Mitsubishi Electric Servo System Family Catalog
Leading the World with the industry's Top Class Technology
GLOBAL IMPACT OF MITSUBISHI ELECTRIC

Changes for the Better

We bring together the best minds to create the best technologies. At Mitsubishi Electric, we understand that technology is the driving force of change in our lives. By bringing greater comfort to daily life, maximizing the efficiency of businesses and keeping things running across society, we integrate technology and innovation to bring changes for the better.

Mitsubishi Electric is involved in many areas including the following:

**Energy and Electric Systems**
A wide range of power and electrical products from generators to large-scale displays.

**Electronic Devices**
A wide portfolio of cutting-edge semiconductor devices for systems and products.

**Home Appliance**
Dependable consumer products like air conditioners and home entertainment systems.

**Information and Communication Systems**
Commercial and consumer-centric equipment, products and systems.

**Industrial Automation Systems**
Maximizing productivity and efficiency with cutting-edge automation technology.
# OVERVIEW

## Contents

<table>
<thead>
<tr>
<th>Section</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Servo Application Examples</td>
<td>4</td>
</tr>
<tr>
<td>Product Lines</td>
<td>6</td>
</tr>
<tr>
<td>Controllers</td>
<td>8</td>
</tr>
<tr>
<td>Servo Amplifiers</td>
<td>12</td>
</tr>
<tr>
<td>Servo Motors</td>
<td>22</td>
</tr>
<tr>
<td>Engineering Software</td>
<td>26</td>
</tr>
<tr>
<td>Networks</td>
<td>30</td>
</tr>
<tr>
<td>Controller Selection Guide</td>
<td>34</td>
</tr>
<tr>
<td>Solutions</td>
<td>42</td>
</tr>
<tr>
<td>Production System/R&amp;D</td>
<td>44</td>
</tr>
<tr>
<td>History of Mitsubishi Electric Servo System</td>
<td>48</td>
</tr>
<tr>
<td>Support</td>
<td>50</td>
</tr>
<tr>
<td>Warranty</td>
<td>52</td>
</tr>
</tbody>
</table>

## Related Catalogs

Refer to the following catalogs for details:

- **Mitsubishi Electric Servo System Controllers**
  - MELSEC iQ-R/MELSEC iQ-F series catalog
    - L(NA)/03100
- **Mitsubishi Electric General-Purpose AC Servo**
  - MELSERVO-J4 catalog
    - L(NA)/03058
- **MELSEC iQ-R Series**
  - IQ Platform-compatible PAC catalog
    - L(NA)/08298ENG
- **MELSEC iQ-F Series**
  - MELSEC iQ-F Series catalog
    - L(NA)/08428ENG
- **Ethernet-based Open Network CC-Link IE Product Catalog**
  - L(NA)/08111E
Servo Application Examples

Industry leading performance MELSERVO supports various system configurations. Going beyond servo amplifiers and servo motors, Mitsubishi Electric offers system level solutions that include programmable controllers, Motion controllers, and networks to satisfy a broad scope of needs.

Automotive manufacturing

Improve productivity and realize flexibility in different automotive assembly lines with high-accuracy motion control, including linear/circular interpolation and electric cam profile.

Material handling

Realize advanced logistics coordination and eliminate errors in repetitive processes. Servo-based high-speed material handling and highly accurate positioning improve productivity and reduce energy consumption.

Food processing machines

Realize improvements in various packaging applications such as high-speed filling, which requires a highly accurate, continuous feed rate and precision.

Semiconductor manufacturing equipment

In today's semiconductor manufacturing process, wafer diameter is getting larger and components smaller. To meet the requirements of higher quality and productivity, Mitsubishi Electric's high-performance servos and high-resolution encoder achieve fast and accurate positioning at stable speeds.
Mounters

Flexible mounting of electronic components with high speed and density is demanded in printed circuit board applications. Mitsubishi Electric offers a high level of servo system solutions for rapid mounting of highly miniaturized components and for flexible mounting of irregular shapes.

FPD manufacturing systems

In addition to the high-speed and high-accuracy positioning control, linear servos and a broad array of other actuators play important roles in the manufacturing of constantly evolving flat panel displays.

Printing machines

Mitsubishi Electric provides high-accuracy synchronous system solutions for the paper feeding, printing, cutting, and assembly functions within the printing process, achieving high-speed and high-quality converting applications.

Injection molding machines

The integrated system with the advanced motion control supports high-accuracy molding in injection molding machines, which consist of various control sections.

Machine tools

High-performance servos enable fast and accurate positioning, and support high-speed handling of works. We promote the sophisticated machining capabilities that are a key part of the world's most advanced manufacturing.
Mitsubishi Electric Servo System

Our Total Solution for Your Satisfaction
As the leading supplier of automation products and solutions worldwide, Mitsubishi Electric, known for its high quality and diverse range of automation products including servo system controllers, servo amplifiers, and servo motors, together with our exclusive engineering software and various networks including “CC-Link IE Field Network” and “SSCNET III/H”, boasts a whole range of solutions specific to your needs.

Product Lines

**Controllers**
- MELSEC iQ-R series
- MELSEC Q series
- MELSEC-L series
- MELSEC iQ-F series
- MELSEC-F series

**Programmable controller**

**Master/local module**
- CC-Link IE Field Network
  - RJ71GF11-T2
  - QJ71GF11-T2

**Simple Motion module**
- SSCNET III/H
  - RD77GF
  - QQ77GF

**C controller interface module**
- SSCNET III/H
  - Q173SCCF

**Interface**

**CC-Link IE Field Network**
- MR-J4-GF
- MR-JE-C

**CC-Link IE Field Network Basic**
- MR-J4B-MR-J4W2-B/MR-J4W3-B

**SSCNET III/H**
- MR-JE-B

**Servo Amplifiers**
- MR-J4-GF
- MR-JE-C
- MR-J4B-MR-J4W2-B/MR-J4W3-B

**Sensing Modules**
- MR-J4-A(-RJ)
- SSCNET III/H compatible servo amplifier
- MR-J4A(-RJ)

**Servo Motors**
- Medium capacity, medium inertia
  - HG-MR series
  - Capacity: 0.5 to 7 kW
- Medium capacity, ultra-low inertia
  - HG-SR series
  - Capacity: 0.5 to 7 kW
- Ultra compact, ultra-small capacity
  - HG-AK series
  - Capacity: 10 to 30 W
- Medium capacity, ultra-low inertia
  - HG-RR series
  - Capacity: 1 to 5 kW
- Available in the future
  - Large capacity, ultra-low inertia
  - HG-RR series
  - Capacity: 11 to 22 kW
Sensing Modules
Servo Amplifiers
Servo Motors
Controllers

MELSEC iQ-R series
servo amplifier
CC-Link IE Field
MR-J4-GF(-RJ)

Field Network
CC-Link IE
QJ71GF11-T2
RJ71GF11-T2

Capacity: 0.75 to 5 kW
flat type
Medium capacity,
Capacity: 0.5 to 55 kW
Capacity: 1 to 5 kW
series
low inertia
Medium/large capacity,
Capacity: 50 to 750 W
Capacity: 50 to 750 W
Capacity: 0.5 to 7 kW
series
low inertia
Small capacity,
HG-RR
HG-MR

Programmable controller
Simple Motion module

HG-JR
HG-AK

capacity,
Capacity: 10 to 30 W
ultra-small capacity
Ultra-compact,
series
ultra-low inertia

MELSEC iQ-F series

Low-Voltage Switchgear

Graphic Operation Terminal
Personal computer

GOT2000 series

Software

Motion Controller
Personal computer embedded type
Positioning module

SSCNET III/H

Solution
e-F@ctory is the Mitsubishi Electric solution for improving the performance of any manufacturing enterprise by enhancing productivity, and reducing the maintenance and operation costs together with seamless information flow throughout the plant.

Mitsubishi Electric’s integrated FA platform for achieving lateral integration of controllers &HMI, engineering environments and networks at production sites.

SSCNET III/H

Pulse train input/
Positioning function

Graphic Operation Terminal
Personal computer

GOT2000 series

Motion Controller
Personal computer embedded type
Positioning module

SSCNET III/H

Power regeneration converter
+ SSCNET III/H compatible drive unit
MR-CV+MR-J4-DU_B(-RJ)

MR-JE-B does not support the Motion controllers.

Sensing module

MR-JE-A

Linear servo motor for MR-J4

Direct drive motor for MR-J4

Rotary servo motor for MR-JE

Core type
LM-H3 series
Rating: 70 to 960 N
Core type (natural/liquid cooling)
LM-F series
Rating: 300 to 3000 N (natural cooling)
Rating: 600 to 6000 N (liquid cooling)
Core type with magnetic attraction counter-force
LM-K2 series
Rating: 120 to 2400 N
Coreless type
LM-U2 series
Rating: 50 to 800 N

Low-profile flange type
TM-RG2M series
Rating: 2.2 to 9 N m
Low-profile table type
TM-RU2M series
Rating: 2.2 to 9 N m
High rigidity
TM-RFM series
Rating: 2 to 240 N m

Small capacity, low inertia
HG-KN series
Capacity: 100 to 750 W
Medium capacity,
HG-SN series
Capacity: 0.5 to 3 kW
Controllers

From simple positioning to multi-axis and high-speed systems

Our extensive product lines cover from Positioning modules, which enables positioning with simple programs, to Simple Motion modules and Motion controllers, which enable advanced control.

MELSEC iQ-R series

The MELSEC iQ-R series is equipped with the new, high-speed system bus, achieving a shorter cycle time.

Simple Motion module

RD77GF

The RD77GF is a CC-Link IE Field Network compatible Simple Motion module which combines the versatility of Ethernet and highly accurate synchronous operation for Motion control.

The module easily performs various control, such as synchronous, cam, and speed-torque control using only sequence programs.

<table>
<thead>
<tr>
<th></th>
<th>RD77GF4</th>
<th>RD77GF8</th>
<th>RD77GF16</th>
<th>RD77GF32</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of control axes</td>
<td>Up to 4 axes</td>
<td>Up to 8 axes</td>
<td>Up to 16 axes</td>
<td>Up to 32 axes</td>
</tr>
<tr>
<td>Operation cycle</td>
<td>0.5 ms or longer</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Servo amplifier</td>
<td>MR-J4-GF(-RJ)</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Command interface</td>
<td>CC-Link IE Field Network</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Simple Motion module

RD77MS

The RD77MS is an intelligent function module which easily performs various control, such as positioning, synchronous, cam, and speed-torque (tightening & press-fit) control using only sequence programs.

<table>
<thead>
<tr>
<th></th>
<th>RD77MS2</th>
<th>RD77MS4</th>
<th>RD77MS8</th>
<th>RD77MS16</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of control axes</td>
<td>Up to 2 axes</td>
<td>Up to 4 axes</td>
<td>Up to 8 axes</td>
<td>Up to 16 axes</td>
</tr>
<tr>
<td>Operation cycle</td>
<td>0.444 ms or longer</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Servo amplifier</td>
<td>MR-J4-Bi(-RJ)/MR-J4W_-B</td>
<td>MR-J4-B</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Command interface</td>
<td>SSCNET III/H</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Motion controller

RnMTCPU

The RnMTCPU is a CPU module which performs control using the Motion SFC program, independently of a PLC CPU.

The controller performs various advanced Motion control, such as positioning, speed, torque, tightening & press-fit, synchronous, and cam control.

Add-on libraries can be additionally installed to the Motion controller to expand its functionality.

With "G-code control add-on library" (not free of charge), the Motion controller can use G-code programs to control a processing machine using general-purpose AC servo. With an add-on library "machine library" (free of charge), the controller can control a simplified robot (link configuration).

<table>
<thead>
<tr>
<th></th>
<th>R16MTCPU</th>
<th>R32MTCPU</th>
<th>R64MTCPU</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of control axes</td>
<td>Up to 16 axes</td>
<td>Up to 32 axes</td>
<td>Up to 64 axes</td>
</tr>
<tr>
<td>Operation cycle</td>
<td>0.222 ms or longer</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Servo amplifier</td>
<td>MR-J4-Bi(-RJ)/MR-J4W_-B</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Command interface</td>
<td>SSCNET III/H</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Positioning module

RD75P/RD75D

The RD75P/RD75D are capable of controlling up to four axes with a high-speed pulse output (5 Mpulses/s at fastest). The RD75P and the RD75D are compatible with the transistor output and the differential driver output respectively.

*1. This speed is applicable when a differential driver output type is used. The speed depends on the specifications of servo amplifiers.

<table>
<thead>
<tr>
<th>Number of control axes</th>
<th>RD75P2</th>
<th>RD75P4</th>
<th>RD75D2</th>
<th>RD75D4</th>
</tr>
</thead>
<tbody>
<tr>
<td>Start time</td>
<td>0.3 ms or longer</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Servo amplifier</td>
<td>MR-J4-A(-RJ)</td>
<td>MR-JE-A/MR-JE-C</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Command interface</td>
<td>Pulse train (transistor output)</td>
<td>Pulse train (differential driver output)</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

MELSEC-Q series

A variety of MELSEC-Q series controllers fully meets the control needs in each industry and field.

Simple Motion module

QD77GF

The QD77GF is a CC-Link IE Field Network compatible Simple Motion module which combines the versatility of Ethernet and highly accurate synchronous operation for Motion control.

QD77GF4: 4 axes
QD77GF8: 8 axes
QD77GF16: 16 axes

Motion controller

Q17nDSCPU

The Q17nDSCPU is a CPU module used with a PLC CPU for Motion control.

Q172DSCPU: 16 axes
Q173DSCPU: 32 axes

Positioning module

QD75PN/QD75DN

The QD75PN/QD75DN are pulse train output compatible modules. The QD75PN is for transistor output, and the QD75DN is for differential driver output.

QD75P1N/QD75D1N: 1 axis
QD75P2N/QD75D2N: 2 axes
QD75P4N/QD75D4N: 4 axes

Simple Motion module

QD77MS

The QD77MS is simple to use just like Positioning modules while capable of performing various control, such as positioning, synchronous, cam, and speed-torque control (tightening & press-fit) using only sequence programs.

QD77MS2: 2 axes
QD77MS4: 4 axes
QD77MS16: 16 axes

Stand-alone Motion controller

Q170MSCPU

The Q170MSCPU is an all-in-one controller integrating a power supply, a PLC, and a Motion controller.

Q170MSCPU: 16 axes (Equivalent to Q03UDCPU)
Q170MSCPU-S1: 16 axes (Equivalent to Q06UDHCPU)

Positioning module

QD70P/QD70D

The QD70P/QD70D are pulse train output compatible modules. These modules are suitable for driving stepping motors because they enable smooth acceleration/deceleration with gradual speed change.

QD70P4/QD70D4: 4 axes
QD70P8/QD70D8: 8 axes
Controllers

MELSEC iQ-F series

From stand-alone use to networked system applications, the MELSEC iQ-F series brings your business to the next level of industry.

Simple Motion module

FX5-40SSC-S/FX5-80SSC-S

The FX5-40SSC-S/FX5-80SSC-S are next-generation, compact servo system controllers with extensive built-in functions. These modules easily perform various control, such as synchronous, cam, and speed-torque control (tightening & press-fit) using only sequence programs.

<table>
<thead>
<tr>
<th>Number of control axes</th>
<th>FX5-40SSC-S</th>
<th>FX5-80SSC-S</th>
</tr>
</thead>
<tbody>
<tr>
<td>Up to 4 axes</td>
<td></td>
<td>Up to 8 axes</td>
</tr>
<tr>
<td>Servo amplifier</td>
<td>MR-J4-B(-RJ)/MR-J4W_-B</td>
<td>MR-JE-B</td>
</tr>
<tr>
<td>Command Interface</td>
<td>SSCNET III/H</td>
<td></td>
</tr>
</tbody>
</table>

PLC CPU module (built-in positioning function)

FX5U/FX5UC series

The FX5U/FX5UC feature a built-in positioning function with 4-axis pulse output. They can execute positioning by using a positioning instruction and table operation. Together with high-speed pulse I/O modules, control of up to 12 axes is possible.

<table>
<thead>
<tr>
<th>Number of control axes</th>
<th>FX5U/FX5UC series</th>
</tr>
</thead>
<tbody>
<tr>
<td>Up to 4 axes</td>
<td></td>
</tr>
<tr>
<td>Servo amplifier</td>
<td>MR-J4-A(-RJ)/MR-JE-C</td>
</tr>
<tr>
<td>Command Interface</td>
<td>Pulse train (transistor output)</td>
</tr>
</tbody>
</table>

MELSEC-L series

The MELSEC-L series is a baseless highly scalable controller ideal for applications having limited space.

Simple Motion module

LD77MS

The LD77MS is simple to use just like Positioning modules while capable of performing various control, such as positioning, synchronous, cam, and speed-torque (tightening & press-fit) control.

LD77MS2: 2 axes
LD77MS4: 4 axes
LD77MS16: 16 axes

Positioning module

LD75P/LD75D

The LD75P/LD75D are pulse train output compatible modules. The LD75P is for transistor output, and the LD75D is for differential driver output.

LD75P1/LD75D1: 1 axis
LD75P2/LD75D2: 2 axes
LD75P4/LD75D4: 4 axes

SSCNET III/H Head module

LJ72MS15

The SSCNET III/H head module is used to connect the MELSEC-L series I/O module and the intelligent function module to SSCNET III/H.

PLC CPU module (built-in positioning function)

L CPU

The positioning function, equipped as standard, outputs command pulses to a servo amplifier by using the built-in I/O function.

Control axes: 2 axes
MELSEC-F series

Main unit (built-in positioning function)

FX3U/FX3UC
The FX3U and FX3UC feature positioning functionality with pulse outputs, enabling positioning control only with the main unit.
FX3U and FX3UC: 3 axes

Positioning module

FX3U-1PG
This pulse train output block is used with the FX series programmable controller.
FX3U-1PG: 1 axis

Ethernet-based open network CC-Link IE master stations

Servo control is enabled by the Ethernet-based open network CC-Link IE compatible master station. The following are examples of master stations.

Master/local module

RJ71GF11-T2/QJ71GF11-T2
The RJ71GF11-T2/QJ71GF11-T2 are master/local modules supporting CC-Link IE Field Network. With these modules, MR-J4-GF(RJ) can be used in I/O mode for positioning control. RnENCPU and L series master/local module can also be used as a master station.

CPU module

FX5U/FX5UC/RnCPU/RnENCPU
The FX5U/FX5UC/RnCPU/RnENCPU are PLC CPU modules supporting CC-Link IE Field Network Basic. Having a built-in Ethernet port, these CPU modules can be used as a master station. The equivalent CPU modules are also available in Q and L series.

C Controller/Personal computer embedded type servo system controllers

A combination of the board controllers and a personal computer, or the interface module and a C controller enables high-response servo control.

Simple Motion board

MR-EM340GF
Embedded in a personal computer, the MR-EM340GF Simple Motion board controls MR-J4-GF through a user program. The controller supports PCI Express®. Control axes in motion mode: 16 axes Control stations in I/O mode: 120 stations

Position Board

MR-MC series
Embedded in a personal computer, the MR-MC series Position Boards control MR-J4-B through a user program. The controllers support PCI Express®, PCI bus, and Compact PCI®. MR-MC2_0: 20 axes MR-MC2_1: 32 axes MR-MC341: 64 axes

C Controller Interface Module

Q173SCCF
Connected directly to a C Controller via PCI Express®, the Q173SCCF controls MR-J4-B through a user program. Q173SCCF: 20 axes
Servo Amplifiers

From the industry's top level high-speed, high-accuracy servos to one-touch servos and multi-axis models. In addition to the high-end MELSERVO-J4 series, a variety of models to match various applications is available. The Mitsubishi Electric's servo amplifiers support motors from rotary servo motors to linear servo motors and direct drive motors, and greatly enhance system performance.

~Man, Machine and Environment in Perfect Harmony~

MELSERVO-J4 series

MELSERVO-J4 series is the leading member of the MELSERVO family, backed by Mitsubishi Electric's leadership in all-digital technology. With safety, Ethernet-based CC-Link IE Field Network, SSCNET III/H high-speed optical communication and energy-efficient design of the MELSERVO-J4 series - man, machine and environment can at last work together in perfect harmony.

MR-J4-GF(-RJ)
CC-Link IE Field Network compatible servo amplifier

This servo amplifier is compatible with CC-Link IE Field Network. Together with the Simple Motion module, advanced synchronous control and interpolation control by sequential commands are enabled. The servo amplifier has a built-in point table function (point table method/indexer method), offering easy positioning with a combination with a master module. The servo amplifier also supports CC-Link IE Field Network Basic.

Command interface | CC-Link IE Field Network
--- | ---
Control mode | Position/Speed/Torque/Fully closed loop
Power supply | 100 V AC 200 V AC 400 V AC
Capacity range | 0.1 kW to 0.4 kW 0.1 kW to 22 kW 0.6 kW to 22 kW
Compatible servo motor | Rotary servo motor, linear servo motor, DD motor

MR-J4-B(-RJ)
MR-J4W2-B/MR-J4W3-B
SSCNET III/H compatible servo amplifier

A complete synchronous system with SSCNET III/H can be configured using 0.222 ms cycle high-speed serial communication between the controller and the servo amplifier. 2-axis/3-axis servo amplifiers are also available, enabling energy-saving, less-wiring, compact machine at lower cost.

Command interface | SSCNET III/H
--- | ---
Control mode | Position/Speed/Torque/Fully closed loop
Power supply | 100 V AC 200 V AC 400 V AC
Capacity range | 0.1 kW to 0.4 kW 0.1 kW to 37 kW 0.6 kW to 55 kW
Compatible servo motor | Rotary servo motor, linear servo motor, DD motor

MR-J4-A(-RJ)
General-purpose interface compatible servo amplifier

Pulse train and analog input, etc., are provided as a standard for the command interface. Position, speed, and torque control modes are available, and the modes can be switched with an input device. The MR-J4-A-RJ has a built-in positioning function, supporting MODBUS® RTU, simple cam, and mark sensor input compensation.

Command interface | Pulse train/Analog voltage/RS-422/MODBUS® RTU
--- | ---
Control mode | Position/Speed/Torque/Fully closed loop
Power supply | 100 V AC 200 V AC 400 V AC
Capacity range | 0.1 kW to 0.4 kW 0.1 kW to 37 kW 0.6 kW to 55 kW
Compatible servo motor | Rotary servo motor, linear servo motor, DD motor

MR-J4W2-0303B6
MR-J4-03A6(-RJ)
Ultra-small capacity servo amplifier

This servo amplifier is compatible with the ultra-compact HG-AK servo motor series (10 W to 30 W) and two types of main circuit power supply of 48 V DC and 24 V DC, being suitable for compact machines. 2-axis servo amplifiers are also available.

Command interface | SSCNET III/H or Pulse train/Analog voltage/RS-422
--- | ---
Control mode | Position/Speed/Torque
Power supply | 48 V DC/24 V DC
Capacity range | 10 W to 30 W
Compatible servo motor | Rotary servo motor

4 Servo Amplifiers
Harmony with Machine
The leading edge in drive control, with unrivaled accuracy and response for next-generation machine performance.

Industry-Leading Level of Servo Amplifier Basic Performance

Speed frequency response of 2.5 kHz is achieved by applying our original high-speed servo control architecture evolved from the conventional two-degrees-of-freedom model adaptive control to the dedicated execution engine. Together with a high-resolution absolute position encoder of 4,194,304 pulses/rev, fast and accurate operation is enabled. The performance of the high-end machines is utilized to the fullest.

One-Touch Tuning
Just turn on the one-touch tuning function to complete servo gain adjustment automatically, including machine resonance suppression filter, advanced vibration suppression control II\(^1\), and robust filter for maximizing your machine performance. This function also sets responsivity automatically, while the real-time auto tuning requires manual setting. Moreover, a new method\(^2\) allows to create an optimum tuning command inside the servo amplifier.

Advanced Vibration Suppression Control II
The advanced vibration suppression control II suppresses two types of low-frequency vibrations, owing to vibration suppression algorithm which supports three-inertia system. This function is effective in suppressing residual vibration with relatively low frequency of approximately 100 Hz or less generated at the end of an arm and in a machine, enabling a shorter settling time.

Application examples
- [Pick and place robots]
- [Automatic assembly equipment]
- [Material handling systems]
Robust Filter

Achieving both high responsivity and stability was difficult with the conventional control in high-inertia systems with belts and gears such as printing and packaging machines. Now, this function enables the high responsivity and the stability at the same time without adjustment. The robust filter gradually reduces the fluctuation of torque in a wide frequency range and achieves more stability as compared to the prior model.

Gain  
Conventional low-pass filter  
Robust filter  
Frequency  
Conventional control  
With robust filter

Application examples
[Printing machines]  
[Packaging machines]

Expanded Machine Resonance Suppression Filter

With advanced filter structure, applicable frequency range is expanded from between 100 Hz and 4500 Hz to between 10 Hz and 4500 Hz. Additionally, the number of simultaneously applicable filters is increased from two to five, improving vibration suppression performance of a machine.

Lost Motion Compensation Function

This function suppresses quadrant protrusion caused by friction and torsion generated when the servo motor rotates in a reverse direction. Therefore, the accuracy of circular path will be improved in trajectory control used in XY table, etc.

* This function is not supported by MR-J4W2-B and MR-J4W3-B.

Suppression of quadrant protrusion of circular trajectory
Built-in Positioning Function

MR-J4-GF(-RJ) and MR-J4-A-RJ have a built-in positioning function, enabling positioning operation with point table, program-based*, and indexer methods. With these servo amplifiers, a positioning system is configured without a Positioning module (command pulse). Positioning command is executed by CC-Link IE Field network, input/output signals, or RS-422/RS-485 communication (up to 32 axes).

MR Configurator2 allows easy setting of the positioning data.

* The program-based method is supported only by MR-J4-A-RJ.

Point table method*  
Set position data (target position), servo motor speed, and acceleration/deceleration time constants in point table. Up to 255 points can be set in the point table, and setting the data is as easy as setting parameters. Perform positioning operation with a start signal after selecting the point table Nos.

For MR-J4-A-RJ, point table can be set with push buttons on the servo amplifier or with MR-PRU03 parameter unit.

<table>
<thead>
<tr>
<th>Point table example</th>
</tr>
</thead>
<tbody>
<tr>
<td>No.</td>
</tr>
<tr>
<td>-----</td>
</tr>
<tr>
<td>1</td>
</tr>
<tr>
<td>2</td>
</tr>
<tr>
<td>255</td>
</tr>
</tbody>
</table>

Program example

Program Nos. 256 programs max

Program example

<table>
<thead>
<tr>
<th>Program No. 1</th>
</tr>
</thead>
<tbody>
<tr>
<td>SPN(3000)</td>
</tr>
<tr>
<td>STC(20)</td>
</tr>
<tr>
<td>MOV(1000)</td>
</tr>
<tr>
<td>TIM(100)</td>
</tr>
<tr>
<td>FOR(3) (1)</td>
</tr>
<tr>
<td>MOVI(100)</td>
</tr>
<tr>
<td>TIM(100)</td>
</tr>
<tr>
<td>NEXT STOP</td>
</tr>
</tbody>
</table>

Indexer method*  
Perform positioning operation by specifying equally divided stations (up to 255 stations) and the number of gear teeth on machine and motor sides. The travel distance will be calculated automatically based on the number of equally divided stations set in the parameter. The positioning operation is performed with a start signal after the station position No. is selected. Rotation direction specifying indexer or shortest rotating indexer can be set.

* Fully closed loop control mode and linear servo motor control mode are not supported by the indexer method.
Harmony with Man

The leading edge in safety and convenience, designed to harmonize with the way you work.

Functions Compliant with IEC/EN 61800-5-2

STO (Safe torque off) and SS1*1 (Safe stop 1) are integrated as standard, enabling the safety system to be configured easily in a machine.

- By using STO, it is not necessary to turn off the control power of the servo amplifier, resulting in a shorter restart time and eliminating the necessity of home position return.
- A magnetic contactor for preventing unexpected motor start is not needed.*2
- The safety level of STO is increased to SIL 3 from SIL 2. *3

<table>
<thead>
<tr>
<th>IEC/EN 61800-5-2:2007 function</th>
<th>Safety level</th>
</tr>
</thead>
<tbody>
<tr>
<td>STO (Safe torque off)</td>
<td>Category 3 PL e, SIL 3</td>
</tr>
<tr>
<td>SS1 (Safe stop 1)</td>
<td>Category 3 PL e, SIL 3</td>
</tr>
</tbody>
</table>

*1. Safety equipment (MR-J3-D05, safety programmable controller MELSEC QS/WS series, etc.) is required.
*2. For MR-J4 series servo amplifier, magnetic contactors are not required to meet the STO requirements. However, this illustration has a magnetic contactor installed to prevent servo alarms and electric shock.
*3. For Category 3 PL e, SIL 3, use compatible safety equipment and set the parameters. When MR-J3-D05 is used, safety level is Category 3 PL d, SIL 2.

Category 4 PL e, SIL 3 with functional safety unit

Safety level is Category 4 PL e, SIL 3 when the safety signals are inputted directly to MR-D30 functional safety unit or through safety communication to the servo amplifier. The safety observation function is operated on the MR-D30, and therefore expansion of the safety observation function is possible independent of controllers.

Servo motors with functional safety are now available.
(HG-KR_W0C/HG-SR_W0C/HG-JR_W0C)

Safety level is Category 4 PL e, SIL 3 when the safety signals are inputted directly to MR-D30 functional safety unit or through safety communication to the servo amplifier. The safety observation function is operated on the MR-D30, and therefore expansion of the safety observation function is possible independent of controllers.

Servo motors with functional safety are now available.
(HG-KR_W0C/HG-SR_W0C/HG-JR_W0C)
**Tough Drive Function**

**Instantaneous power failure tough drive**
When an instantaneous power failure is detected, this function allows the servo amplifier to use the electric energy charged in the main circuit capacitor in the servo amplifier to avoid an alarm occurrence, increasing the machine availability even with an unstable power supply.

**Vibration tough drive**
Machine resonance suppression filter is automatically readjusted when a change in machine resonance frequency is detected by the servo amplifier, reducing unplanned machine downtime caused by age-related degradation.

---

**Large Capacity Drive Recorder**

Servo data such as motor current and position command before and after the alarm occurrence are stored in non-volatile memory of the servo amplifier. Reading the servo data on MR Configurator2 helps you analyze the cause of the alarm.

---

**Machine Diagnosis Function**

This function detects changes in mechanical parts (ball screw, guide, bearing, belt, etc.) by analyzing changes in machine friction, load moment of inertia, unbalanced torque, and vibration components from the data inside a servo amplifier, supporting timely maintenance of these parts. The following failure prediction functions are available with MR-J4-GF and notify the maintenance timing.

- Friction failure prediction function
- Vibration failure prediction function
- Total distance failure prediction function
Harmony with the Environment

An evolution in eco-friendly design, and that’s winning acclaim worldwide.

2-axis/3-axis Types for Energy-Saving, Miniaturized, and Low-Cost Machine

2-axis and 3-axis servo amplifiers are available for operating two and three servo motors, respectively. These servo amplifiers enable energy-saving, compact machine at lower cost. Different types of servo motors including rotary servo motors, linear servo motors, and direct drive motors are freely combined as long as the servo motors are compatible with the servo amplifier.

Space-Saving with Industry’s Smallest* 3-axis Type

2-axis servo amplifier MR-J4W2-B requires 26% less installation space than two units of MR-J4-B. 3-axis servo amplifier MR-J4W3-B requires 30% less installation space than three units of MR-J4-B.

Reduced Wiring by Approx. 50% with 3-axis Type

The three axes of 3-axis servo amplifier MR-J4W3-B use the same connections for main and control circuit power, peripheral equipment, control signal wire, etc. Thus, the number of wirings and devices is greatly reduced.

* Based on Mitsubishi Electric research as of August 2018
Energy-Conservation with Common DC Bus Connection

When multiple servo amplifiers and drive units are connected to the MR-CV power regeneration converter unit by a common DC bus connection, the regenerative energy of one axis is used for driving other axes, contributing to energy-conservation. The multi-axis servo amplifier has the same effect.

Further Energy-Conservation with Power Regeneration System

The MR-CV power regeneration converter unit has a power regeneration system which returns the regenerative energy back to the power supply, enabling the regenerative energy to be used for other systems for further energy-conservation. In addition, when the MR-CV power regeneration converter unit is used, a regenerative option is not required, and thus, the total heat generation in a system will be decreased.

System Configuration Examples

SSCNET III/H compatible Motion controller
3-phase power supply
AC reactor MR-AL
Power regeneration converter unit MR-CV
Drive unit MR-J4-DU_B
Common DC bus connection
Servo amplifier MR-J4-B
Continuous regenerative axis MR-J4-DU_B
Roller axis MR-J4-B
Continuous driving axis MR-J4-DU_B

Less heat generation due to elimination of regenerative option
Non-reusable power is returned to the power supply and used as the power for other system.
Heritage
A heritage of trust and continuity — the hallmark of every MELSERVO product.

Easy Replacement of MR-J3 Series

MR-J4-B/MR-J4-A has the same mounting dimensions\(^1\) with MR-J3-B/MR-J3-A. HG rotary servo motor series has the same mounting dimensions\(^2\) and uses the same option cables for the power, the encoder\(^3\), and the electromagnetic brake as HF series or HC-RP/HC-UP series.

\(^1\) Mounting dimensions are smaller for servo amplifiers rated 200 V 5 kW, 400 V 3.5 kW, 200 V/400 V 11 kW, and 200 V/400 V 15 kW.
\(^2\) For replacing HA-LP series with HG-JR series, contact your local sales office for more detail.
\(^3\) HG-JR series of 11 kW to 55 kW uses a different encoder cable from HF-JP series.

Supporting Replacement of MR-J2-Super Series

MELSERVO-J4 series product lines include general-purpose interface, positioning function, and SSCNET III/H interface. MELSERVO-J4 series is compatible with a wide variety of command interface and also replaceable from MELSERVO-J2S series.

We provide support for the renewal with the following materials from the catalog of renewal introduction, the handbook with detailed information to the instruction manual for the renewal tool to use the existing wiring.

Transition from MELSERVO-J3/J3W Series to J4 Series Handbook
L(NA)03127
This handbook explains how to replace your MR-J3/J3W with MR-J4 series.

Transition from MELSERVO-J2-Super/J2M Series to J4 Series Handbook
L(NA)03093
This handbook explains how to replace your MR-J2S/J2M with MR-J4 series.

MR-J2S Renewal Tool Catalog
X901307-312
This guide introduces a renewal tool for replacing MR-J2S with MR-J4. The renewal tool allows to use the existing wiring and mounting holes, making the replacement simple and fast.

Mitsubishi Electric System & Service Co., Ltd.
~Reliable Basic Performance and Advanced Ease-of-Use~

MELSERVO-JE series

[Easy To Use]
- One-touch tuning adjusts servo gains with one-touch ease.
- Instantaneous power failure tough drive function and a large capacity capacitor reduce machine downtime.
- MR-JE-C and MR-JE-B support absolute position detection system.
- MR-JE-C and MR-JE-A have a built-in positioning function. MR-JE-A is equipped with advanced functions such as simple cam and position compensation.

[High Performance]
- MR-JE series is compatible with various networks including CC-Link IE Field Network Basic, SSCNET III/H, and MODBUS®.
- The dedicated engine enables speed frequency response of 2.0 kHz, shortening the cycle time.
- The large capacity main circuit capacitor allows the regenerative energy to be used effectively.

[Global Standard]
- Global servo, MR-JE series, complies with global standards as standard.
- Command pulse input and digital input/output are compatible with both sink and source type connections.

MR-JE-C
Ethernet compatible servo amplifier

MR-JE-C supports Ethernet communication (CC-Link IE Field Network Basic, SLMP, and MODBUS®/TCP) and RS-485 communication (MODBUS® RTU), and enables a flexible system configuration. In addition, the MR-JE-C has a built-in positioning function (point table method and indexer method), making positioning operation easy without a Positioning module.

Control interface: CC-Link IE Field Network Basic, SLMP, and MODBUS®/TCP
Control mode: Position/Speed/Torque
Power supply: 200 V AC
Capacity range: 0.1 kW to 3 kW
Compatible servo motor: Rotary servo motor

MR-JE-B
SSCNET III/H compatible servo amplifier

MR-JE-B is compatible with SSCNET III/H, optical servo system controller network that enables a high-response and multi-axis system with high synchronous performance and less wiring. In addition, absolute position detection system can be configured easily with the MR-JE-B servo amplifiers.

Control interface: SSCNET III/H
Control mode: Position/Speed/Torque
Power supply: 200 V AC
Capacity range: 0.1 kW to 3 kW
Compatible servo motor: Rotary servo motor

MR-JE-A
General-purpose interface compatible servo amplifier

Pulse train and analog input, etc., are provided as a standard for the command interface. Position, speed, and torque control modes are available, and the modes can be switched with an input device. The MR-JE-A has a built-in positioning function, being compatible with MODBUS®, simple cam, and mark sensor input compensation.

Control interface: Pulse train/Analog/RS-422/MODBUS® RTU
Control mode: Position/Speed/Torque
Power supply: 200 V AC
Capacity range: 0.1 kW to 3 kW
Compatible servo motor: Rotary servo motor
**Servo Motors**

**From rotary to linear and direct drive motors**
Rotary servo motors are available in capacities from 10 W to 220 kW. Linear servo motors and direct drive motors satisfy new needs in driving control by providing high rigidity, performance and flexibility in system configurations unique to a direct drive.

Rotary servo motor: A wide range of capacities and series for various system applications

### HG series for MELSERVO-J4 series

#### HG-KR/HG-MR
Capacity: 50 W to 750 W
Rated speed: 3000 r/min, Maximum speed: 6000 r/min
[Application example]
- Inserters, mounters and bonders
- PCB drilling machines
- In-circuit testers and label printers
- Knitting and embroidery machines
- Compact robots and robot hand sections

#### HG-SR
Medium capacity, medium inertia. Suitable for machines having large load inertia.
Capacity: 0.5 kW to 7 kW
Rated speed: 1000 r/min and 2000 r/min
[Application example]
- Material handling systems
- Dedicated machines
- Robots
- Loaders and unloaders
- Winders and tension units
- Turrets
- X-Y tables

#### HG-JR
Medium to ultra-large capacity, low inertia. Perfect for high-throughput positioning or high acceleration/deceleration operations.
Capacity: 0.5 kW to 220 kW
Rated speed: 1000 r/min, 1500 r/min, 2000 r/min, and 3000 r/min
[Application example]
- Food packaging machines
- Printers
- Injection molding machines
- Press machines

#### HG-AK
Ultra-compact, ultra-small capacity with flange size of 25 mm. Suitable for small machines.
Capacity: 10 W to 30 W
Rated speed: 3000 r/min, Maximum speed: 6000 r/min
[Application example]
- Mounters and bonders
- Semiconductor/FPD manufacturing systems
- Compact robots
- Electronic component manufacturing machines
- Compact X-Y table

#### HG-RR
Medium capacity, ultra-low inertia. Perfect for high-throughput operation.
Capacity: 1 kW to 22 kW*
Rated speed: 1500 r/min and 3000 r/min
[Application example]
- Roll feeders
- Loaders and unloaders
- Ultra high-throughput material handling systems
- Vibration testing machines
* HG-RR series with 11 kW, 15 kW, and 22 kW will be available in the future.

#### HG-UR
Medium capacity, flat type. Perfect for applications with limited mounting space.
Capacity: 0.75 kW to 5 kW
Rated speed: 2000 r/min
[Application example]
- Robots
- Conveyors
- Winders and tension machines
- Food processing machines
Equipped with High-Resolution Absolute Position Encoder

Servo motors are equipped with a high-resolution absolute position encoder of 4,194,304 pulses/rev (22-bit) as standard. Positioning accuracy is increased.

* 262,144 pulses/rev (18-bit) for HG-AK series.

Improved Environmental Resistance

Ingress protection\(^2\) of servo motors:
HG-SR/HG-JR: IP67\(^1\)
HG-AK: IP55

\(^1\) HG-JR1000 r/min series 15 kW or larger, HG-JR1500 r/min series 22 kW or larger, and HG-JR 2000 r/min series are rated IP44.

\(^2\) The shaft-through portion is excluded.

Cable Leading Direction

Cables for power, encoder, and electromagnetic brake are capable of connecting either in direction or in opposite direction of the load side, depending on the cable selection. (HG-KR and HG-MR series)

Reduced Torque Ripple during Conduction

The torque ripple is reduced owing to the optimized combination of the numbers of the motor poles and the slots. Thereby, smooth rotation is achieved even during a low-speed operation which is more likely affected by the torque ripple, improving the operation stability.

HG series for MELSERVO-JE series

**HG-KN**
Small capacity, low inertia. Perfect for general-purpose industrial machines.
Capacity: 0.1 kW to 0.75 kW
Rated speed: 3000 r/min
[Application example]
- Inserters, mounters and bonders
- PCB drilling machines
- In-circuit testers and label printers
- Knitting and embroidery machines
- Compact robots and robot hand sections

**HG-SN**
Medium capacity, medium inertia. Suitable for machines having large load inertia.
Capacity: 0.5 kW to 3 kW
Rated speed: 2000 r/min
[Application example]
- Material handling systems
- Dedicated machines
- Robots
- Loaders and unloaders
- Winders, tension units
- Turrets
- X-Y tables
Servo Motors

Linear servo motor: Suitable for linear motion systems requiring high speed and accuracy

**LM series for MELSERVO-J4 series**

**LM-H3**
- Maximum speed: 3 m/s
- Rated thrust: 70 N to 960 N
- Core type suitable for space-saving.
- The magnetic attraction force contributes to high rigidity.

**LM-F**
- Maximum speed: 2 m/s
- Rated thrust: 300 N to 3000 N (natural cooling), 600 N to 6000 N (liquid cooling)
- Core type compact linear servo motor.
- The integrated liquid-cooling system doubles the continuous thrust.
- The magnetic attraction force contributes to high rigidity.

**LM-K2**
- Maximum speed: 2 m/s
- Rated thrust: 120 N to 2400 N
- Core type with magnetic attraction counter-force.
- The magnetic attraction counter-force structure extends life of the linear guides and contributes to lowering audible noise.

**LM-U2**
- Maximum speed: 2 m/s
- Rated thrust: 50 N to 800 N
- Coreless type without cogging resulting in small speed fluctuation.
- The structure with no magnetic attraction force extends life of the linear guides.

**Sophisticated Performance**

Supporting maximum speed of 3 m/s (LM-H3 series) and maximum thrust of 150 N to 18000 N.
Small size and high thrust are achieved by the increased winding density and the optimized core and magnet geometries as a result of electromagnetic field analysis.
Diverse product lines include core, liquid-cooling core, magnetic attraction counter-force core, and coreless types.

A/B/Z-phase differential output type linear encoders are also supported by MR-J4-GF-RJ/MR-J4-B-RJ/MR-J4-A-RJ servo amplifiers.

An advanced system including high-accuracy tandem synchronous control can be configured with CC-Link IE Field Network or SSCNET III/H compatible controller.

**Application Example**

- [Machine tools XYZ stage]
- [Semiconductor/FPD manufacturing systems]
- [Screen printing systems]
Direct drive motor: For compact and simplified machine driving part with high-accuracy control

**TM series for MELSERVO-J4 series**

**TM-RG2M**
- Motor outer diameter: φ130 mm, φ180 mm, and φ230 mm
- Rated torque: 2.2 N·m to 9 N·m
- Low-profile direct drive motor available in two types: flange type (with pilot) and table type (with positioning pin holes)

**TM-RU2M**
- Motor outer diameter: φ130 mm, φ180 mm, φ230 mm, φ330 mm
- Rated torque: 2 N·m to 240 N·m
- High-rigidity direct drive motor for high-torque

**TM-RFM**
- Motor outer diameter: φ130 mm, φ180 mm, φ230 mm, φ330 mm
- Rated torque: 2 N·m to 240 N·m
- High-rigidity direct drive motor for high-torque

### Sophisticated Performance

**[High performance with the latest technologies]**
Our latest magnetic design and winding technologies enable high torque density. In addition, extremely smooth rotation is achieved by the minimized torque ripple.

**[Compact and low-profile design]**
Due to high level of structural design technology, compact and low-profile design is achieved. This design enables a small mounting space and a low center of gravity.

**[High-resolution absolute position encoder]**
The direct drive motor is equipped with a high-resolution absolute position encoder (1,048,576 to 4,194,304 pulses/rev) as standard. High-accuracy machine is achieved.

**[Hollow shaft diameter range: ø20 mm to 104 mm]**
The motor is equipped with a large hollow shaft resulting from using bearing and encoder with large diameter. It allows cables and air tubing to pass through.

### Application Example

Suitable for low speed and high torque applications.

- [Coating and vapor deposition systems]
- [Spin-type cleaning systems for FPD/semiconductor]
- [FPD/semiconductor testing systems (XYθ tables)]
- [Index table for machine tools]
- [Rotary axis for polishing systems]
- [Rotary axis for material handling robots]
**Engineering Software**

**FA Integrated Engineering Software MELSOFT iQ Works**

MELSOFT iQ Works is an integrated software suite consisting of GX Works3, MT Works2, GT Works3, RT ToolBox3, FR Configurator2, MR Configurator2 and CW Configurator, which are programming software for each respective product. Integration is further enhanced with MELSOFT Navigator as the central system configuration incorporating an easy-to-use, graphical user interface with additional project-sharing features such as system labels and parameters. The advantages of this powerful integrated software suite are that system design is made much easier with a substantial reduction in repetitious tasks, cutting down on errors while helping to reduce the overall TCO.

**System management software**
**MELSOFT Navigator**

System level graphic-based configuration tool that simplifies the system design by providing a visual representation of the system. System management features such as system-wide parameterization, labels and block reading of project data are also included.

**Programmable controller engineering software**
**MELSOFT GX Works3**

GX Works3 is the latest generation of programming and maintenance software offered by Mitsubishi Electric specifically designed for the MELSEC iQ-R series control system. It includes many new features such as graphic-based system configuration, integrated motion control setup, multiple language support, providing an intuitive engineering environment solution.

**HMI/GOT screen design software**
**MELSOFT GT Works3**

This graphic operation terminal (GOT) screen creation software is designed with three main features—simplicity, graphics design and operation ease—that help to create graphic screens in fewer steps.

**Motion controller engineering software**
**MELSOFT MT Works2**

This motion control design and maintenance software includes intuitive graphic-based programming together with a digital oscilloscope simulator.

**Servo setup software**
**MELSOFT MR Configurator2**

Tuning, monitor display, diagnosis, reading/writing parameters, and test operations are easily performed on a personal computer. This powerful software tool supports a stable machine system and optimum control, and moreover, shortens setup time.

- Robot engineering software
  **MELSOFT RT ToolBox3**
- Inverter setup software
  **MELSOFT FR Configurator2**
- Controller setting and monitoring tool
  **MELSOFT CW Configurator**
Fully supporting all your needs from model selection, system design, startup to maintenance with diverse software

MELSOFT is the FA integrated engineering software that demonstrates their abilities in various FA scenes including designing, debugging and startup, and operation and maintenance to facilitate all aspects from specification review to daily data collection.

Programmable Controller Engineering Software
MELSOFT GX Works3

Motion Controller Engineering Software
MELSOFT MT Works2

Servo Setup Software
MELSOFT MR Configurator2

All-in-one tool for quick and easy startup
This software supports the engineering process - from creation of a sequence program, parameter settings of the Simple Motion module, and creation of a positioning data table and cam data through startup, debugging, and maintenance.

Comprehensively supporting Motion controller design and maintenance
With features including Motion SFC programming, parameter settings, and the digital oscilloscope function, this software supports the engineering process - from system configuration and programming through debugging and maintenance of the Motion controller.

User-friendly software for easy setup, tuning, and operation
Tuning, monitoring, diagnosis, reading/writing parameters, and test operations are easily performed.

System Design

System configuration
Servo amplifiers and modules are set easily with the graphical system setting screen.

Module configuration
Each parameter is set from the module configuration screen.

Servo data setting
One-point help allows you to set parameters without manuals.

Copying servo data
Copy & paste of the data between axes is easy.
## Programming

### Positioning data setting

Functions, such as Data setting assistant and Automatic calculation of auxiliary arc, simplify the setting input process of positioning data.

### Simulation

Simulation can be executed without an actual machine during the debugging process.

### Programming

User-friendly functions make Motion controller program development easier.

### Synchronous control parameter

The synchronous control parameter is easily set using software instead of controlling mechanically with physical gears, shafts, speed change gears or cams.

### Cam data creation

Various cam patterns are created more freely and flexibly.

### Cam data list

The created cam data are easily viewed as thumbnails.

## Startup and Adjustment

### Monitor

The required items and axes are selected from various monitoring information.

### Digital oscilloscope

Data collection and waveform display which are synchronized with the Motion operation cycle greatly help you check operation and perform troubleshooting.

### Multi-axis adjustment

The multi-axis adjustment function enables easy servo adjustment and quick startup for machines executing multi-axis simultaneous operation, such as a tandem configuration.
Startup and Adjustment of Servo Amplifier

Servo assistant function
Complete setting up the servo amplifier just by following guidance displays.

Parameter setting function
Display parameter setting in list or visual formats, and set parameters by selecting from the drop down list.

Monitor function
Monitor the operation information on the [Display all] window. The power consumption can also be monitored without additional measurement equipment.

One-touch tuning function
With the ease of clicking the start button, adjustments including estimating load to motor inertia ratio, adjusting gain, and suppressing machine resonance are automatically performed for the maximum servo performance.

Tuning function
Adjust control gain finely on the [Tuning] window manually for further performance after the one-touch tuning.

Alarm display
MR-J4 series displays the alarm No. in three digits to show the servo alarm in more details, making troubleshooting easy.

Select the most suitable motor for your machine
Capacity selection software MRJW3-MOTSZ111E

Select the most suitable servo motor, servo amplifier, and regenerative option for your machine just by setting machine specifications and operation pattern.
Select the operation pattern from either position control mode or speed control mode. The capacity selection software is available for free download.
Contact your local sales office for more details.
CC-Link IE Field Network

Ethernet-based open network, CC-Link IE Field Network —
All-rounder network opens up new areas of control
This Ethernet-based open network is designed to simultaneously handle distributed control, I/O control, safety control, and Motion control.

Two Times Faster Operation Cycle
The operation cycle of 0.5 ms, two times faster than the previous model, enables smoother machine control. Smooth control of synchronization, cam control, and S-curve acceleration/deceleration improves the product quality with a shorter cycle time.

Motion Control Achieved
The CC-Link IE Field Network is equipped with Motion function in the cyclic communication bandwidth. Synchronous communication with the servo amplifiers becomes possible, offering high-speed and high-accuracy positioning, synchronous control, and cam control.

Easy Startup
Selecting each field device on the screen of CC-Link IE Field configuration via drag & drop enables easy parameter settings. An addition or a change of field devices are also easily made by modifying the parameters.
All-Rounder Network

CC-Link IE Field Network is an Ethernet-based open network. The highly flexible wiring of CC-Link IE Field enables versatile control from I/O control to Motion control over the single network. Cables and connectors are highly available in the world as CC-Link IE Field Network is based on the Ethernet.

* Up to 32 servo amplifiers (motion mode) are connectable.
Slave stations:
- RD77GF: 120 stations (including the number of servo amplifiers in motion mode)
- QD77GF: 120 stations (16 servo amplifiers in motion mode + 104 I/O devices)

Flexible Network Topology

Star topology

Line topology

- Star, line, and star/line mixed topologies are available for a network configuration by using a switching hub.
- When using star topology, be sure to use the following switching hubs:
  - Intelligent hub: NZ2MHG-T8F2
  - Industrial switching hub: DT135TX (manufactured by Mitsubishi Electric System & Service Co., Ltd.)

Synchronous Communication Function

The operation timings of multiple slave units match since the synchronous communication compatible slave devices operate at the operation cycle of the Simple Motion module.

CC-Link IE Field Network Basic

With recent trends of IoT*, network connection of devices and equipment for small-scale systems is becoming more mainstream. CC-Link IE Field Network Basic realizes easier network integration of Ethernet devices, as its cyclic communications stack is software-based, without requiring a dedicated ASIC helping to reduce implementation costs for device partners.

Transparent communications are achieved by utilizing SLMP® that enables seamless connectivity within all levels of manufacturing.

CC-Link IE Field Network Basic is supported by MR-J4-GF and MR-JE-C.

*1. Internet of Things
*2. Seamless Message Protocol
SSCNET III/H

The blazingly fast speed and response of 150 Mbps full-duplex baud rate

SSCNET III/H is a high-speed servo system controller network employing fiber optic cables, enabling high precision synchronization. The communication cycle as fast as 0.222 ms increases responsivity and reduces cycle time of machine. The dedicated fiber optic cable reduces the wiring and makes the setting up so simple.

Three Times Faster Communication Speed

Communication speed is increased to 150 Mbps full duplex (equivalent to 300 Mbps half duplex), three times faster than the conventional speed. System response is dramatically improved.

Cycle Time as Fast as 0.222 ms

Smooth control of a machine is possible using high-speed serial communication with a cycle time of 0.222 ms.

Synchronous communication

Synchronous communication is achieved with SSCNET III/H, offering technical advantages for machines in printing and food processing industry that require deterministic control.

Improved Noise Tolerance by Optical Communication

The fiber-optic cables thoroughly shut out noise that enters from the power cable or external devices. Noise tolerance is dramatically improved as compared to metal cables.
Long Distance Wiring up to 3200 m

Long distance wiring is possible up to 3200 m per system (maximum of 100 m between stations × 32 axes), suitable for large-scale systems.

- Maximum overall distance per system
  - Standard code/standard cable: 640 m (20 m × 32 axes)
  - Long distance cable: 3200 m (100 m × 32 axes)

Central Control with Network

Large amounts of servo data are exchanged in real-time between the controller and the servo amplifier. Using MR Configurator2 on a personal computer that is connected to the Motion controller or the Simple Motion module helps consolidate information, such as parameter settings and monitoring for the multiple servo amplifiers.

Network Topology

Star and line topologies are available with MR-MV200 optical hub unit through SSCNET III/H for a network configuration. Maintenance can be executed without stopping the whole system, and thus the machine availability will be increased.

I/O Signals Synchronized with Motion Control

MR-MT2000 series sensing modules including the I/O module, analog I/O module, pulse I/O module, and encoder I/F module are connected to SSCNET III/H. These various modules enable a faster, more accurate machine operation by synchronizing the I/Os of a general-purpose pulse train driver, sensor, and SSI encoder with the motion control.
Selection of Servo System Controller

Select the type of servo system controller roughly on the basis of control method after selecting a PLC CPU. Next, select the optimal servo system controller that suits your application on the basis of connecting devices, performance/program types, and functions.
Model Selection of PLC CPU and Controller

Medium- to large-scale control

A next-generation programmable automation controller (PAC), the MELSEC iQ-R series resolves your tasks as the core of the automation system by integrating high-performance capabilities based on the high-end iQ-R system bus, inter-module synchronization, and high precision processing achieved by synchronization between high-speed networks.

The first to incorporate the multiple CPU architecture, the MELSEC-Q series wide-range of CPUs enables control of multiple operations, improving the performance and scalability of the overall production system.

Small- to medium-scale control

The MELSEC-L series is a baseless highly scalable controller ideal for applications having limited space. With various I/O functionality embedded into the CPU module, high performance is achieved in a compact body.

Small-scale and stand-alone

Designed to provide outstanding performance and superior drive control, the MELSEC iQ-F series is a high-performance compact-class controller with a rich assortment of integrated functions.

Incorporating abundant features with a flexible system configuration, the MELSEC-F series has a power supply, CPU, and I/Os into a single compact body.

Motion control by C Language based programming

High-response servo control can be performed with a combination of the Position Board and a personal computer, or the C Controller Interface Module and the C Controller.
Controller Selection Guide

Model Selection by Control Method

Select the controller on the basis of control method, program, and command interface.

Control method

Positioning control only

Special control, such as pressure control

Synchronous control, Speed-torque control, Mark detection, etc.

X-Y tables, Material handling, Mounters, etc.

Injection molding, etc.

Packaging, Printing, Pressing, Converting, Semiconductor manufacturing, etc.

Program

R16MTCPU
R32MTCPU
R64MTCPU

Motion SFC

Sequence program (FB included)

C language

Command interface

SSCNET III/H
CC-Link IE Field Network

Transistor output or Differential driver output

Motion SFC

Sequence program (FB included)

C language

Command interface

SSCNET III/H
CC-Link IE Field Network

Transistor output or Differential driver output

R16MTCPU
R32MTCPU
R64MTCPU

RD77MS
QD77MS
LD77MS
FX5-40SSC-S
FX5-80SSC-S

RD77GF
QD77GF

RD75P
RD75D
QD75PN
QD75DN
LD75P
LD75D
LCPU
FXsu-FXuc
FX5UFX5UC

MR-MC240
MR-MC241
MR-MC341
MR-MC220U3
MR-MC220U6
MR-MC210
MR-MC211
Q173SCCF

MR-EM340GF

* For RnMTCPU, add-on libraries can be additionally installed. With "G-code control add-on library" (not free of charge), the controller can control a processing machine using general-purpose AC servo system. With an add-on library "machine library" (free of charge), the controller can control a simplified robot (link configuration).
Model Selection of PLC CPU

Select the PLC CPU in consideration of the size and expandability of the equipment.
## Product Lines

<table>
<thead>
<tr>
<th>Programmable controller</th>
<th>Model</th>
<th>Engineering software</th>
<th>Command interface</th>
<th>MELSERVO-J4</th>
<th>MELSERVO-JE</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Servo amplifier</td>
<td>Servo motor</td>
</tr>
<tr>
<td>MELSEC iQ-R series</td>
<td>CPU module</td>
<td>ReCPU/ReENCPU</td>
<td>GX Works3</td>
<td>CC Link IE Basic</td>
<td>MR-J4-GF</td>
</tr>
<tr>
<td></td>
<td>Simple Motion module</td>
<td>RD77GF</td>
<td>GX Works3</td>
<td>CC Link IE Basic</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>RD77MS</td>
<td>GX Works3</td>
<td>MR-J4(W)-B</td>
<td>MI-JE-B</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Motion controller</td>
<td>ReMTCPU</td>
<td>GX Works3 MT Works2</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>Positioning module</td>
<td>RD75P RD75D</td>
<td>GX Works3</td>
<td>Transistor output</td>
<td>MR-J4-A</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Differential Shaper output</td>
<td>MI-JE-A</td>
</tr>
<tr>
<td>MELSEC-Q series *3</td>
<td>Simple Motion module</td>
<td>QD77GF</td>
<td>GX Works2</td>
<td>CC Link IE Basic</td>
<td>MR-J4-GF</td>
</tr>
<tr>
<td></td>
<td>QD77MS</td>
<td>GX Works2</td>
<td>MR-J4(W)-B</td>
<td>MI-JE-B</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Motion controller</td>
<td>Q71/SDCPU Q71MS2PU</td>
<td>GX Works2 MT Works2</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>Positioning module</td>
<td>QD75PN QD75SN</td>
<td>GX Works2</td>
<td>Transistor output</td>
<td>MR-J4-A</td>
</tr>
<tr>
<td></td>
<td>QD70P QD70D</td>
<td>GX Works2</td>
<td>Transistor output</td>
<td>Differential Shaper output</td>
<td>MI-JE-A</td>
</tr>
<tr>
<td>MELSEC L series *3</td>
<td>CPU module</td>
<td>LCPU</td>
<td>GX Works2</td>
<td>MR-J4-A</td>
<td>MI-JE-C</td>
</tr>
<tr>
<td></td>
<td>Simple Motion module</td>
<td>LD77MS</td>
<td>GX Works2</td>
<td>MR-J4(W)-B</td>
<td>MI-JE-B</td>
</tr>
<tr>
<td></td>
<td>LD75P LD75D</td>
<td>GX Works2</td>
<td>Transistor output</td>
<td>MR-J4-A</td>
<td>MI-JE-C</td>
</tr>
<tr>
<td></td>
<td>Positioning module</td>
<td></td>
<td></td>
<td>Differential Shaper output</td>
<td>MI-JE-A</td>
</tr>
<tr>
<td>MELSEC iQ-F series</td>
<td>CPU module</td>
<td>FXSU FXSUC</td>
<td>GX Works3</td>
<td>Transistor output</td>
<td>MR-J4-A</td>
</tr>
<tr>
<td></td>
<td>Simple Motion module</td>
<td>FXS-405SC-S FXS-805SC-S</td>
<td>GX Works3</td>
<td>MR-J4(W)-B</td>
<td>MI-JE-B</td>
</tr>
<tr>
<td></td>
<td>Positioning module</td>
<td>FXu-1PG</td>
<td>GX Works2</td>
<td>Transistor output</td>
<td>MR-J4-A</td>
</tr>
<tr>
<td>MELSEC Q series</td>
<td>Personal computer</td>
<td>MR-EM540GF</td>
<td>EM Software Development Kit *1</td>
<td>CC Link IE Basic</td>
<td>MR-J4-GF</td>
</tr>
<tr>
<td></td>
<td>Board type controllers</td>
<td>MR-MC2_0 MR-MC2_1 MR-MC341</td>
<td>*1</td>
<td>MR-J4(W)-B</td>
<td>MI-JE-B</td>
</tr>
<tr>
<td></td>
<td>C Language compatible module</td>
<td>Q173SCCF</td>
<td>*2</td>
<td>MR-J4(W)-B</td>
<td>MI-JE-B</td>
</tr>
</tbody>
</table>

*1. Be sure to prepare the development environment in which Microsoft Visual Studio® can be used.
*2. CW Workbench/Wind River Workbench, and Setting/monitoring tool for the C Language Controllers
*3. MELSEC Q and MELSEC L series also support CC-Link IE Field Network Basic.
## Performance/Program

<table>
<thead>
<tr>
<th>Programmable controller</th>
<th>Model</th>
<th>Maximum number of control axes</th>
<th>Operation cycle</th>
<th>Positioning program</th>
<th>Electronic gear</th>
</tr>
</thead>
<tbody>
<tr>
<td>CPU module</td>
<td></td>
<td></td>
<td></td>
<td>Synchronous control parameter</td>
<td></td>
</tr>
<tr>
<td>Simple Motion module</td>
<td></td>
<td></td>
<td></td>
<td>Motion profile table</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Motion SFC</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>G-code (^*1)</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Machine control</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Sequence program</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>C language</td>
<td></td>
</tr>
<tr>
<td>MELSEC iQ-R series</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CPU module</td>
<td>ReCPU</td>
<td>Depends on the master station</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>ReENCPU</td>
<td>Depends on the master station</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Simple Motion module</td>
<td>RD77GF</td>
<td>32 0.5 ms or longer</td>
<td>●</td>
<td></td>
<td>●</td>
</tr>
<tr>
<td></td>
<td>RD77MS</td>
<td>16 0.444 ms or longer</td>
<td>●</td>
<td></td>
<td>●</td>
</tr>
<tr>
<td>Motion controller</td>
<td>ReMTCPU</td>
<td>64 0.222 ms or longer</td>
<td>—</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Positioning module</td>
<td>RD75P</td>
<td>4</td>
<td>—</td>
<td>●</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>RD75D</td>
<td></td>
<td>—</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>MELSEC-Q series</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Motion controller</td>
<td>QD77GF</td>
<td>16 1 ms or longer</td>
<td>●</td>
<td></td>
<td>●</td>
</tr>
<tr>
<td></td>
<td>QD77MS</td>
<td>16 0.888 ms or longer</td>
<td>●</td>
<td></td>
<td>●</td>
</tr>
<tr>
<td>Positioning module</td>
<td>QD75P</td>
<td>4</td>
<td>—</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td></td>
<td>QD75D</td>
<td>8</td>
<td>—</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>MELSEC-L series</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CPU module</td>
<td>LCPU</td>
<td>2</td>
<td>—</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Simple Motion module</td>
<td>LD77MS</td>
<td>16 0.888 ms or longer</td>
<td>●</td>
<td></td>
<td>●</td>
</tr>
<tr>
<td>Positioning module</td>
<td>LD75P</td>
<td>4</td>
<td>—</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td></td>
<td>LD75D</td>
<td>8</td>
<td>—</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>MELSEC-iQ-F series</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CPU module</td>
<td>FX5U</td>
<td>Depends on the master station</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>FX5UC</td>
<td>Depends on the master station</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Simple Motion module</td>
<td>FX5-40SSC-S</td>
<td>4 0.888 ms or longer</td>
<td>●</td>
<td></td>
<td>●</td>
</tr>
<tr>
<td></td>
<td>FX5-80SSC-S</td>
<td>8 0.888 ms or longer</td>
<td>●</td>
<td></td>
<td>●</td>
</tr>
<tr>
<td>C Language compatible module</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Personal computer</td>
<td>MR-BM040GF</td>
<td>16 0.5 ms or longer</td>
<td>●</td>
<td></td>
<td>●</td>
</tr>
<tr>
<td></td>
<td>MR-MC2_0</td>
<td>20 0.222 ms or longer</td>
<td>●</td>
<td></td>
<td>●</td>
</tr>
<tr>
<td></td>
<td>MR-MC341</td>
<td>32 0.222 ms or longer</td>
<td>●</td>
<td></td>
<td>●</td>
</tr>
</tbody>
</table>

\(^*1\) “G-code control add-on library” (provided for a fee) is additionally required. With the library, control of a processing machine using AC servo is possible.
## Function comparison

<table>
<thead>
<tr>
<th>Function</th>
<th>MELSEC-iQ-R</th>
<th>MELSEC-Q</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>RD77GF4</td>
<td>RD77GF8</td>
</tr>
<tr>
<td></td>
<td>RD77GF16</td>
<td>RD77GF32</td>
</tr>
<tr>
<td>Position control</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Speed control</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Torque control</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Position follow-up control</td>
<td>–</td>
<td>●</td>
</tr>
<tr>
<td>Cam control</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Linear interpolation</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Circular interpolation</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Continuous trajectory control</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Speed/position switching control</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Helical interpolation</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Trapezoidal acceleration/deceleration</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>S-curve acceleration/deceleration</td>
<td>◊</td>
<td>●</td>
</tr>
<tr>
<td>Advanced S-curve acceleration/deceleration</td>
<td>—</td>
<td>●</td>
</tr>
<tr>
<td>JOG operation</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Manual pulse generator operation</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Current value change</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Target position change</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Speed change</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Override</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Acceleration/deceleration time change</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Home position return</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Absolute position system</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Unlimited length feed</td>
<td>□</td>
<td>●</td>
</tr>
<tr>
<td>Optional data monitor</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Mark detection</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Event history</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Cam auto-generation</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>Driver communication</td>
<td>—</td>
<td>●</td>
</tr>
<tr>
<td>Digital oscilloscope</td>
<td>—</td>
<td>●</td>
</tr>
<tr>
<td>Vision system</td>
<td>—</td>
<td>●</td>
</tr>
<tr>
<td>Security key</td>
<td>—</td>
<td>●</td>
</tr>
</tbody>
</table>

*1. Available only with QD70D.*

*2. Available only with MR-MC341.*
<table>
<thead>
<tr>
<th>Controller Selection Guide</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Position control</strong></td>
</tr>
<tr>
<td>●●●●●●●●●●</td>
</tr>
<tr>
<td><strong>Speed control</strong></td>
</tr>
<tr>
<td>●●●●●●●●</td>
</tr>
<tr>
<td><strong>Torque control</strong></td>
</tr>
<tr>
<td>●●●</td>
</tr>
<tr>
<td><strong>Tightening &amp; press-fit control</strong></td>
</tr>
<tr>
<td>–</td>
</tr>
<tr>
<td><strong>Advanced synchronous control</strong></td>
</tr>
<tr>
<td>●●●</td>
</tr>
<tr>
<td><strong>Cam control</strong></td>
</tr>
<tr>
<td>●●●</td>
</tr>
<tr>
<td><strong>Linear interpolation</strong></td>
</tr>
<tr>
<td>●●●Simple ver.</td>
</tr>
<tr>
<td><strong>Circular interpolation</strong></td>
</tr>
<tr>
<td>●●●</td>
</tr>
<tr>
<td><strong>Continuous trajectory control</strong></td>
</tr>
<tr>
<td>●●●●●●●●●●</td>
</tr>
<tr>
<td><strong>Speed/position switching control</strong></td>
</tr>
<tr>
<td>●●●●●●●●</td>
</tr>
<tr>
<td><strong>Position follow-up control</strong></td>
</tr>
<tr>
<td>–</td>
</tr>
<tr>
<td><strong>Helical interpolation</strong></td>
</tr>
<tr>
<td>●●●</td>
</tr>
<tr>
<td><strong>Trapezoidal acceleration/deceleration</strong></td>
</tr>
<tr>
<td>●●●●●●●●●●</td>
</tr>
<tr>
<td><strong>S-curve acceleration/deceleration</strong></td>
</tr>
<tr>
<td>●●●</td>
</tr>
<tr>
<td><strong>Advanced S-curve acceleration/deceleration</strong></td>
</tr>
<tr>
<td>–</td>
</tr>
<tr>
<td><strong>JOG operation</strong></td>
</tr>
<tr>
<td>●●●●●●●●●●</td>
</tr>
<tr>
<td><strong>Manual pulse generator operation</strong></td>
</tr>
<tr>
<td>–</td>
</tr>
<tr>
<td><strong>Current value change</strong></td>
</tr>
<tr>
<td>●●●●●●●●</td>
</tr>
<tr>
<td><strong>Target position change</strong></td>
</tr>
<tr>
<td>●●●●●●●●</td>
</tr>
<tr>
<td><strong>Speed change</strong></td>
</tr>
<tr>
<td>●●●●●●●●</td>
</tr>
<tr>
<td><strong>Override</strong></td>
</tr>
<tr>
<td>●●●●●●</td>
</tr>
<tr>
<td><strong>Acceleration/deceleration time change</strong></td>
</tr>
<tr>
<td>●●●●●●●●</td>
</tr>
<tr>
<td><strong>Home position return</strong></td>
</tr>
<tr>
<td>●●●●●●●●●●●●●●●●</td>
</tr>
<tr>
<td><strong>Absolute position system</strong></td>
</tr>
<tr>
<td>●●●Simple ver.●●●Simple ver.</td>
</tr>
<tr>
<td><strong>Unlimited length feed</strong></td>
</tr>
<tr>
<td>●●●●●●●●</td>
</tr>
<tr>
<td><strong>Optional data monitor</strong></td>
</tr>
<tr>
<td>●●●</td>
</tr>
<tr>
<td><strong>Mark detection</strong></td>
</tr>
<tr>
<td>●●●</td>
</tr>
<tr>
<td><strong>Event history</strong></td>
</tr>
<tr>
<td>●●●●●●</td>
</tr>
<tr>
<td><strong>Cam auto-generation</strong></td>
</tr>
<tr>
<td>●●●</td>
</tr>
<tr>
<td><strong>Driver communication</strong></td>
</tr>
<tr>
<td>–</td>
</tr>
<tr>
<td><strong>Digital oscilloscope</strong></td>
</tr>
<tr>
<td>●●●</td>
</tr>
<tr>
<td><strong>Vision system</strong></td>
</tr>
<tr>
<td>–</td>
</tr>
<tr>
<td><strong>Security key</strong></td>
</tr>
<tr>
<td>–</td>
</tr>
</tbody>
</table>

*1. Available only with QD70D.
Solutions

MELSERVO Solution

Introducing the MELSERVO solutions for problems in production sites. We offer the optimal solutions for various problems in various production sites.

Applications

- Vertical form, fill & seal
- Pick and place robots
- Converting systems
- Rotary knives
- Press-fit machines
- Screw tightening machines
- Motion alignment (X-Y-θ)
- Conveyor systems utilizing safety observation function
- Automated guided vehicles
- Gantry applications
- Eco-friendly conveyors and product handling equipment
- Flying shears

Function Guide

Introducing the latest functions for easier and safer operations. MELSERVO-J4 and our servo products come with a wide selection of functions to solve the challenges in production.

- Failure Prediction
- Functional Safety
- Drive Recorder
- Monitoring
- Master-Slave Operation
- One-Touch Tuning
- Super Trace Control
- Multi-Axis Adjustment
- Simple Cam
- Pressure Control

Mitsubishi Electric FA Application Package iQ Monozukuri

Offering concentrates on improving the productivity, quality, and concepts for achieving process improvements associated with the construction and configuration of applications, and devices.

- CONVERTING  Strongly supporting development of converting systems with unwinder/rewinder control
- HANDLING  Strongly supporting development of transportation mechanisms with calculation of coordinate transformation
- PACKAGING  Strongly supporting development of packaging machines with cam control and positioning compensation

Refer to "MELSERVO J4 Function Guide (L(NA)03152ENG)" for details.
The e-F@ctory Alliance is an FA manufacturer partnering program that strongly links the connection compatibility of Mitsubishi Electric FA equipment utilizing excellent software and machinery offered by partners, thereby enabling systems to be built by systems integration partners and the proposal of optimal solutions to customers.

Mitsubishi Electric Servo System Partners

Servo system includes controllers, servo drivers, actuators, sensors, etc. The servo system takes a step further to accelerate the equipment revolution by collaborating with our partner companies. Now that a wide variety of partner products are available such as pressure-resistance, explosion-proof type motors, custom-made servo motors, magnetic type linear encoders, your system will be configured flexibly. The Mitsubishi Electric Servo System Partner Association is a subcommittee of e-F@ctory Alliance.
Production System

Homes of MELSERVO where the advanced FA technologies are incorporated. To guarantee the high quality and performance of MELSERVO, Mitsubishi Electric has built a cooperative system of three facilities - Shinshiro Factory, a branch factory of Nagoya Works; MEAMC (Mitsubishi Electric Automation Manufacturing (Changshu) Co., Ltd.) a manufacturing base; and Nagoya Works at the core. Mitsubishi Electric responds to customer needs throughout the world by uniting technologies and know-hows of these facilities.

Nagoya Works

Integrated manufacturing of servo amplifiers, servo motors, and other Mitsubishi Electric's servo system products.

Nagoya Works was established in 1924 as Mitsubishi Electric's first mass-production factory for electric motors. The lineup of factory automation and mechatronics products has continued to expand gradually since the advent of high economic growth in Japan. Along with its numerous successful achievements, Nagoya Works continues to actively develop solutions for improving productivity and quality.

<table>
<thead>
<tr>
<th>Number of employees</th>
<th>2,500</th>
</tr>
</thead>
<tbody>
<tr>
<td>Site area</td>
<td>306,000 m²</td>
</tr>
<tr>
<td>Gross floor space</td>
<td>Approx. 252,000 m² (Satellite factories excluded)</td>
</tr>
</tbody>
</table>

Shinshiro Factory

Mitsubishi Electric's servo motor manufacturing facility.

Shinshiro Factory was established in 1974 as a satellite factory of Nagoya Works, supplying various types of motors built utilizing the latest mechatronic and system technologies. Moreover, the integrated FA solution e-F@ctory was introduced for the motor shaft processing line, which utilizes many special components. The productivity of the production line has been improved, and the factory is now able to handle multi-model, small-lot production in a shorter period of time.

<table>
<thead>
<tr>
<th>Number of employees</th>
<th>100</th>
</tr>
</thead>
<tbody>
<tr>
<td>Site area</td>
<td>130,000 m²</td>
</tr>
<tr>
<td>Gross floor space</td>
<td>42,000 m²</td>
</tr>
</tbody>
</table>

MEAMC

(Mitsubishi Electric Automation Manufacturing (Changshu) Co., Ltd.)

AC servo manufacturing facility in China

MEAMC was established in June 2011 in Changshu, China, as a manufacturing base. Operations at Factory 2 started in April 2017 in response to the increasing demands for controllers and drive products in China and around the world. FA integrated solution, "e-F@ctory", has been implemented in the manufacturing line to improve productivity and conserve energy.

<table>
<thead>
<tr>
<th>Number of employees</th>
<th>490</th>
</tr>
</thead>
<tbody>
<tr>
<td>Site area</td>
<td>63,910 m²</td>
</tr>
<tr>
<td>Gross floor space</td>
<td>44,810 m²</td>
</tr>
</tbody>
</table>
Key parts of own manufacturing on unique technology

In the advanced production system integrating the production management system and the FA system based on IT, key components such as power modules and servo-motor encoders for drive control devices and oscillators and lenses for laser machining equipment are manufactured in our company by making the best use of unique technologies. This strategic facility is indispensable for Nagoya Works to enhance competitiveness of its products and to add values to the products.

Passing on technologies developed to future generations

Manufacturing is an achievement of advanced technologies, and at the same time, it is the result of skills passed from person to person. Nagoya Works periodically holds Nagoya Works Technology School, in which educational sessions are conducted where senior engineers teach younger engineers techniques and procedures such as machining, finishing, welding, and assembly of electronic components. The skills developed are passed on to future generations as precious resources of manufacturing.

Painstaking quality assurance through the application of cutting-edge testing equipment.

- Ultrasonic Probing Devices
- LSI testers
- X-ray scanners
- EMC chamber (large-size anechoic chamber)
- Equipment for highly accelerated limit test (HALT)
World-class R&D capabilities to offer a unique set of servo systems. To bring cutting-edge servo systems to worldwide market, Mitsubishi Electric has established FA-related development centers in its Nagoya Works, Europe, the U.S., and India. Together with our Advanced Technology R&D Center, and Information and Technology R&D Center, we are moving forward with the development of new products to correspond to technology trends and the voices of our customers.

### Japan (Nagoya Works)

**FA Development Center**

Integrating product-development ability as a comprehensive FA supplier

The FA Development Center is comprised of engineers who specialized in controllers and drive system products. Its function is to promote higher product compatibility and integration, as well as improve the overall performance of Mitsubishi Electric FA products by merging the respective technologies of different parties at a high level. The newly added Experiment and Verification Room is used for joint development projects with customers and development partners. The Center has a secure Internet environment, and the connection status of our FA devices and software can be assessed easily. This shortens the development timeframe and enables us to be one step ahead in creating FA products that connect to the world and meet the needs of the IoT era.

In addition, the number of prototypes necessary in the product planning, development, design and prototype phases has been reduced through simulation technology built in a virtual environment. The product development timeframe has also been shortened and design quality improved by reducing the man-hours required for evaluation.

**Mechatronics Development Center**

Advanced base for advantage of technology and development of industrial mechatronics products

In addition to FA devices, industrial mechatronics products are another major product line manufactured at Nagoya Works. The Mechatronics Development Center is the development base for these products. It has established advanced machining technologies that enable highly accurate ultrafine machining at the nanometer-level, and works to improve development efficiency and reduce development time by seamlessly linking itself with relevant technological organizations. It is also utilized for joint development projects with our customers, leading to the creation of products that can be used, and new applications and new markets.
Japan (Mitsubishi Electric R&D)

Advanced Technology R&D Center

The Advanced Technology R&D Center engages in next-generation product development utilizing the fundamental technologies that underpin our business and R&D, which helps to sow the seeds for new business in the future and aims to create new values accepted by society.

Information and Technology R&D Center

As the main base for information and communication technology development, the Information and Technology R&D Center conducts R&D in the fields of information, multimedia, optic radio waves and communication technologies and solution proposal-type development utilizing IT.

Global Development Centers

Global development centers and Mitsubishi Electric domestic laboratories collaborating to lead the world in product development

European Development Center (EDC)  North American Development Center (NADC)  India Development Center (INDC)  China Development Center (CDC)

Production System/R&D
History of Mitsubishi Electric Servo System

Passing our technologies and experiences from one generation to the next, Mitsubishi Electric continuously strives for cutting-edge technology.

- **1980**
  - Launch of Mitsubishi Electric’s first servo amplifier (MR-A/S0)
  - Improvement of productivity
  - Industry needs

- **1985**
  - MR-SA/SB/SC/SD
  - First to introduce a completely digital servo
  - Maintenance-free
  - High-speed response
  - Low-cost

- **1990**
  - MR-J
  - Industry’s smallest servo (at the time)
  - Core type
  - HA-SA
  - Medium/ large capacity
  - 0.2 to 7 kW

- **1995**
  - MR-H
  - Most advanced servo (at the time)
  - Coreless type
  - HA-LH
  - Medium capacity
  - HA-SA
  - 0.5 to 22 kW

- **2000**
  - MR-J2-Super/J2M
  - Launched super-miniaturized series
  - MR-J2
  - Continuous thrust 250 to 4000 N
  - HA-LF/LFS
  - Medium/ large capacity
  - HA-SA
  - 0.5 to 22 kW

- **2005**
  - MR-JR
  - Continuous thrust 250 to 4000 N
  - HA-LF/LFS
  - Medium/ large capacity
  - HA-SA
  - 0.5 to 22 kW

- **2010**
  - MR-E
  - Continuous thrust 250 to 4000 N
  - HA-LF/LFS
  - Medium/ large capacity
  - HA-SA
  - 0.5 to 22 kW

- **2015**
  - MR-JR
  - Continuous thrust 250 to 4000 N
  - HA-LF/LFS
  - Medium/ large capacity
  - HA-SA
  - 0.5 to 22 kW

- **2020**
  - MR-E
  - Continuous thrust 250 to 4000 N
  - HA-LF/LFS
  - Medium/ large capacity
  - HA-SA
  - 0.5 to 22 kW

**Servo amplifier**
- MR-A/S0
- MR-SA/SB/SC/SD
- MR-J
- MR-H
- MR-J2-Super/J2M
- MR-JR
- MR-E

**Industry Needs**
- Improvement of productivity
- Maintenance-free
- High-speed response
- Low-cost

**Motion controller**
- MR-P20/P40
- Multi-axis Controller
- A373CPU

**Simple Motion module Positioning module**
- A series
- Q series
- A173CPU/A172SHCPU
- Q173/Q172CPU

**Field network**
- 10 Mbps
- CC-Link
- High-speed (5.6 Mbps / 2)
- DeviceNet
- SSCNET

**Servo system controller network**
- DeviceNet
In 1987, Mitsubishi Electric announced MELSERVO-SA, the first completely digital hardware logic product at a time when analog products were at their zenith. Since then, we have pioneered servo technology in Japan. Carrying that heritage forward, we will continuously offer you globally-acknowledged servo systems that completely satisfy your needs.

<table>
<thead>
<tr>
<th>2005</th>
<th>2010</th>
</tr>
</thead>
<tbody>
<tr>
<td><img src="image" alt="2-axis type" /> MR-J3W</td>
<td><img src="image" alt="3-Speed frequency response of 2.5 kHz" /> MR-J4/MR-J4W2/MR-J4W3</td>
</tr>
<tr>
<td><img src="image" alt="MR-E Super" /> MR-JE</td>
<td><img src="image" alt="CC-Link IE Field" /> MR-J4-GF</td>
</tr>
<tr>
<td><img src="image" alt="Easy to use" /></td>
<td><img src="image" alt="High-performance" /></td>
</tr>
<tr>
<td><img src="image" alt="Safety standard" /></td>
<td><img src="image" alt="Energy-saving" /></td>
</tr>
<tr>
<td><img src="image" alt="Software modules" /></td>
<td><img src="image" alt="Easy to use" /></td>
</tr>
<tr>
<td><img src="image" alt="Widened scope of servo application" /></td>
<td><img src="image" alt="Vibration suppression" /></td>
</tr>
<tr>
<td><img src="image" alt="Diagnosis functions" /></td>
<td><img src="image" alt="Maintenance function" /></td>
</tr>
<tr>
<td><img src="image" alt="Open network" /></td>
<td><img src="image" alt="Environment resistance" /></td>
</tr>
<tr>
<td><img src="image" alt="High-speed processing" /></td>
<td><img src="image" alt="High-speed and High-performance" /></td>
</tr>
<tr>
<td><img src="image" alt="Environment resistance" /></td>
<td><img src="image" alt="ABS standard" /></td>
</tr>
<tr>
<td><img src="image" alt="High-reliability" /></td>
<td><img src="image" alt="CS-Link IE Field Network Basic" /></td>
</tr>
<tr>
<td>![Multi-axis (16 axes)]</td>
<td>![High-speed processing (50 Mbps × 2)]</td>
</tr>
<tr>
<td>![High-speed processing (150 Mbps × 2)]</td>
<td>![High-speed processing (50 Mbps × 2)]</td>
</tr>
</tbody>
</table>
Warranty

General-purpose AC servo

1. Warranty period and coverage
   We will repair any failure or defect hereinafter referred to as "failure" in our FA equipment hereinafter referred to as the "Product" arisen during warranty period at no charge to you for causes for which we are responsible through the distributor from which you purchased the Product or our service provider. However, we will charge the actual cost of dispatching our engineer for an on-site repair work on request by customer in Japan or overseas countries. We are not responsible for any on-site readjustment and/or trial run that may be required after a defective unit is repaired or replaced.

[Term]
   The term of warranty for Product is twelve (12) months after your purchase or delivery of the Product to a place designated by you or eighteen (18) months from the date of manufacture whichever comes first ("Warranty Period"). Warranty period for repaired Product cannot exceed the original warranty period before any repair work.

[Limitations]
   (1) You are requested to conduct an initial failure diagnosis by yourself, as a general rule. It can also be carried out by us or our service company upon your request and the actual cost will be charged. However, it will not be charged if we are responsible for the cause of the failure.
   (2) This limited warranty applies only when the condition, method, environment, etc. of use are in compliance with the terms and conditions and instructions that are set forth in the instruction manual and user manual for the Product and the caution label affixed to the Product.
   (3) Even during the term of warranty, the repair cost will be charged on you in the following cases;
      (i) a failure caused by your improper storing or handling, carelessness or negligence, etc., and a failure caused by your hardware or software problem
      (ii) a failure which may be regarded as avoidable, if your equipment in which the Product is incorporated is equipped with a safety device required by applicable laws and has any function or structure considered to be indispensable according to a common sense in the industry
      (iii) a failure which may be regarded as avoidable if consumable parts designated in the instruction manual, etc. are duly maintained and replaced
      (iv) any replacement of consumable parts (battery, fan, smoothing capacitor, etc.)
      (v) a failure caused by external factors such as inevitable accidents, including without limitation fire and abnormal fluctuation of voltage, and acts of God, including without limitation earthquake, lightning and natural disasters
      (vi) a failure generated by an unforeseeable cause with a scientific technology that was not available at the time of the shipment of the Product from our company
      (vii) any other failures which we are not responsible for or which you acknowledge we are not responsible for

2. Term of warranty after the stop of production
   (1) We may accept the repair at charge for another seven (7) years after the production of the product is discontinued. The announcement of the stop of production for each model can be seen in our Sales and Service, etc.
   (2) Please note that the Product (including its spare parts) cannot be ordered after its stop of production.

3. Service in overseas countries
   Our regional FA Center in overseas countries will accept the repair work of the Product. However, the terms and conditions of the repair work may differ depending on each FA Center. Please ask your local FA Center for details.

4. Exclusion of loss in opportunity and secondary loss from warranty liability
   Regardless of the gratis warranty term, Mitsubishi shall not be liable for compensation to:
   (1) Damages caused by any cause found not to be the responsibility of Mitsubishi.
   (2) Loss in opportunity, lost profits incurred to the user by Failures of Mitsubishi products.
   (3) Special damages and secondary damages whether foreseeable or not, compensation for accidents, and compensation for damages to products other than Mitsubishi products.
   (4) Replacement by the user, maintenance of on-site equipment, start-up test run and other tasks.

5. Change of Product specifications
   Specifications listed in our catalogs, manuals or technical documents may be changed without notice.

6. Application and use of the Product
   (1) For the use of our General-Purpose AC Servo, its applications should be those that may not result in a serious damage even if any failure or malfunction occurs in General-Purpose AC Servo, and a backup or fail-safe function should operate on an external system to General-Purpose AC Servo when any failure or malfunction occurs.
   (2) Our General-Purpose AC Servo is designed and manufactured as a general purpose product for use at general industries. Therefore, applications substantially influential on the public interest for such as atomic power plants and other power plants of electric power companies, and also which require a special quality assurance system, including applications for railway companies and government or public offices are not recommended, and we assume no responsibility for any failure caused by these applications when used.
   In addition, applications which may be substantially influential to human lives or properties for such as airlines, medical treatments, railway service, incineration and fuel systems, man-operated material handling equipment, entertainment machines, safety machines, etc. are not recommended, and we assume no responsibility for any failure caused by these applications when used.
   We will review the acceptability of the abovementioned applications, if you agree not to require a specific quality for a specific application. Please contact us for consultation.
Servo system controller

1. Warranty period and coverage

We will repair any failure or defect (hereinafter referred to as “failure”) in our FA equipment (hereinafter referred to as the “Product”) arisen during warranty period at no charge due to causes for which we are responsible through the distributor from which you purchased the Product or our service provider. However, we will charge the actual cost of dispatching our engineer for an on-site repair work on request by customer in Japan or overseas countries. We are not responsible for any on-site readjustment and/or trial run that may be required after a defective unit is repaired or replaced.

[Term]
The term of warranty for Product is thirty six (36) months after your purchase or delivery of the Product to a place designated by you or forty two (42) months from the date of manufacture whichever comes first (“Warranty Period”). Warranty period for repaired Product cannot exceed beyond the original warranty period before any repair work.

[Limitations]

(1) You are requested to conduct an initial failure diagnosis by yourself, as a general rule. It can also be carried out by us or our service company upon your request and the actual cost will be charged. However, it will not be charged if we are responsible for the cause of the failure.

(2) This limited warranty applies only when the condition, method, environment, etc. of use are in compliance with the terms and conditions and instructions that are set forth in the instruction manual and user manual for the Product and the caution label affixed to the Product.

(3) Even during the term of warranty, the repair cost will be charged on you in the following cases;

(i) a failure caused by your improper storing or handling, carelessness or negligence, etc., and a failure caused by your hardware or software problem

(ii) a failure caused by any alteration, etc. to the Product made on your side without our approval

(iii) a failure which may be regarded as avoidable, if your equipment in which the Product is incorporated is equipped with a safety device required by applicable laws and has any function or structure considered to be indispensable according to a common sense in the industry

(iv) a failure which may be regarded as avoidable if consumable parts designated in the instruction manual, etc. are duly maintained and replaced

(v) any replacement of consumable parts (battery, fan, etc.)

(vi) a failure caused by external factors such as inevitable accidents, including without limitation fire and abnormal fluctuation of voltage, and acts of God, including without limitation earthquake, lightning and natural disasters

(vii) a failure generated by an unforeseeable cause with a scientific technology that was not available at the time of the shipment of the Product from our company

(viii) any other failures which we are not responsible for or which you acknowledge we are not responsible for

2. Term of warranty after the stop of production

(1) We may accept the repair at charge for another seven (7) years after the production of the product is discontinued. The announcement of the stop of production for each model can be seen in our Sales and Service, etc.

(2) Please note that the Product (including its spare parts) cannot be ordered after its stop of production.

3. Service in overseas countries

Our regional FA Center in overseas countries will accept the repair work of the Product. However, the terms and conditions of the repair work may differ depending on each FA Center. Please ask your local FA Center for details.

4. Exclusion of loss in opportunity and secondary loss from warranty liability

Regardless of the gratis warranty term, Mitsubishi shall not be liable for compensation to:

(1) Damages caused by any cause found not to be the responsibility of Mitsubishi.

(2) Loss in opportunity, lost profits incurred to the user by Failures of Mitsubishi products.

(3) Special damages and secondary damages whether foreseeable or not, compensation for accidents, and compensation for damages to products other than Mitsubishi products.

(4) Replacement by the user, maintenance of on-site equipment, start-up test run and other tasks.

5. Change of Product specifications

Specifications listed in our catalogs, manuals or technical documents may be changed without notice.

6. Application and use of the Product

(1) For the use of our Motion controller/Simple Motion module, its applications should be those that may not result in a serious damage even if any failure or malfunction occurs in Motion controller/Simple Motion module, and a backup or fail-safe function should operate on an external system to Motion controller/Simple Motion module when any failure or malfunction occurs.

(2) Our Motion controller/Simple Motion module are designed and manufactured as general purpose product for use at general industries.

Therefore, applications substantially influential on the public interest for such as atomic power plants and other power plants of electric power companies, and also which require a special quality assurance system, including applications for railway companies and government or public offices are not recommended, and we assume no responsibility for any failure caused by these applications when used.

In addition, applications which may be substantially influential to human lives or properties for such as airlines, medical treatments, railway service, incineration and fuel systems, man-operated material handling equipment, entertainment machines, safety machines, etc., are not recommended, and we assume no responsibility for any failure caused by these applications when used.

We will review the acceptability of the abovementioned applications, if you agree not to require a specific quality for a specific application. Please contact us for consultation.
Precautions before use

This publication explains the typical features and functions of the products herein and does not provide restrictions or other information related to usage and module combinations. Before using the products, always read the product user manuals. Mitsubishi Electric will not be held liable for damage caused by factors found not to be the cause of Mitsubishi Electric; opportunity loss or lost profits caused by faults in Mitsubishi Electric products; damage, secondary damage, or accident compensation, whether foreseeable or not, caused by special factors; damage to products other than Mitsubishi Electric products; or any other duties.

For safe use

- To use the products given in this publication properly, always read the relevant manuals before beginning operation.
- The products have been manufactured as general-purpose parts for general industries, and are not designed or manufactured to be incorporated in a device or system used in purposes related to human life.
- Before using the products for special purposes such as nuclear power, electric power, aerospace, medicine or passenger-carrying vehicles, consult with Mitsubishi Electric.
- The products have been manufactured under strict quality control. However, when installing the products where major accidents or losses could occur if the products fail, install appropriate backup or fail-safe functions in the system.
YOUR SOLUTION PARTNER

Mitsubishi Electric offers a wide range of automation equipment from PLCs and HMIs to CNC and EDM machines.

A NAME TO TRUST
Since its beginnings in 1870, some 45 companies use the Mitsubishi name, covering a spectrum of finance, commerce and industry.

The Mitsubishi brand name is recognized around the world as a symbol of premium quality.

Mitsubishi Electric Corporation is active in space development, transportation, semi-conductors, energy systems, communications and information processing, audio visual equipment and home electronics, building and energy management and automation systems, and has 237 factories and laboratories worldwide in over 121 countries.

This is why you can rely on Mitsubishi Electric automation solution - because we know first hand about the need for reliable, efficient, easy-to-use automation and control in our own factories.

As one of the world’s leading companies with a global turnover of over 4 trillion Yen (over $40 billion), employing over 100,000 people, Mitsubishi Electric has the resource and the commitment to deliver the ultimate in service and support as well as the best products.

* Not all products are available in all countries.
<table>
<thead>
<tr>
<th>Country/Region</th>
<th>Sales office</th>
<th>Tel</th>
</tr>
</thead>
<tbody>
<tr>
<td>USA</td>
<td>Mitsubishi Electric Automation, Inc. 520 Corporate Woods Parkway, Vernon Hills, IL 60061, U.S.A.</td>
<td>+1-847-478-2100</td>
</tr>
<tr>
<td>Mexico</td>
<td>Mitsubishi Electric Automation, Mexico Branch Boulevard Miguel de Cervantes Saavedra 301, Torre Norte Piso 5, Ampliaci6on Granada, Miguel Hidalgo, Ciudad de Mexico, M6xico, C.P.11520</td>
<td>+52-55-3067-7512</td>
</tr>
<tr>
<td>Brazil</td>
<td>Mitsubishi Electric do Brasil Comercio e Servicios Ltda. Av. Avenida Adelino Cardana 293, 21 andar, Beltaville, Barueri SP, Brazil</td>
<td>+55-11-4689-3000</td>
</tr>
<tr>
<td>Germany</td>
<td>Mitsubishi Electric Europe B.V. German Branch Mitsubishi-Electric-Platz 1, 40882 Ratingen, Germany</td>
<td>+49-2102-486-0</td>
</tr>
<tr>
<td>UK</td>
<td>Mitsubishi Electric Europe B.V. UK Branch Travellers Lane, UK-Hatfield, Hertfordshire, AL10 8XB, U.K.</td>
<td>+44-1707-28-8780</td>
</tr>
<tr>
<td>Italy</td>
<td>Mitsubishi Electric Europe B.V. Italian Branch Centro Direzionale Colleoni - Palazzo Sirio, Viale Colleoni 7, 20864 Agrate Brianza (MB), Italy</td>
<td>+39-039-60531</td>
</tr>
<tr>
<td>Spain</td>
<td>Mitsubishi Electric Europe B.V. Spanish Branch Carretera de Rubi 76-80-Apdo. 420, E-08190 Sant Cugat del Valles (Barcelona), Spain</td>
<td>+34-935-65-3131</td>
</tr>
<tr>
<td>France</td>
<td>Mitsubishi Electric Europe B.V. French Branch 25, Boulevard des Bouvets, 92741 Nanterre Cedex, France</td>
<td>+33-1-55-68-55-68</td>
</tr>
<tr>
<td>Czech Republic</td>
<td>Mitsubishi Electric Europe B.V. Czech Branch, Prague Office Pekarska 62/17, 150 00 Praha 5, Czech Republic</td>
<td>+420-255-719-200</td>
</tr>
<tr>
<td>Poland</td>
<td>Mitsubishi Electric Europe B.V. Polish Branch ul. Krakowska 50, 32-083 Balice, Poland</td>
<td>+48-12-347-65-00</td>
</tr>
<tr>
<td>Russia</td>
<td>Mitsubishi Electric (Russia) LLC St. Petersburg Branch Piskarevskiy pr. 2, bld 2, lit &quot;Sch&quot;, BC &quot;Benua&quot;, office 720, 195027 St. Petersbur, Russia</td>
<td>+7-812-633-3497</td>
</tr>
<tr>
<td>Sweden</td>
<td>Mitsubishi Electric Europe B.V. (Scandinavia) Fjellevagen 8, SE-22736 Lund, Sweden</td>
<td>+46-8-625-10-00</td>
</tr>
<tr>
<td>Turkey</td>
<td>Mitsubishi Electric Turkey A.S. Umranliye Branch Seretal Mahallesi Nufuk Sokak No.5, TR-34775 Umranliye / Istanbul, Turkey</td>
<td>+90-216-526-3990</td>
</tr>
<tr>
<td>UAE</td>
<td>Mitsubishi Electric Europe B.V. Dubai Branch Dubai Silicon Oasis, P.O. BOX 34241, Dubai, U.A.E.</td>
<td>+971-4-3724716</td>
</tr>
<tr>
<td>South Africa</td>
<td>Adroit Technologies 20 Waterford Office Park, 189 Wilkoppert Road, Fourways, South Africa</td>
<td>+27-11-658-8100</td>
</tr>
<tr>
<td>China</td>
<td>Mitsubishi Electric Automation (China) Ltd.</td>
<td>+86-21-2322-3030</td>
</tr>
<tr>
<td>Taiwan</td>
<td>Mitsubishi Electric Automation Center, No.1386 Hongqiao Road, Shanghai, China</td>
<td>+86-21-2299-2499</td>
</tr>
<tr>
<td>Korea</td>
<td>Mitsubishi Electric Automation Korea Co., Ltd. 7F to 9F, Gangseo Hangang Xi-tower A, 401, Yangcheon-ro, Gangseo-Gu, Seoul 07528, Korea</td>
<td>+82-2-3660-9529</td>
</tr>
<tr>
<td>Singapore</td>
<td>Mitsubishi Electric Asia Pte. Ltd. 307 Alexandra Road, Mitsubishi Electric Building, Singapore 159943</td>
<td>+65-6473-2308</td>
</tr>
<tr>
<td>Thailand</td>
<td>Mitsubishi Electric Factory Automation (Thailand) Co., Ltd. 129th Floor, SV City Building, Office Tower 1, No. 896/19 and 20 Rama 3 Road, Kwaeng Bangporpsang, Khet Yanaw, Bangkok 10120, Thailand</td>
<td>+66-2682-6522 to 6531</td>
</tr>
<tr>
<td>Indonesia</td>
<td>PT, Mitsubishi Electric Indonesia Gedung Jaya 8th Floor, JL, MH. Thamrin No.12, Jakarta Pusat 10340, Indonesia</td>
<td>+62-21-3192-6461</td>
</tr>
<tr>
<td>Vietnam</td>
<td>Mitsubishi Electric Vietnam Company Limited Unit 01-04, 10th Floor, Vincom Center, 72 Le Thanh Ton Street, District 1, Ho Chi Minh City, Vietnam</td>
<td>+84-29-3910-5945</td>
</tr>
<tr>
<td>India</td>
<td>Mitsubishi Electric India Pvt. Ltd. Pune Branch Emerald House, EL-3, J Block, M.I.D.C., Bhosari, Pune - 411026, Maharashtra, India</td>
<td>+91-20-2710-2000</td>
</tr>
<tr>
<td>Australia</td>
<td>Mitsubishi Electric Australia Pty. Ltd. 348 Victoria Road, P.O. Box 11, Rydalmere, N.S.W. 2116, Australia</td>
<td>+61-2-9684-7777</td>
</tr>
</tbody>
</table>

Mitsubishi Electric Corporation Nagoya Works is a factory certified for ISO 14001 (standards for environmental management systems) and ISO 9001 (standards for quality assurance management systems).

MITSUBISHI ELECTRIC CORPORATION
HEAD OFFICE: TOKYO BUILDING, 5-7-3, MARUNOUCHI, CHIYODA-KU, TOKYO 100-8310 JAPAN
NAGOYA WORKS: 1-14, YADA-CHUO-CHI, HISASHIKU, NAGOYA, JAPAN