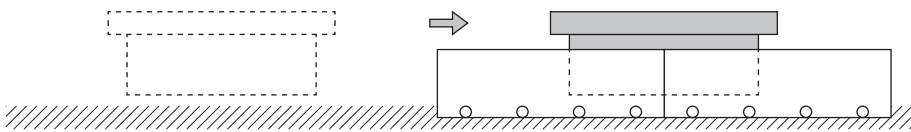
1. Mount a portion of the secondary sides.



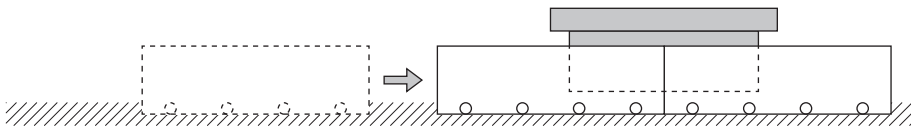
2. Mount the primary side in a position where no secondary side is present.



3. Move the primary side over the mounted secondary side. Confirm that the primary and secondary sides are not touching each other.



4. Mount the rest of the secondary sides. Confirm that the primary and secondary sides are not touching each other.



# 7.5 Dimensions

## Primary-side (coil) dimensions

When mounting the primary side, use hexagon socket head cap screws (material should be SUS304 with a lower yield point of 206 N/mm<sup>2</sup> or equivalent and a thread engagement length of 4 mm or more).

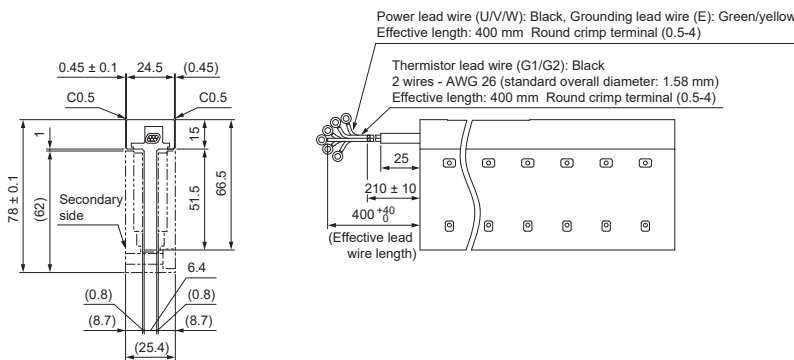
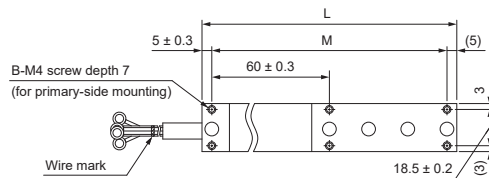
The power lead wires, grounding lead wires, and thermistor lead wires are for fixed wiring. Securely fix them to the structure. The recommended minimum bending radius for the lead wire is six times or more (reference value) the standard overall diameter of the lead wire. Consider the speed of the linear servo motor and the flexing radius when selecting the cable to use for the moving part.

When mounting the primary side on the secondary side, make adjustments so that the gap can be secured.

### LM-U2PAB-05M-0SS0/LM-U2PAD-10M-0SS0/LM-U2PAF-15M-0SS0

Model name	Variable dimensions			Power/grounding lead wires	
	L	M	B	Size	Standard overall diameter
LM-U2PAB-05M-0SS0	130	2 × 60 (= 120) *1	6	AWG 26	1.58
LM-U2PAD-10M-0SS0	250	4 × 60 (= 240) *1	10		
LM-U2PAF-15M-0SS0	370	6 × 60 (= 360) *1	14		

\*1 The pitch tolerance of the holes at both ends is ±0.3.

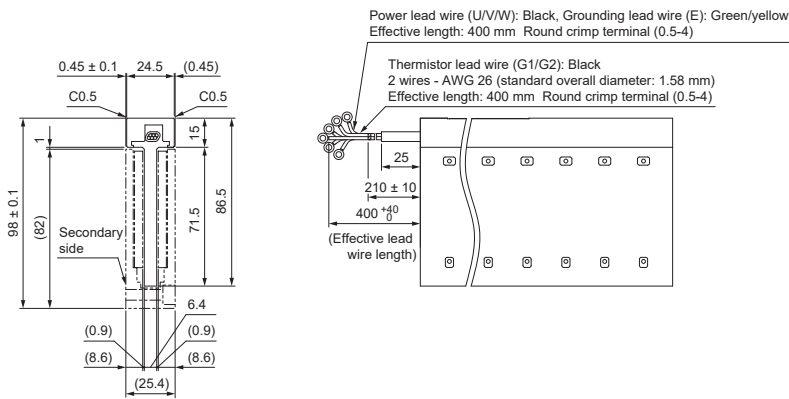
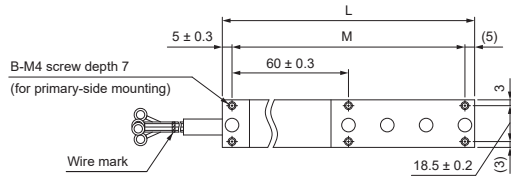


[Unit: mm]

# LM-U2PBB-07M-1SS0/LM-U2PBD-15M-1SS0/LM-U2PBF-22M-1SS0

Model name	Variable dimensions			Power/grounding lead wires	
	L	M	B	Size	Standard overall diameter
LM-U2PBB-07M-1SS0	130	$2 \times 60 (= 120)^{*1}$	6	AWG 26	1.58
LM-U2PBD-15M-1SS0	250	$4 \times 60 (= 240)^{*1}$	10		
LM-U2PBF-22M-1SS0	370	$6 \times 60 (= 360)^{*1}$	14		

\*1 The pitch tolerance of the holes at both ends is  $\pm 0.3$ .

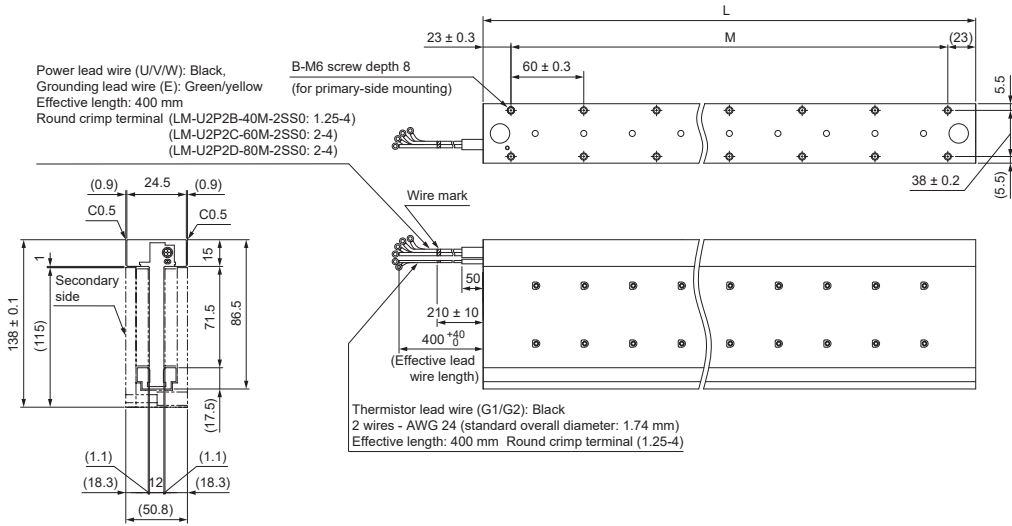


[Unit: mm]

# LM-U2P2B-40M-2SS0/LM-U2P2C-60M-2SS0/LM-U2P2D-80M-2SS0

Model name	Variable dimensions			Power/grounding lead wires	
	L	M	B	Size	Standard overall diameter
LM-U2P2B-40M-2SS0	286	4 × 60 (= 240) *1	10	AWG 16	2.7
LM-U2P2C-60M-2SS0	406	6 × 60 (= 360) *1	14	AWG 14	3.12
LM-U2P2D-80M-2SS0	526	8 × 60 (= 480) *1	18	AWG 14	3.12

\*1 The pitch tolerance of the holes at both ends is ±0.3.



[Unit: mm]

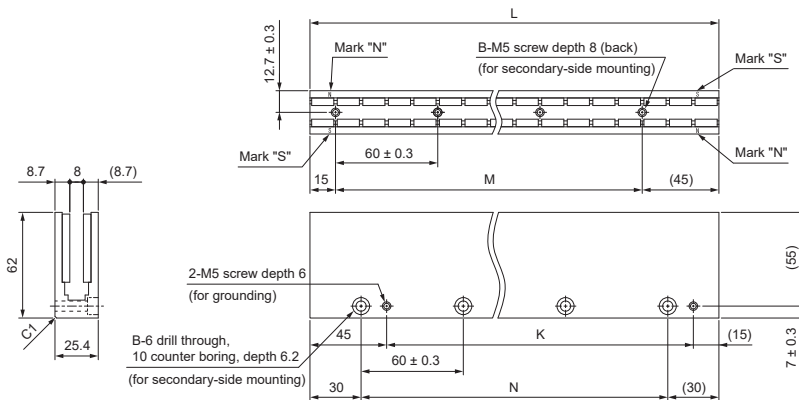
# Secondary-side (magnet) dimensions

When mounting the secondary side, use hexagon socket head cap screws (material should be SUS304 with a lower yield point of 206 N/mm<sup>2</sup> or equivalent).

## LM-U2SA0-240-0SS0/LM-U2SA0-300-0SS0/LM-U2SA0-420-0SS0

Model name	Variable dimensions				
	L	M	B	K	N
LM-U2SA0-240-0SS0	240	3 × 60 (= 180) *1	4	180	3 × 60 (= 180) *1
LM-U2SA0-300-0SS0	300	4 × 60 (= 240) *1	5	4 × 60 (= 240) *1	
LM-U2SA0-420-0SS0	420	6 × 60 (= 360) *1	7	360	6 × 60 (= 360) *1

\*1 The pitch tolerance of the holes at both ends is ±0.3.

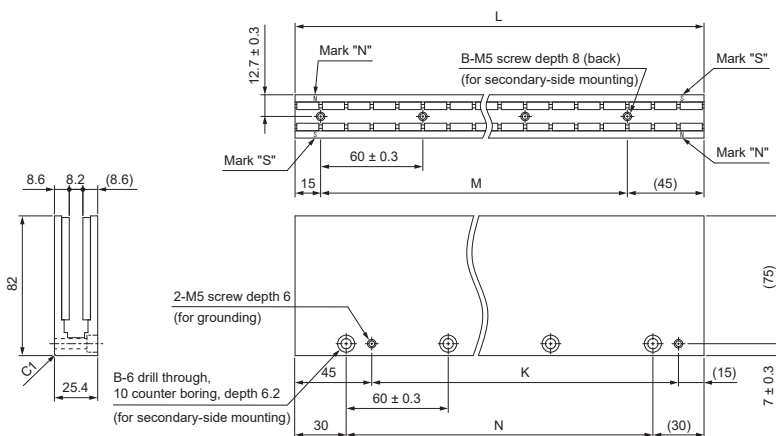


[Unit: mm]

## LM-U2SB0-240-1SS1/LM-U2SB0-300-1SS1/LM-U2SB0-420-1SS1

Model name	Variable dimensions				
	L	M	B	K	N
LM-U2SB0-240-1SS1	240	3 × 60 (= 180) *1	4	180	3 × 60 (= 180) *1
LM-U2SB0-300-1SS1	300	4 × 60 (= 240) *1	5	240	4 × 60 (= 240) *1
LM-U2SB0-420-1SS1	420	6 × 60 (= 360) *1	7	360	6 × 60 (= 360) *1

\*1 The pitch tolerance of the holes at both ends is ±0.3.

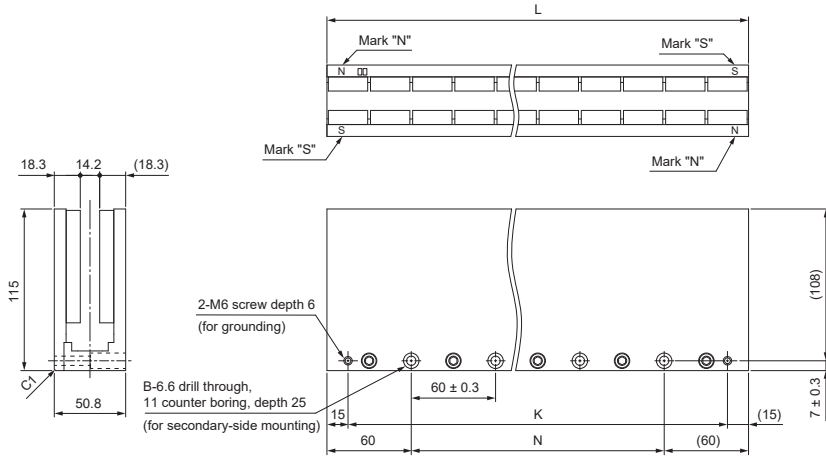


[Unit: mm]

# LM-U2S20-300-2SS1/LM-U2S20-480-2SS1

Model name	Variable dimensions			
	L	N	B	K
LM-U2S20-300-2SS1	300	$3 \times 60 (= 180)$ *1	4	270
LM-U2S20-480-2SS1	480	$6 \times 60 (= 360)$ *1	7	450

\*1 The pitch tolerance of the holes at both ends is  $\pm 0.3$ .



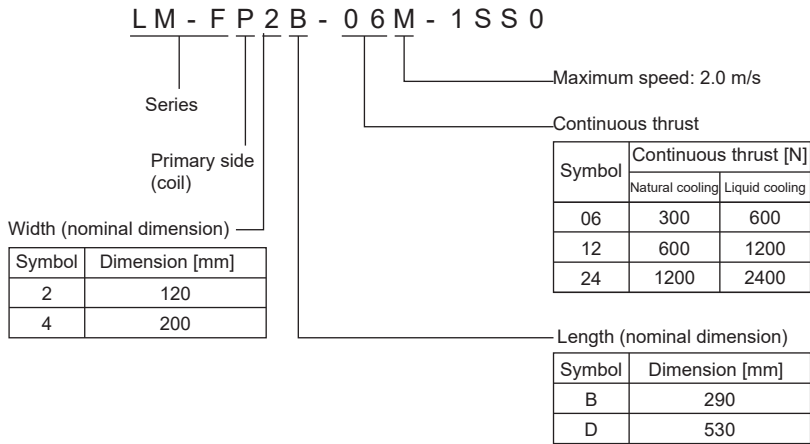
[Unit: mm]

# 8 LM-F SERIES

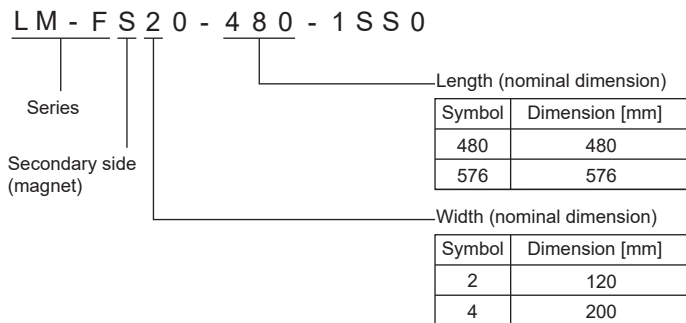
## 8.1 Model name designation

The following describes what each block of a model name indicates. Not all combinations of the symbols are available.

### Primary side (coil)



### Secondary side (magnet)



## 8.2 Standard specifications

### Standard specifications list

Linear servo motor (primary side) LM-F_		P2B-06M-1SS0	P2D-12M-1SS0	P2F-18M-1SS0	P4B-12M-1SS0	P4D-24M-1SS0	
Linear servo motor (secondary side) LM-F_		S20-480-1SS0 S20-576-1SS0	S20-480-1SS0 S20-576-1SS0		S40-480-1SS0 S40-576-1SS0		
Power supply capacity [kVA]		Refer to "Power supply capacity and generated loss" in the User's Manual (Hardware) for the servo amplifier being used.					
Cooling method		Natural cooling, liquid cooling					
Thrust	Continuous <sup>*2</sup> <sup>*4</sup> [N]	Natural cooling	300	600	900	600	1200
		Liquid cooling	600	1200	1800	1200	2400
	Maximum [N]	1800	3600	5400	3600	7200	
Maximum speed <sup>*1</sup> [m/s]		2.0					
Magnetic attraction force [N]		4500	9000	13500	9000	18000	
Rated current [A]	Natural cooling	4.0	7.8	12	7.8	15	
	Liquid cooling	7.8	16	23	17	31	
Maximum current [A]		30	58	87	57	109	
Recommended load to motor mass ratio		15 times or less the mass of the linear servo motor primary side					
Thermistor		Built-in					
Insulation class		155 (F)					
Structure		Open (IP rating: IP00 <sup>*3</sup> )					
Vibration resistance [m/s <sup>2</sup> ]		49					
Mass	Primary side [kg]	9.0	18	27	14	28	
	Secondary side [kg]	7.0 (480 mm/pc) 9.0 (576 mm/pc)			12 (480 mm/pc) 15 (576 mm/pc)		

\*1 The actual maximum speed of the linear servo motor is the lower value between the maximum speed of the linear servo motor and the rated speed of the linear encoder.

\*2 The continuous thrust values in the table apply when an aluminum board (table) with the dimensions (L [mm] × W [mm] × H [mm]) shown below is mounted on the primary side. (The dimensions shown are for reference purposes only)

LM-FP2B-06M-1SS0: 280 × 250 × 50

LM-FP2D-12M-1SS0: 510 × 250 × 50

LM-FP2F-18M-1SS0: 740 × 250 × 50

LM-FP4B-12M-1SS0: 280 × 425 × 50

LM-FP4D-24M-1SS0: 500 × 425 × 50

\*3 IP classifies the degree of protection provided against the intrusion of solid objects and water in electrical enclosures.

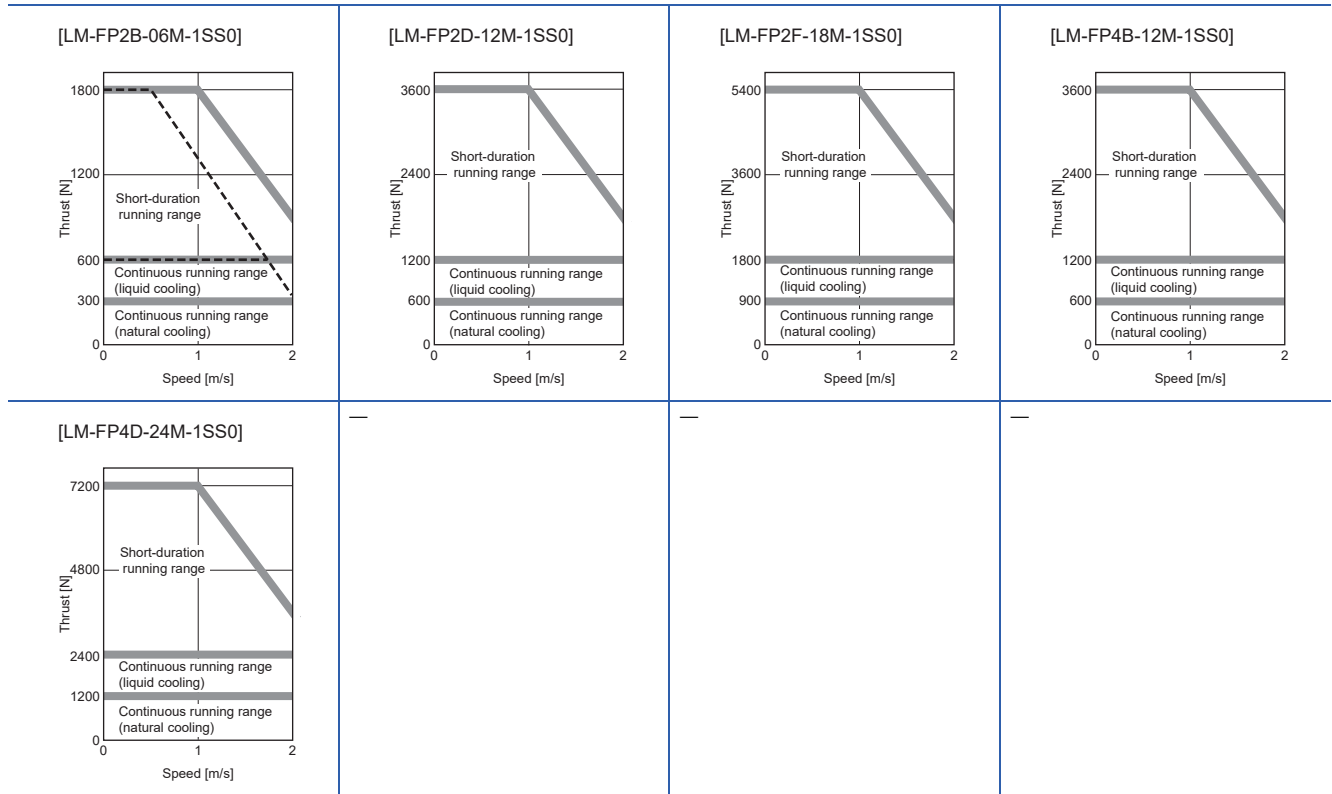
\*4 Use the linear servo motor with 70 % or less of the effective load ratio when it is servo-locked or if there is faint reciprocating motion.

# Thrust characteristics

The following shows the thrust characteristic when the power supply input of the servo amplifier is 3-phase 200 V AC or 1-phase 200 V AC.

The continuous/maximum thrust and maximum speed of the linear servo motor are specified based on the rated voltage and frequency applied by the combined servo amplifier.

- : 3-phase 200 V AC
- : 1-phase 200 V AC



## 8.3 Derating

The derating conditions are reference values. As the temperature rise value of the linear servo motor changes depending on operation conditions such as speed, confirm that [AL. 0E2 Servo motor overheat warning] and [AL. 046 Servo motor overheat] do not occur on the actual machine before use.

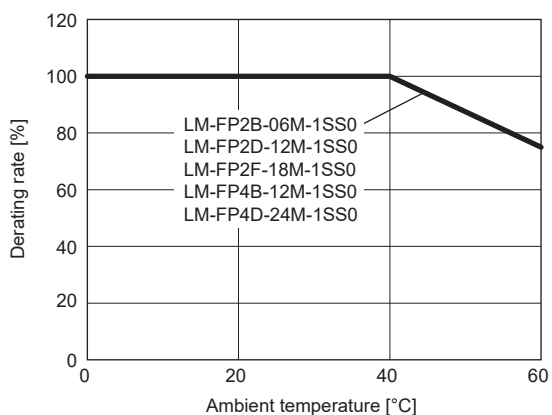
If a warning or alarm occurs, consider taking the following measures:

- Lower the effective load ratio of the linear servo motor.
- Review the heat dissipation conditions.

To use this product under conditions with multiple derating, calculate the multiplication of each derating rate, and use at the calculated derating rate or lower.

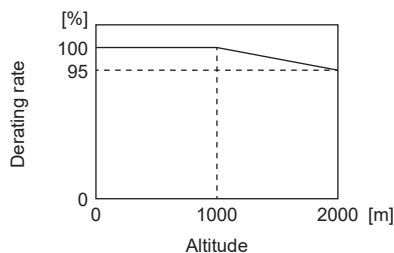
### Restrictions on the ambient temperature

When using this product in an environment with a high ambient temperature, derate the product in accordance with the following conditions:



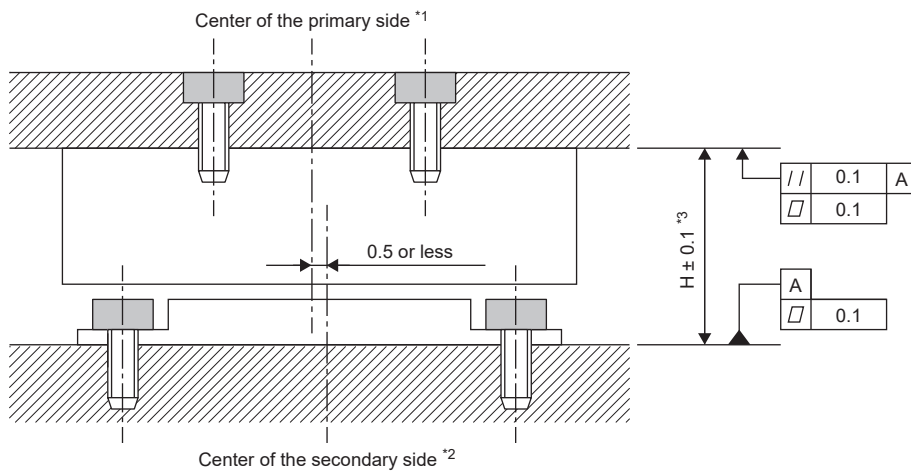
### Restrictions on the altitude

When using this product at an altitude between 1000 m and 2000 m, derate the product in accordance with the following conditions:



# 8.4 Installation

## Fitting method



[Unit: mm]

- \*1 The locations of the center of the primary side are shown below.  
 LM-FP2\_-M-1SS0: the center of the mounting screw pitch  
 LM-FP4\_-M-1SS0: the position of the center mounting screw
- \*2 The center of the secondary side is located at the center of the mounting screw pitch.
- \*3 H length indicates (height of primary side) + (height of secondary side) + (length of empty clearance: 0.5 mm).  
 LM-FP2\_-M-1SS0: H = 70 mm  
 LM-FP4\_-M-1SS0: H = 70 mm

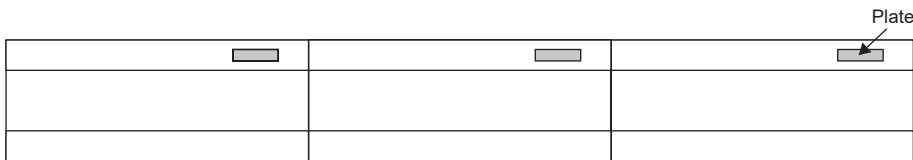
# Installation of the secondary side (magnet)

## Precautions

- The secondary side contains a strong magnet. Because an attraction force occurs between the surrounding magnetic materials or other secondary sides, be very careful not to get your hands or other body parts caught.
- If mounting an additional secondary side with a secondary side already set, first set the additional side so that it is distanced from the already mounted one, then slide the additional side to mount it in its specified position as shown in this section.
- Keep the cumulative pitch error of the mounting screw holes to within  $\pm 0.2$  mm. When two or more secondary sides are installed, clearance may be left between the secondary sides depending on the installing method and the number of secondary sides.

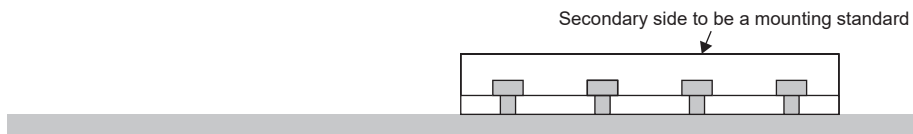
## Procedure

When using multiple secondary sides, arrange them so that the name plate attached to each side all share the same orientation to keep the layout of magnetic poles.

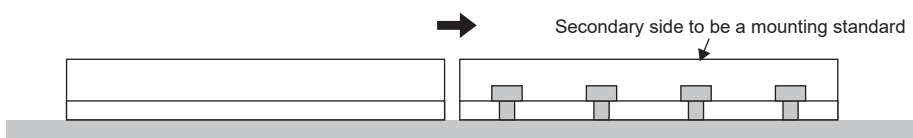


In addition, use the following procedure when mounting the secondary sides to decrease the clearance between them.

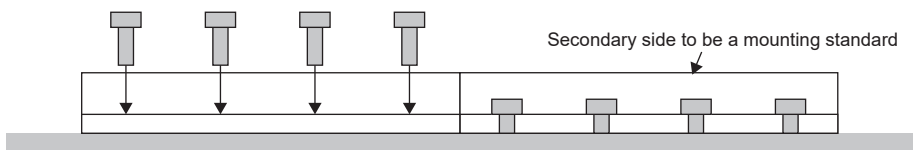
1. Use bolts to securely fix the secondary side that will be used as the mounting standard into place.



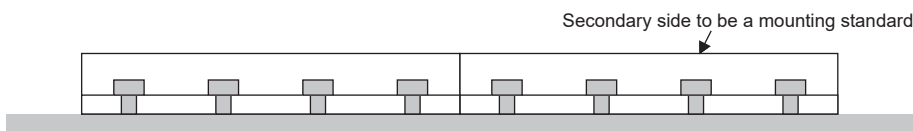
2. Set the next secondary side on the mounting face and press it toward the secondary side to be a mounting standard.



3. Use bolts to temporarily fix the added secondary side and position it.



4. Use bolts to securely fix the added secondary side into place.



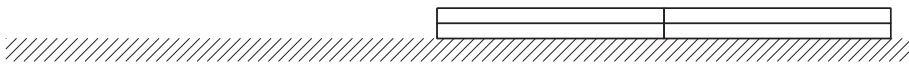
# Installation of the primary side (coil)

## Precautions

- We recommend mounting the primary side in a position where no secondary side is present. If the primary side must be mounted over the secondary side, use material handling equipment such as cranes that can fully withstand the load of the attraction force, etc.
- When sliding the the primary side over the secondary side after installing, take precautions against the attraction force that is generated.

## Procedure

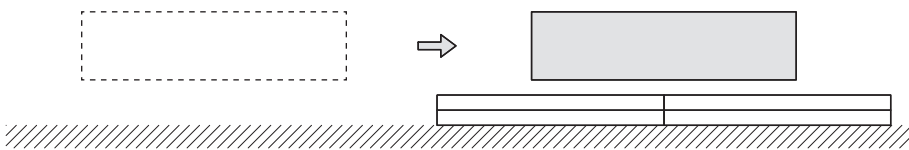
1. Mount a portion of the secondary sides.



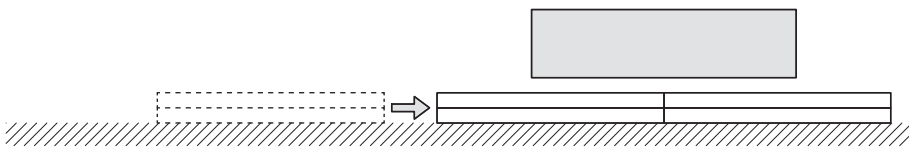
2. Mount the primary side in a position where no secondary side is present.



3. Move the primary side over the mounted secondary side. Confirm that the primary and secondary sides are not touching each other.



4. Mount the rest of the secondary sides. Confirm that the primary and secondary sides are not touching each other.



## 8.5 Liquid cooling

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LM-F series linear servo motors are compatible with liquid cooling. Configure the machine (system) after confirming the following items.

- Parts required for cooling system design, including the cooling pipe laying in the primary-side table, parts required for installation and cooling, the cooling machine (chiller), and the coolant should be carefully selected by the customer. For example, when water is used as coolant, 5 liters or more are required per minute. Ensure that the pressure on the pipe flow entrance is 0.5 MPa or less.
- To prevent foreign matter from entering the cooling pipe, be sure to always set a filter, etc. in the flow path.
- To avoid a liquid leak, the liquid-cooling pipe, coupling, etc. should be carefully selected by the customer. In particular, be sure to select a liquid-cooling pipe that can withstand being bent.
- We recommend keeping the temperature of the liquid injected into the cooling pipe at room temperature (around 20 °C). Ensure that condensation does not occur if lowering the liquid temperature to heighten the cooling effect.
- The overload protection characteristics are different from those for natural cooling, so confirm that conditions such as the operation pattern are matched with the overload protection characteristics. If the operation conditions are not matched with the overload protection characteristics, an alarm may occur. For the overload protection characteristics, refer to "USING A LINER SERVO MOTOR" in the following manual.

 MR-J5 User's Manual (Hardware)

- Copper is used as the material for the cooling pipe, so when choosing the corrosion inhibitor to add to the coolant, be sure to select one that will not corrode the copper.
- When laying the cooling pipe, fix the hexagonal part of the cooling pipe in place using a spanner. The tightening torque used should be 3.0 N•m to 3.5 N•m.

# 8.6 Dimensions

## Primary-side (coil) dimensions

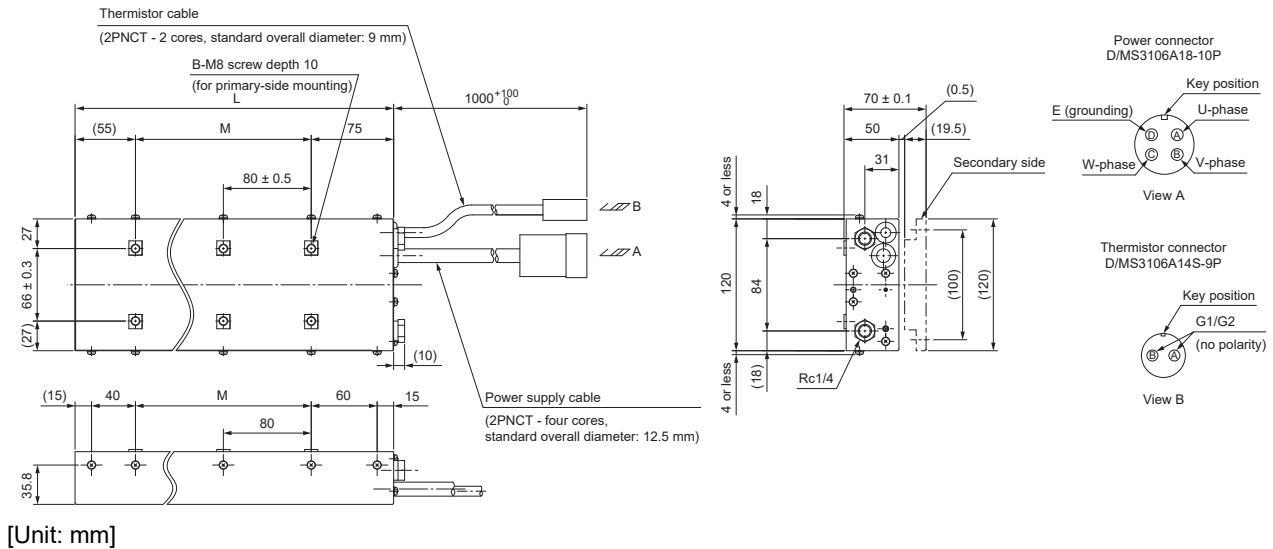
When mounting the primary side, use hexagon socket head cap screws (material should be SCM435 with a lower yield point of 900 N/mm<sup>2</sup> or more).

The power lead wires, grounding lead wires, and thermistor lead wires are for fixed wiring. Securely fix them to the structure. The recommended minimum bending radius for the cable is six times or more (reference value) the standard overall diameter of the cable. Consider the speed of the linear servo motor and the flexing radius when selecting the cable to use for the moving part.

### LM-FP2B-06M-1SS0/LM-FP2D-12M-1SS0/LM-FP2F-18M-1SS0

Model name	Variable dimensions		
	L	M	B
LM-FP2B-06M-1SS0	290	2 × 80 (= 160) *1	6
LM-FP2D-12M-1SS0	530	5 × 80 (= 400) *1	12
LM-FP2F-18M-1SS0	770	8 × 80 (= 640) *1	18

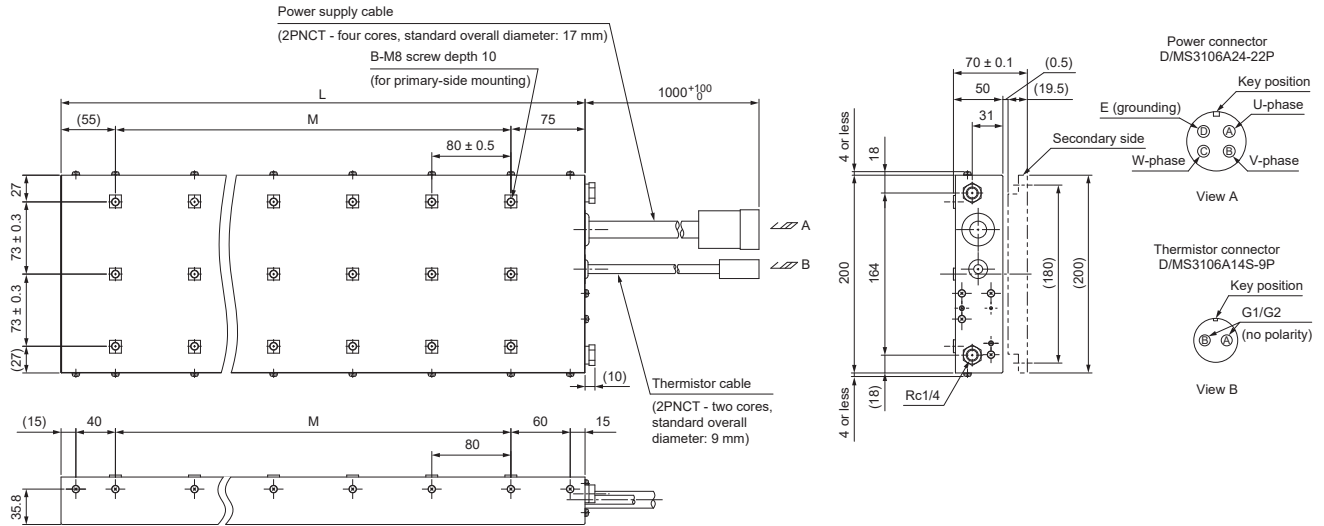
\*1 The pitch tolerance of the holes at both ends is ±0.5.



## LM-FP4B-12M-1SS0/LM-FP4D-24M-1SS0

Model name	Variable dimensions		
	L	M	B
LM-FP4B-12M-1SS0	290	$2 \times 80 (= 160)$ *1	9
LM-FP4D-24M-1SS0	530	$5 \times 80 (= 400)$ *1	18

\*1 The pitch tolerance of the holes at both ends is  $\pm 0.5$ .



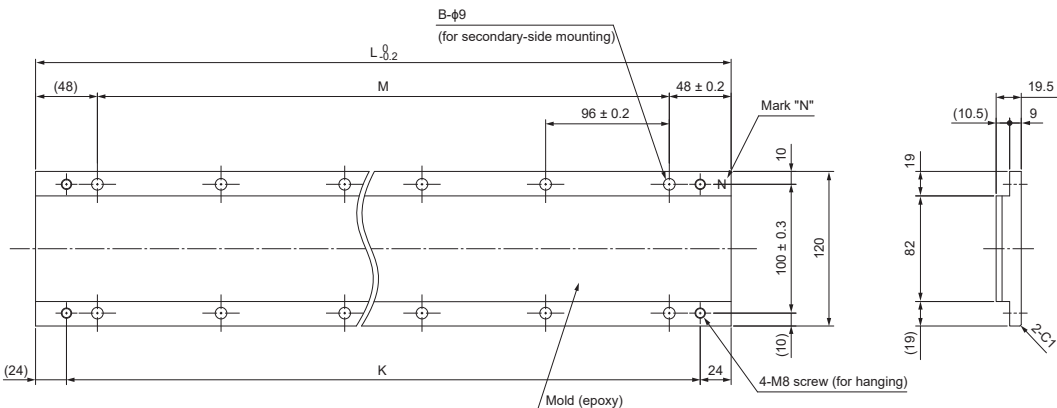
## Secondary-side (magnet) dimensions

When mounting the secondary side, use hexagon socket head cap screws (material should be SCM435 with a lower yield point of  $900 \text{ N/mm}^2$  or equivalent).

## LM-FS20-480-1SS0/LM-FS20-576-1SS0

Model name	Variable dimensions			
	L	M	B	K
LM-FS20-480-1SS0	480	$4 \times 96 (= 384)$ *1	10	432
LM-FS20-576-1SS0	576	$5 \times 96 (= 480)$ *1	12	528

\*1 The pitch tolerance of the holes at both ends is  $\pm 0.2$ .



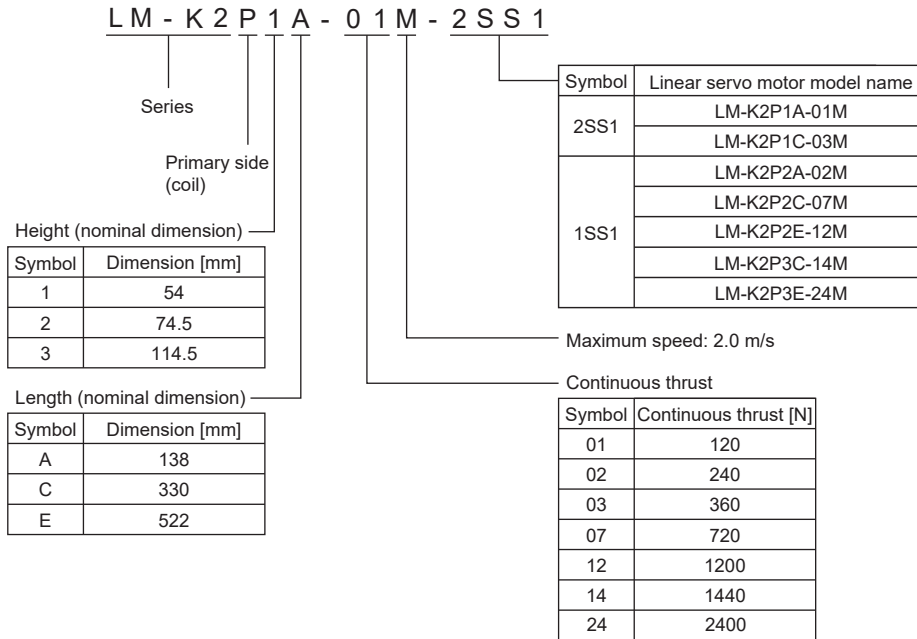


# 9 LM-K2 SERIES

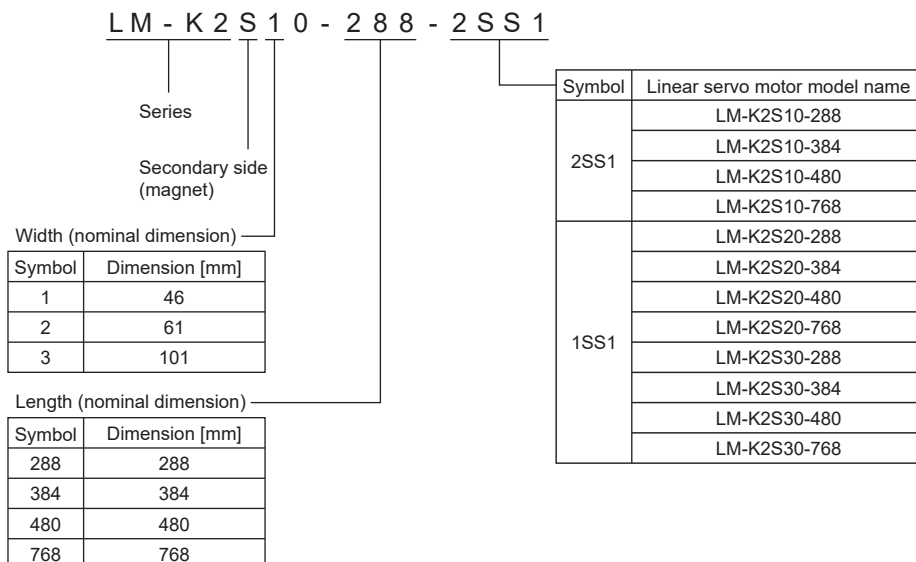
## 9.1 Model name designation

The following describes what each block of a model name indicates. Not all combinations of the symbols are available.

### Primary side (coil)



### Secondary side (magnet)



## 9.2 Standard specifications

### Standard specifications list

Linear servo motor (primary side) LM-K2_		P1A-01M-2SS1	P1C-03M-2SS1	P2A-02M-1SS1	P2C-07M-1SS1	P2E-12M-1SS1	P3C-14M-1SS1	P3E-24M-1SS1
Linear servo motor (secondary side) LM-K2_		S10-288-2SS1 S10-384-2SS1 S10-480-2SS1 S10-768-2SS1		S20-288-1SS1 S20-384-1SS1 S20-480-1SS1 S20-768-1SS1			S30-288-1SS1 S30-384-1SS1 S30-480-1SS1 S30-768-1SS1	
Power supply capacity [kVA]		Refer to "Power supply capacity and generated loss" in the User's Manual (Hardware) for the servo amplifier being used.						
Cooling method		Natural cooling						
Thrust	Continuous <sup>*2 *4</sup> [N]	120	360	240	720	1200	1440	2400
	Maximum [N]	300	900	600	1800	3000	3600	6000
Maximum speed <sup>*1</sup> [m/s]		2.0						
Magnetic attraction force <sup>*5</sup> [N]		0						
Magnetic attraction force (one side) <sup>*6</sup> [N]		800	2400	1100	3200	5300	6400	10700
Rated current [A]		2.3	6.8	3.7	12	19	15	25
Maximum current [A]		7.6	23	13	39	65	47	79
Recommended load to motor mass ratio		30 times or less the mass of the linear servo motor primary side						
Thermistor		Built-in						
Insulation class		155 (F)						
Structure		Open (IP rating: IP00 <sup>*3</sup> )						
Vibration resistance [m/s <sup>2</sup> ]		49						
Mass	Primary side [kg]	2.5	6.5	4.0	10	16	18	27
	Secondary side [kg]	1.5 (288 mm/pc) 2.0 (384 mm/pc) 2.5 (480 mm/pc) 3.9 (768 mm/pc)		1.9 (288 mm/pc) 2.5 (384 mm/pc) 3.2 (480 mm/pc) 5.0 (768 mm/pc)			5.5 (288 mm/pc) 7.3 (384 mm/pc) 9.2 (480 mm/pc) 14.6 (768 mm/pc)	

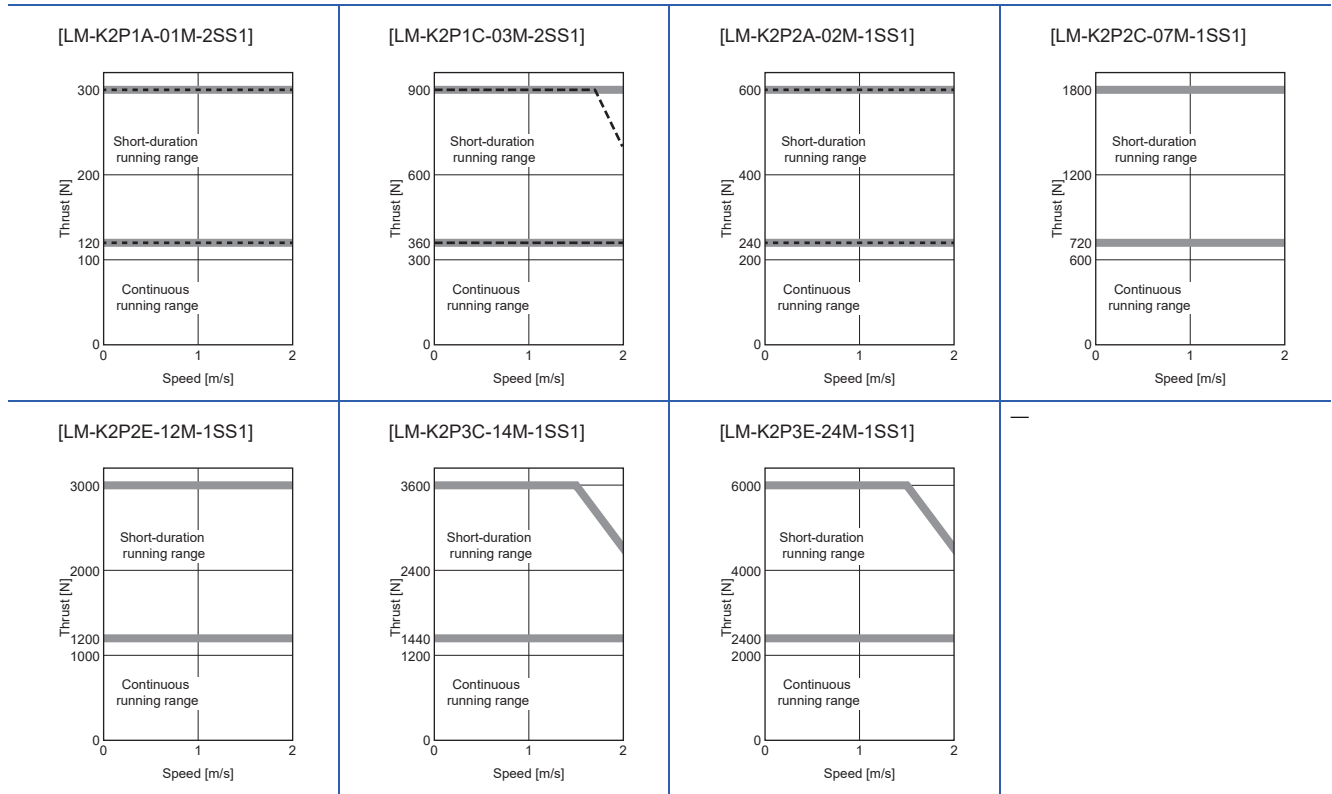
- \*1 The actual maximum speed of the linear servo motor is the lower value between the maximum speed of the linear servo motor and the rated speed of the linear encoder.
- \*2 The continuous thrust values in the table apply when an aluminum board (table) with the dimensions (L [mm] × W [mm] × H [mm]) shown below is mounted on the primary side. (The dimensions shown are for reference purposes only)  
 LM-K2P1A-01M-1SS1: 375 × 270 × 20  
 LM-K2P1C-03M-1SS1: 375 × 270 × 20  
 LM-K2P2A-02M-1SS1: 375 × 270 × 20  
 LM-K2P2C-07M-1SS1: 375 × 270 × 20  
 LM-K2P2E-12M-1SS1: 520 × 270 × 20  
 LM-K2P3C-14M-1SS1: 375 × 270 × 20  
 LM-K2P3E-24M-1SS1: 760 × 610 × 50
- \*3 IP classifies the degree of protection provided against the intrusion of solid objects and water in electrical enclosures.
- \*4 Use the linear servo motor with 70 % or less of the effective load ratio when it is servo-locked or if there is faint reciprocating motion.
- \*5 Magnetic attraction force is generated due to assembly accuracy and other causes.
- \*6 The indicated value is the magnetic attraction force generated on one secondary side.

# Thrust characteristics

The following shows the thrust characteristic when the power supply input of the servo amplifier is 3-phase 200 V AC or 1-phase 200 V AC.

The continuous/maximum thrust and maximum speed of the linear servo motor are specified based on the rated voltage and frequency applied by the combined servo amplifier.

- : 3-phase 200 V AC
- : 1-phase 200 V AC



## 9.3 Derating

The derating conditions are reference values. As the temperature rise value of the linear servo motor changes depending on operation conditions such as speed, confirm that [AL. 0E2 Servo motor overheat warning] and [AL. 046 Servo motor overheat] do not occur on the actual machine before use.

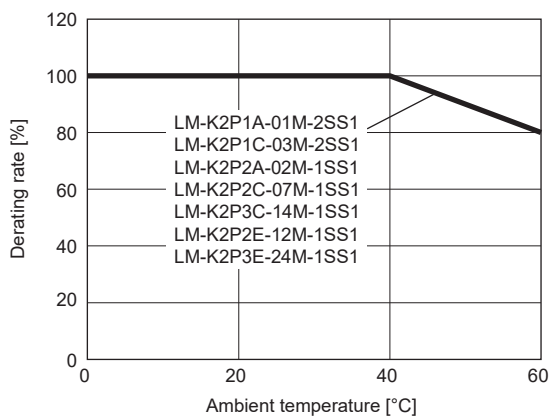
If a warning or alarm occurs, consider taking the following measures:

- Lower the effective load ratio of the linear servo motor.
- Review the heat dissipation conditions.

To use this product under conditions with multiple derating, calculate the multiplication of each derating rate, and use at the calculated derating rate or lower.

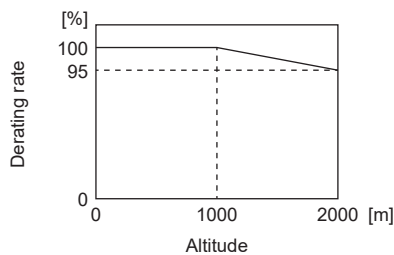
### Restrictions on the ambient temperature

When using this product in an environment with a high ambient temperature, derate the product in accordance with the following conditions:



### Restrictions on the altitude

When using this product at an altitude between 1000 m and 2000 m, derate the product in accordance with the following conditions:



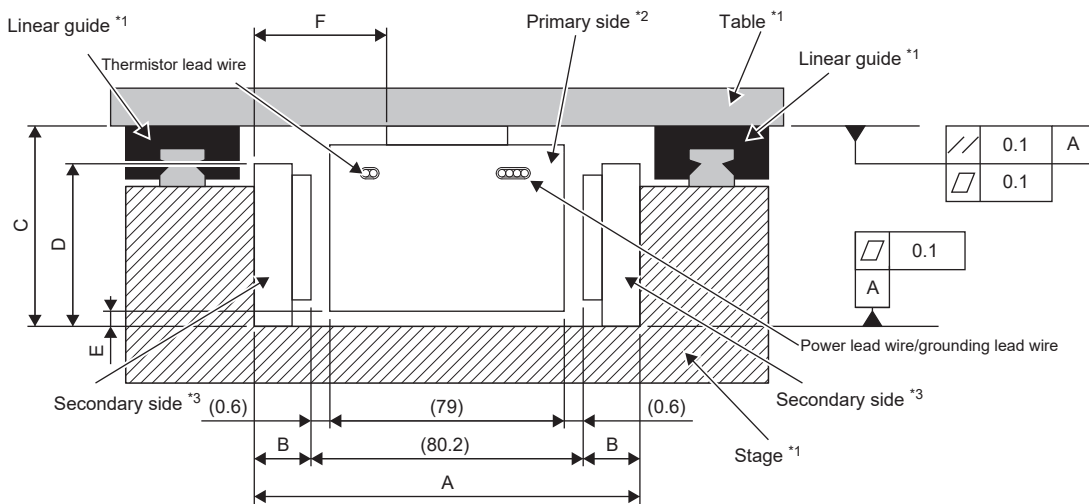
# 9.4 Installation

## Mounting dimensions

Mount the primary side and secondary side so that variable dimensions A, C, and F are as defined as shown in the following table. Refer to the outline drawing for details of the dimensions.

[Unit: mm]

Linear servo motor	Variable dimensions					
	A	B	C	D	E	F
LM-K2P1A-01M-2SS1	115 $^{+0.1}_0$	(17.4)	55 ± 0.1	(46)	(1)	38.5 ± 0.1
LM-K2P1C-03M-2SS1						
LM-K2P2A-02M-1SS1	115 $^{+0.1}_0$	(17.4)	76.5 ± 0.1	(61)	(2)	38.5 ± 0.1
LM-K2P2C-07M-1SS1						
LM-K2P2E-12M-1SS1						
LM-K2P3C-14M-1SS1	139 $^{+0.1}_0$	(29.4)	116.5 ± 0.1	(101)	(2)	50.5 ± 0.1
LM-K2P3E-24M-1SS1						



\*1 These items should be prepared by the customer. Contact the manufacturer for information regarding the mounting method.

\*2 Position the primary side using the table flange rabbet, etc.

\*3 One pair of secondary sides consists of two secondary sides that face each other. Mount the corresponding secondary side to the opposite side.

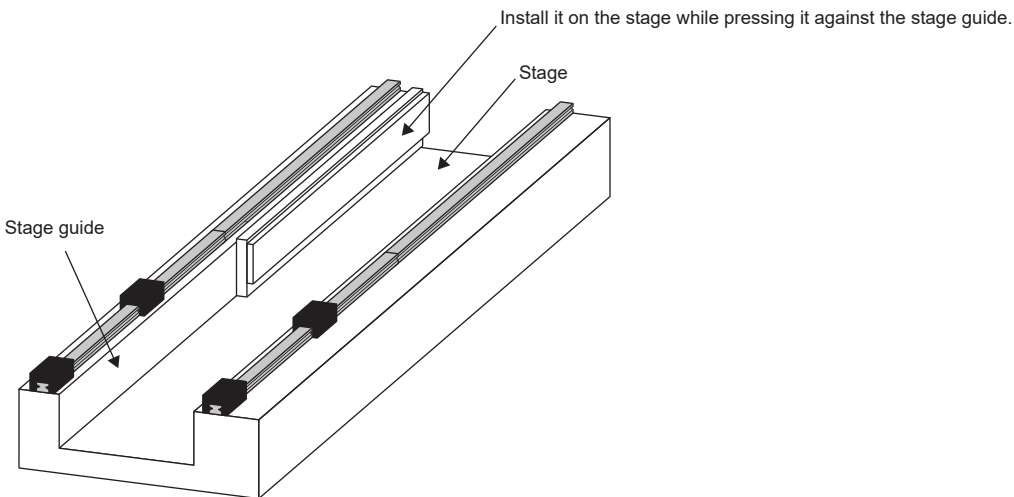
# Installation procedure

## Precautions

- The secondary side contains a strong magnet. Because an attraction force occurs between the surrounding magnetic materials or other secondary sides, be very careful not to get your hands or other body parts caught.
- If mounting an additional secondary side with a secondary side already set, first set the additional side so that it is distanced from the already mounted one, then slide the additional side to mount it in its specified position as shown in this section.
- After installation, confirm that the primary side is not touching the secondary side.
- Keep the cumulative pitch error of the mounting screw holes to within  $\pm 0.1$  mm. When two or more pairs of secondary sides are installed, clearance may be left between the secondary sides depending on the installing method and the number of secondary sides.

## Procedure 1

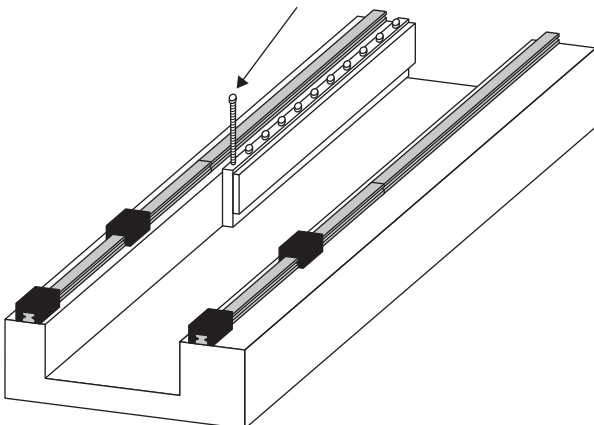
1. Place one half of the first pair of secondary sides on the stage while pressing it against the stage guide.



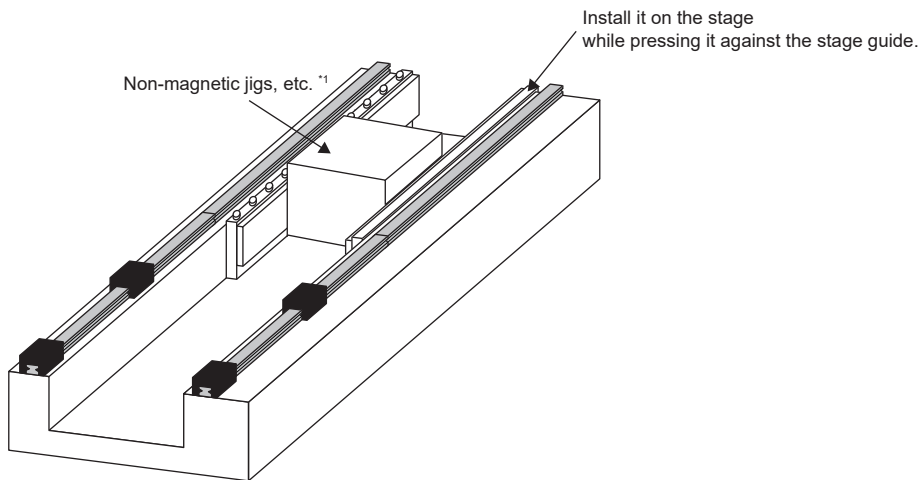
YouTube video

2. Firmly press the side face of the secondary side against the stage guide, then securely fix it into place with hexagon socket head cap screws.

Fix the secondary side with the hexagon socket head cap screw.

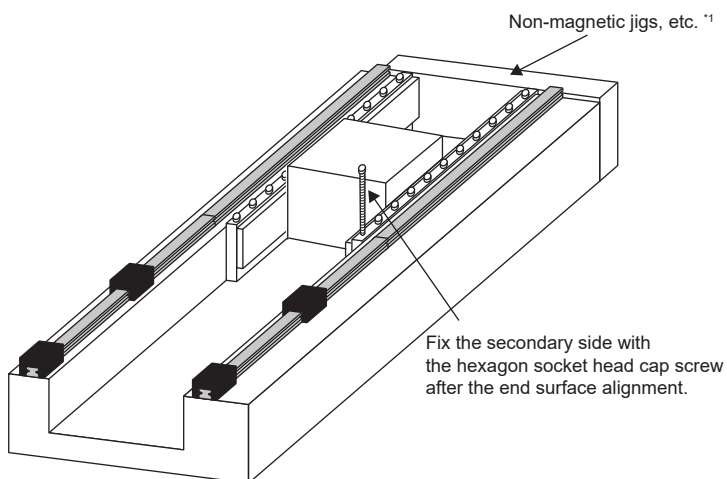


- 3.** Install the side face of the secondary side that will be added on the stage while firmly pressing it into place on the surface facing the secondary side installed in steps 1 and 2. To prevent attraction to the secondary side installed in step 1, place a non-magnetic jig or similar tool before performing the operation.



\*1 These items should be prepared by the customer.

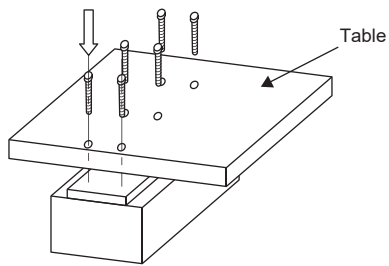
- 4.** Using a non-magnetic jig or similar tool, standardize the positions of the end surface of the secondary side installed in steps 1 and 2 and the end surface of the secondary side installed in step 3. After that, securely fix the added secondary side into place with hexagon socket head cap screws.



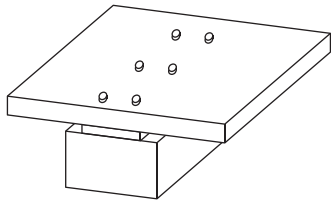
\*1 These items should be prepared by the customer.

## Procedure 2

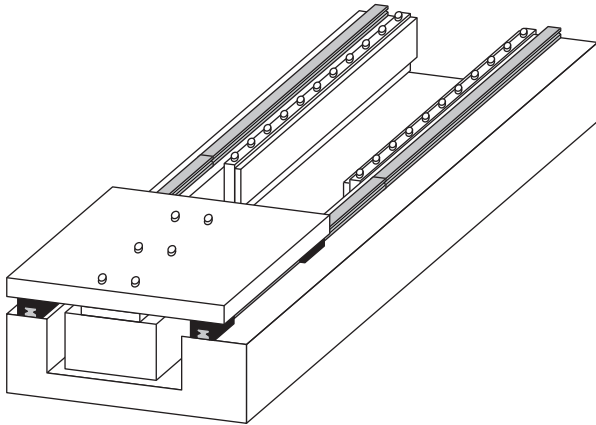
1. Install the table on the primary side using hexagon socket head cap screws.



YouTube video

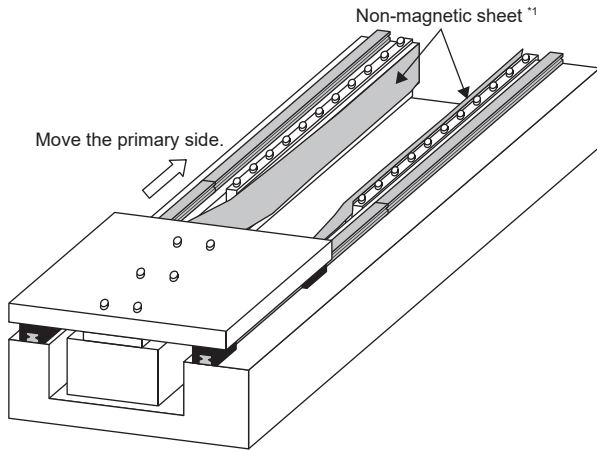


2. Mount the primary side in a position where no secondary side is present.



### Procedure 3

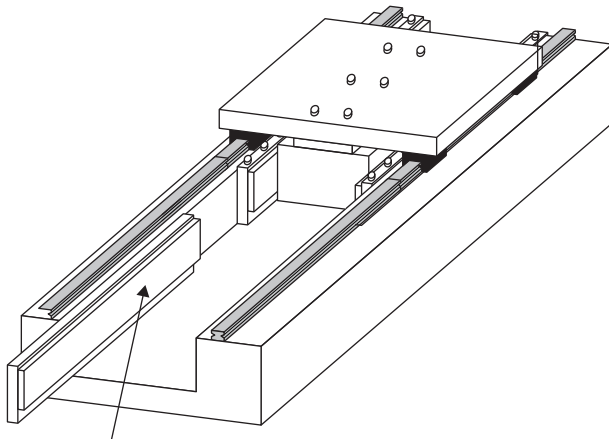
1. To prevent damage caused by contact, place non-magnetic sheets (of approx. 0.3 mm thickness) on the gap part (both sides) between the primary and secondary sides, then move the primary side toward the secondary side that was installed in Procedure 1. Remove the non-magnetic sheets after moving the primary side to the secondary side. When removing the sheets, be careful not to scratch the primary and secondary sides.



YouTube video

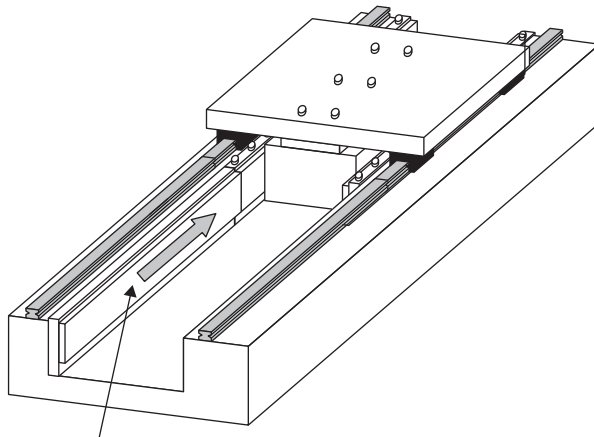
\*1 These items should be prepared by the customer.

2. Place one half of the next pair of secondary sides on the stage while pressing it against the stage guide.



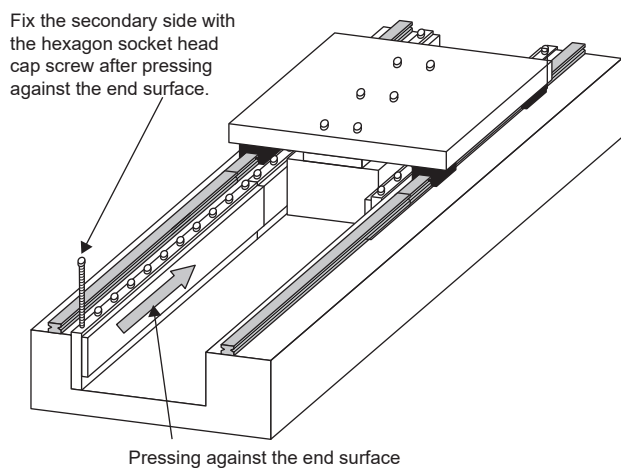
Install it on the stage while pressing it against the stage guide.

3. While firmly pressing the side surface of the secondary side against the stage guide, press it to the secondary side installed in Procedure 1.

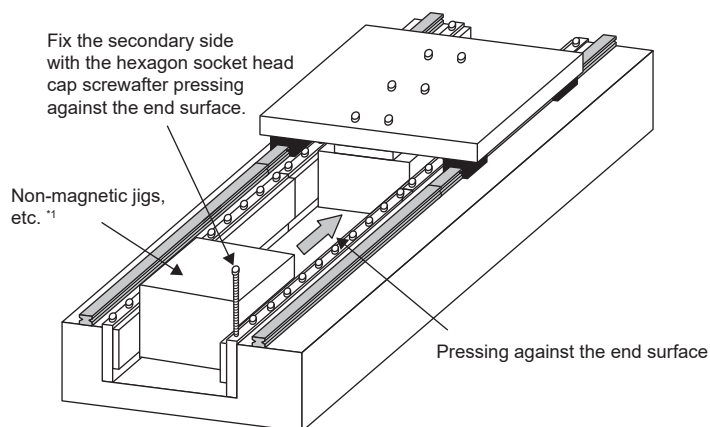


Align it closely with the secondary side installed in step 1 while pressing it against the stage guide.

4. While pressing the added secondary side against the end surface of the secondary side installed in Procedure 1, securely fix it into place using hexagon socket head cap screws.



5. Install the other secondary side on the opposite surface so that it faces the first. As in Procedure 1, to prevent attraction to the secondary sides installed in steps 2, 3, and 4, place a nonmagnetic jig or similar tool before performing the operation.



\*1 These items should be prepared by the customer.

# 9.5 Dimensions

## Primary-side (coil) dimensions

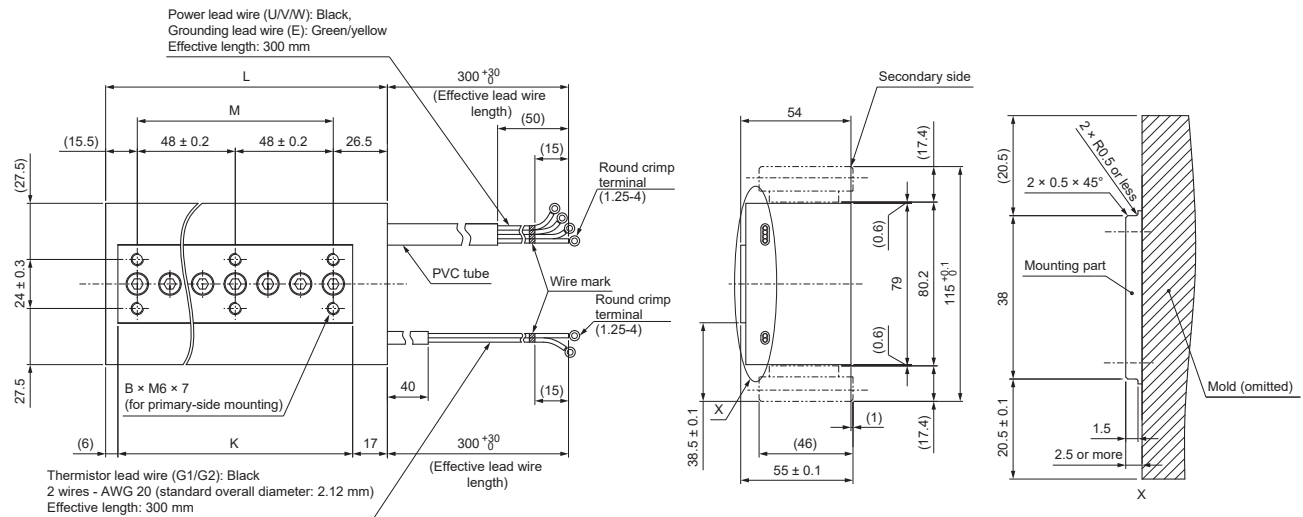
When mounting the primary side, use hexagon socket head cap screws (material should be SCM435 with a lower yield point of 900 N/mm<sup>2</sup> or more).

The power lead wires, grounding lead wires, and thermistor lead wires are for fixed wiring. Securely fix them to the structure. The recommended minimum bending radius for the lead wire is six times or more (reference value) the standard overall diameter of the lead wire. Consider the speed of the linear servo motor and the flexing radius when selecting the cable to use for the moving part.

### LM-K2P1A-01M-2SS1/LM-K2P1C-03M-2SS1

Model name	Variable dimensions				Power/grounding lead wires	
	L	M	K	B	Size	Standard overall diameter
LM-K2P1A-01M-2SS1	138	2 × 48 (= 96) *1	115	6	4 wires - AWG 20	2.12
LM-K2P1C-03M-2SS1	330	6 × 48 (= 288) *1	307	14	4 wires - AWG 16	2.7

\*1 The pitch tolerance of the holes at both ends is ±0.3.

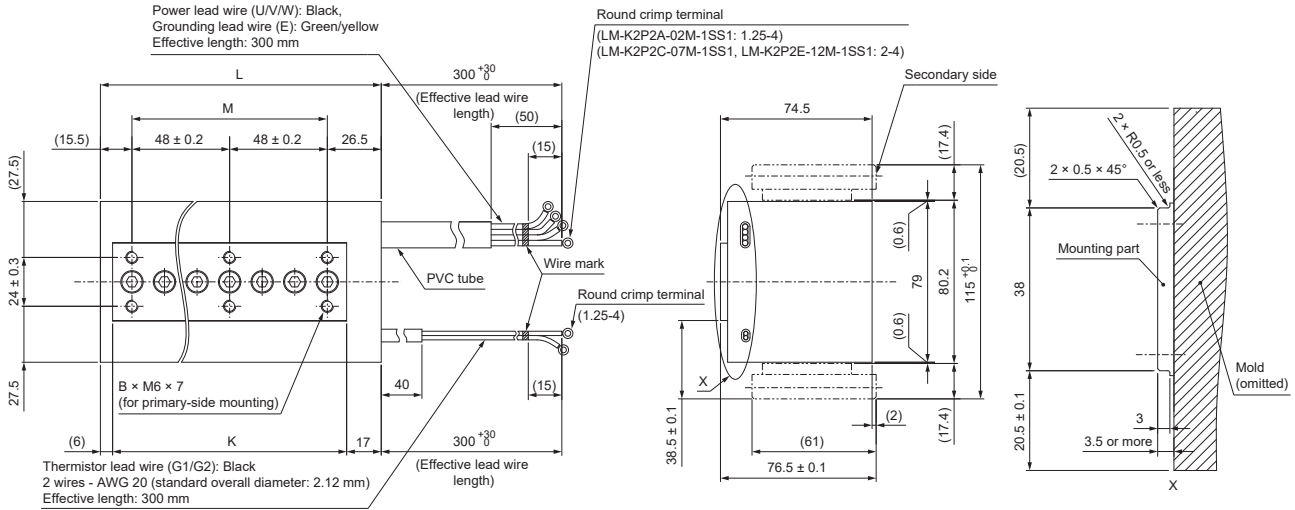


[Unit: mm]

### LM-K2P2A-02M-1SS1/LM-K2P2C-07M-1SS1/LM-K2P2E-12M-1SS1

Model name	Variable dimensions				Power/grounding lead wires	
	L	M	K	B	Size	Standard overall diameter
LM-K2P2A-02M-1SS1	138	2 × 48 (= 96) *1	115	6	4 wires - AWG 16	2.7
LM-K2P2C-07M-1SS1	330	6 × 48 (= 288) *1	307	14	4 wires - AWG 14	3.12
LM-K2P2E-12M-1SS1	522	10 × 48 (= 480) *1	499	22		

\*1 The pitch tolerance of the holes at both ends is ±0.3.

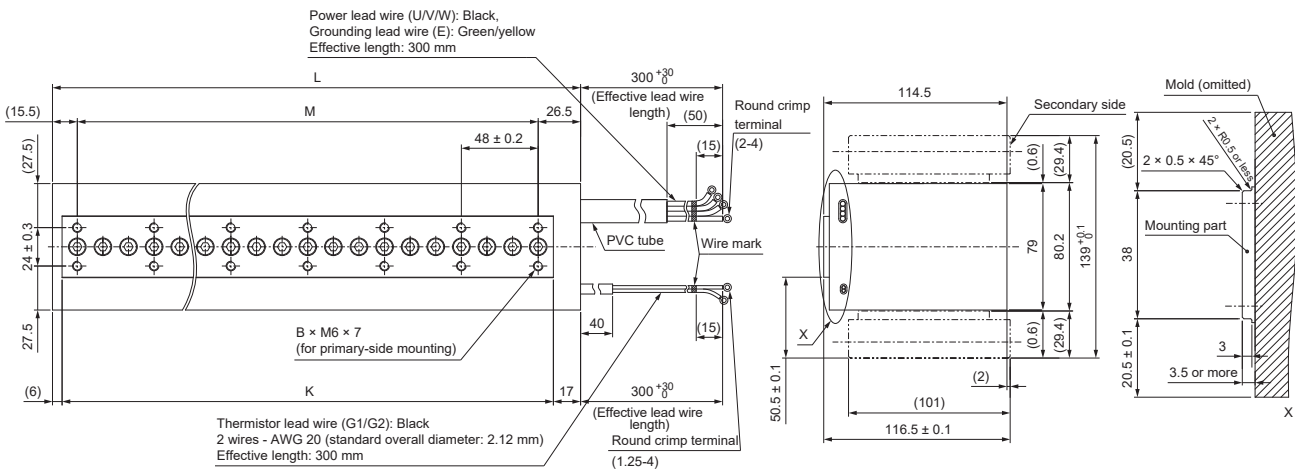


[Unit: mm]

### LM-K2P3C-14M-1SS1/LM-K2P3E-24M-1SS1

Model name	Variable dimensions				Power/grounding lead wires	
	L	M	K	B	Size	Standard overall diameter
LM-K2P3C-14M-1SS1	330	6 × 48 (= 288) *1	307	14	4 wires - AWG 14	3.12
LM-K2P3E-24M-1SS1	522	10 × 48 (= 480) *1	499	22		

\*1 The pitch tolerance of the holes at both ends is ±0.3.



[Unit: mm]

# Secondary-side (magnet) dimensions

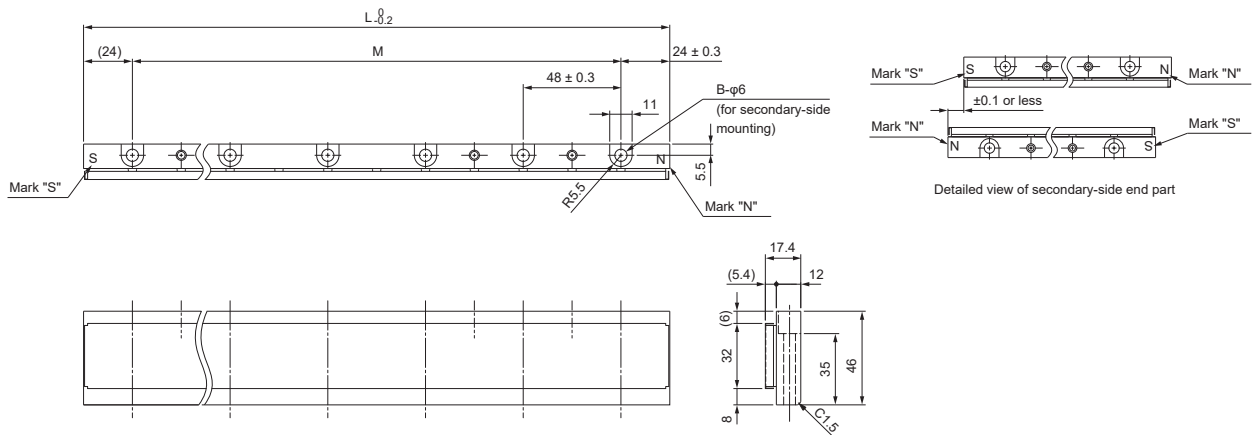
When mounting the secondary side, use hexagon socket head cap screws (material should be SCM435 with a lower yield point of 900 N/mm<sup>2</sup> or equivalent).

The longitudinal deviation of the secondary side must be  $\pm 0.1$  mm or less. (Refer to "Detailed view of secondary-side edge".)

## LM-K2S10-288-2SS1/LM-K2S10-384-2SS1/LM-K2S10-480-2SS1/LM-K2S10-768-2SS1

Model name	Variable dimensions		
	L	M	B
LM-K2S10-288-2SS1	288	5 × 48 (= 240) *1	6
LM-K2S10-384-2SS1	384	7 × 48 (= 336) *1	8
LM-K2S10-480-2SS1	480	9 × 48 (= 432) *1	10
LM-K2S10-768-2SS1	768	15 × 48 (= 720) *1	16

\*1 The pitch tolerance of the holes at both ends is  $\pm 0.3$ .

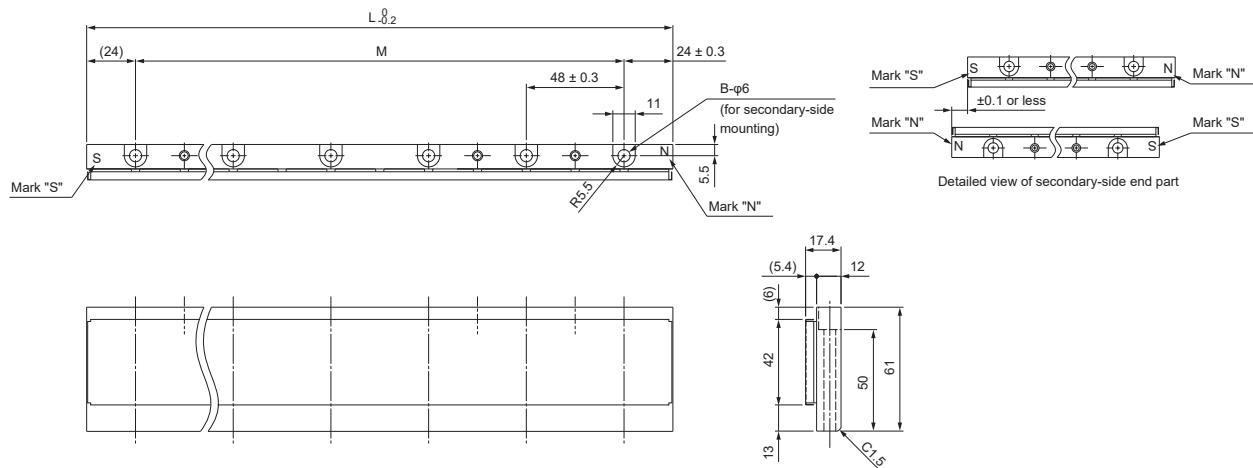


[Unit: mm]

## LM-K2S20-288-1SS1/LM-K2S20-384-1SS1/LM-K2S20-480-1SS1/LM-K2S20-768-1SS1

Model name	Variable dimensions		
	L	M	B
LM-K2S20-288-1SS1	288	5 × 48 (= 240) *1	6
LM-K2S20-384-1SS1	384	7 × 48 (= 336) *1	8
LM-K2S20-480-1SS1	480	9 × 48 (= 432) *1	10
LM-K2S20-768-1SS1	768	15 × 48 (= 720) *1	16

\*1 The pitch tolerance of the holes at both ends is  $\pm 0.3$ .

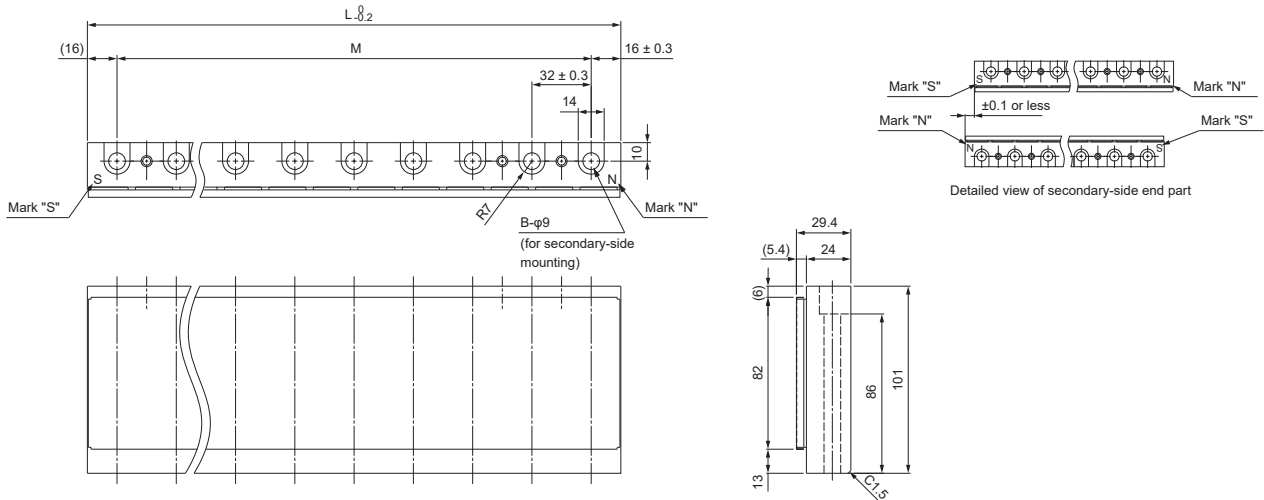


[Unit: mm]

**LM-K2S30-288-1SS1/LM-K2S30-384-1SS1/LM-K2S30-480-1SS1/LM-K2S30-768-1SS1**

Model name	Variable dimensions		
	L	M	B
LM-K2S30-288-1SS1	288	8 × 32 (= 256) *1	9
LM-K2S30-384-1SS1	384	11 × 32 (= 352) *1	12
LM-K2S30-480-1SS1	480	14 × 32 (= 448) *1	15
LM-K2S30-768-1SS1	768	23 × 32 (= 736) *1	24

\*1 The pitch tolerance of the holes at both ends is ±0.3.



[Unit: mm]

# REVISIONS

\*The manual number is given on the bottom left of the back cover.

Revision date	*Manual number	Description
July 2019	SH(NA)-030316ENG-A	First edition
July 2020	SH(NA)-030316ENG-B	<ul style="list-style-type: none"> <li>■ Addition of the following linear servo motors LM-U2P2D-80M-2SS0, LM-FP2D-12M-1SS0 LM-FP2F-18M-1SS0, LM-FP48-12M-1SS0 LM-FP4D-24M-1SS0, LM-FS40-480-1SS0 LM-FS40-576-1SS0, LM-K2P2E-12M-1SS1 LM-K2P3E-24M-1SS1</li> <li>■ Changes to portions on environment requirements</li> <li>■ Edited: Section 1.2, Section 4.2, Section 4.3, Chapter 6, Chapter 7, Chapter 8</li> <li>■ Added: Section 5.4, Section 6.4, Section 7.4, Section 8.4</li> </ul>
December 2021	SH(NA)-030316ENG-C	<ul style="list-style-type: none"> <li>■ Complied with UKCA</li> <li>■ Edited: Section 1.1, Section 4.3</li> </ul>
December 2025	SH(NA)-030316ENG-D	<ul style="list-style-type: none"> <li>■ The LM-H4M series has been added.</li> <li>■ Edited: Section 1.1, Section 1.2, Section 1.4, Section 1.5, Section 2.2, Chapter 4, Section 6.2, Section 6.3, Section 6.4, Section 6.5, Section 7.2, Section 7.3, Section 7.4, Section 7.5, Section 8.2, Section 8.3, Section 8.4, Section 8.6, Section 9.2, Section 9.3, Section 9.4, Section 9.5</li> <li>■ Added: Chapter 5</li> </ul>

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# WARRANTY

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## Warranty

### **1. Warranty period and coverage**

We will repair any failure or defect hereinafter referred to as "failure" in our FA equipment hereinafter referred to as the "Product" arisen during warranty period at no charge due to causes for which we are responsible through the distributor from which you purchased the Product or our service provider. However, we will charge the actual cost of dispatching our engineer for an on-site repair work on request by customer in Japan or overseas countries. We are not responsible for any on-site readjustment and/or trial run that may be required after a defective unit are repaired or replaced.

[Term]

For terms of warranty, please contact your original place of purchase.

[Limitations]

(1) You are requested to conduct an initial failure diagnosis by yourself, as a general rule.

It can also be carried out by us or our service company upon your request and the actual cost will be charged. However, it will not be charged if we are responsible for the cause of the failure.

(2) This limited warranty applies only when the condition, method, environment, etc. of use are in compliance with the terms and conditions and instructions that are set forth in the instruction manual and user manual for the Product and the caution label affixed to the Product.

(3) Even during the term of warranty, the repair cost will be charged on you in the following cases;

1. a failure caused by your improper storing or handling, carelessness or negligence, etc., and a failure caused by your hardware or software problem
2. a failure caused by any alteration, etc. to the Product made on your side without our approval
3. a failure which may be regarded as avoidable, if your equipment in which the Product is incorporated is equipped with a safety device required by applicable laws and has any function or structure considered to be indispensable according to a common sense in the industry
4. a failure which may be regarded as avoidable if consumable parts designated in the instruction manual, etc. are duly maintained and replaced
5. any replacement of consumable parts (battery, fan, smoothing capacitor, etc.)
6. a failure caused by external factors such as inevitable accidents, including without limitation fire and abnormal fluctuation of voltage, and acts of God, including without limitation earthquake, lightning and natural disasters
7. a failure generated by an unforeseeable cause with a scientific technology that was not available at the time of the shipment of the Product from our company
8. any other failures which we are not responsible for or which you acknowledge we are not responsible for

### **2. Term of warranty after the stop of production**

(1) We may accept the repair at charge for another seven (7) years after the production of the product is discontinued. The announcement of the stop of production for each model can be seen in our Sales and Service, etc.

(2) Please note that the Product (including its spare parts) cannot be ordered after its stop of production.

### **3. Service in overseas countries**

Our regional FA Center in overseas countries will accept the repair work of the Product. However, the terms and conditions of the repair work may differ depending on each FA Center. Please ask your local FA center for details.

### **4. Exclusion of loss in opportunity and secondary loss from warranty liability**

Regardless of the gratis warranty term, Mitsubishi shall not be liable for compensation to:

- (1) Damages caused by any cause found not to be the responsibility of Mitsubishi.
- (2) Loss in opportunity, lost profits incurred to the user by Failures of Mitsubishi products.
- (3) Special damages and secondary damages whether foreseeable or not, compensation for accidents, and compensation for damages to products other than Mitsubishi products.
- (4) Replacement by the user, maintenance of on-site equipment, start-up test run and other tasks.

### **5. Change of Product specifications**

Specifications listed in our catalogs, manuals or technical documents may be changed without notice.

### **6. Application and use of the Product**

- (1) For the use of our AC Servo, its applications should be those that may not result in a serious damage even if any failure or malfunction occurs in AC Servo, and a backup or fail-safe function should operate on an external system to AC Servo when any failure or malfunction occurs.
- (2) Our AC Servo is designed and manufactured as a general purpose product for use at general industries. Therefore, applications substantially influential on the public interest for such as atomic power plants and other power plants of electric power companies, and also which require a special quality assurance system, including applications for railway companies and government or public offices are not recommended, and we assume no responsibility for any failure caused by these applications when used.

In addition, applications which may be substantially influential to human lives or properties for such as airlines, medical treatments, railway service, incineration and fuel systems, man-operated material handling equipment, entertainment machines, safety machines, etc. are not recommended, and we assume no responsibility for any failure caused by these applications when used. We will review the acceptability of the abovementioned applications, if you agree not to require a specific quality for a specific application. Please contact us for consultation.

# TRADEMARKS

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SH(NA)-030316ENG-D(2512)MEE

MODEL:

MODEL CODE:

## **mitsubishi electric corporation**

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NAGOYA WORKS : 1-14, YADA-MINAMI 5-CHOME, HIGASHI-KU, NAGOYA, JAPAN

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